

# MOUNTING AND OPERATING INSTRUCTIONS



## EB 5573 EN

### Translation of original instructions



## TROVIS 5573 Heating and District Heating Controller

Firmware version 3.06.xx

Edition March 2025



## Note on these mounting and operating instructions

These mounting and operating instructions (EB) assist you in mounting and operating the device safely. The instructions are binding for handling SAMSON devices. The images shown in this document are for illustration purposes only. The actual product may vary.

- ⇒ For the safe and proper use of these instructions, read them carefully and keep them for later reference.
- ⇒ If you have any additional questions not related to the contents of these instructions, contact SAMSON's After-sales Service (aftersalesservice@samsongroup.com).



Documents relating to the device, such as the mounting and operating instructions, are available on our website:

▶ <https://www.samsongroup.com/en/downloads/documentation>

## Definition of signal words

### **⚠ DANGER**

*Hazardous situations which, if not avoided, will result in death or serious injury*

### **⚠ WARNING**

*Hazardous situations which, if not avoided, could result in death or serious injury*

### **ⓘ NOTICE**

*Property damage message or malfunction*

### **ℹ Note**

*Additional information*

### **💡 Tip**

*Recommended action*

<b>1</b>	<b>Safety instructions and measures.....</b>	<b>6</b>
1.1	Notes on possible severe personal injury.....	7
1.2	Notes on possible property damage.....	7
<b>2</b>	<b>Markings on the device.....</b>	<b>9</b>
2.1	Nameplate.....	9
2.2	Firmware versions.....	9
<b>3</b>	<b>Design and principle of operation.....</b>	<b>12</b>
3.1	Configuration using the TROVIS-VIEW software.....	12
3.2	Connection to SAM DISTRICT ENERGY.....	12
3.3	Technical data.....	13
3.4	Dimensions.....	14
3.5	Values for resistance thermometers.....	15
<b>4</b>	<b>Shipment and on-site transport.....</b>	<b>16</b>
4.1	Accepting the delivered goods.....	16
4.2	Removing the packaging from the heating controller.....	16
4.3	Transporting the heating controller.....	16
4.4	Storing the heating controller.....	16
<b>5</b>	<b>Installation.....</b>	<b>17</b>
5.1	Installation conditions.....	17
5.2	Preparation for installation.....	17
5.3	Mounting the heating controller.....	17
5.4	Electrical connection.....	19
<b>6</b>	<b>Operation.....</b>	<b>23</b>
6.1	Operating controls.....	23
6.2	Display.....	24
6.3	Optional interfaces.....	24
6.4	Accessories.....	25
<b>7</b>	<b>Start-up and configuration.....</b>	<b>26</b>
7.1	Setting the system code number.....	27
7.2	Activating and deactivating functions.....	27
7.3	Changing parameters.....	29
7.4	Calibrating sensors.....	30
7.5	Entering customized key number.....	31
<b>8</b>	<b>Operation.....</b>	<b>32</b>
8.1	Selecting the operating mode.....	32
8.2	Schedules.....	34
8.2.1	Setting the time and date.....	34
8.2.2	Setting the times-of-use.....	34
8.2.3	Setting the party timer (special time-of-use).....	36
8.2.4	Programming public holidays (special times-of-use).....	37
8.2.5	Programming vacation periods (special times-of-use).....	37
8.3	Entering day and night set points.....	39
8.4	Reset to default settings.....	39
8.5	Information readings.....	40
8.6	Operating the heating controller in manual mode.....	41
<b>9</b>	<b>Malfunctions.....</b>	<b>42</b>
9.1	Error list.....	42
9.2	Sensor failure.....	43
9.3	Temperature monitoring.....	44

## Contents

9.4	Error status register.....	44
<b>10</b>	<b>Servicing.....</b>	<b>45</b>
10.1	Recommended inspection and testing.....	45
10.2	Firmware update.....	45
10.2.1	Update over RS-232 interface.....	45
10.2.2	Update over RS-485 bus.....	47
10.2.3	Update over Ethernet.....	48
10.2.4	Automatic update for several controllers over RS-485 bus or Ethernet.....	49
<b>11</b>	<b>Decommissioning.....</b>	<b>52</b>
<b>12</b>	<b>Removal.....</b>	<b>53</b>
<b>13</b>	<b>Repair.....</b>	<b>54</b>
13.1	Returning devices to SAMSON.....	54
<b>14</b>	<b>Disposal.....</b>	<b>55</b>
<b>15</b>	<b>Certificates.....</b>	<b>56</b>
<b>16</b>	<b>Appendix A (configuration instructions).....</b>	<b>58</b>
16.1	Systems.....	58
16.2	Functions of the heating circuit.....	92
16.2.1	Outdoor-temperature-compensated control.....	92
16.2.1.1	Outdoor temperature received or sent as 0 to 10 V signal.....	93
16.2.1.2	Gradient characteristic.....	94
16.2.1.3	Four-point characteristic.....	95
16.2.2	Fixed set point control.....	97
16.2.3	Underfloor heating/drying of jointless floors.....	97
16.2.4	Night set-back.....	98
16.2.4.1	OT activation value in rated operation.....	99
16.2.4.2	OT deactivation value in rated operation.....	99
16.2.4.3	OT deactivation value in reduced operation.....	99
16.2.4.4	Variable night set-back.....	100
16.2.5	Buffer tank systems 16.x.....	100
16.2.6	Summer mode.....	102
16.2.7	Delayed outdoor temperature adaptation.....	102
16.2.8	Remote operation.....	103
16.2.9	Optimization.....	103
16.2.10	Flash adaptation.....	104
16.2.11	Flash adaptation without outdoor sensor (based on room temperature).....	105
16.2.12	Adaptation.....	105
16.2.13	Cooling control.....	106
16.2.14	Differential temperature control.....	107
16.3	Functions of the DHW circuit.....	108
16.3.1	DHW heating in the storage tank system.....	108
16.3.1.1	DHW circuit additionally controlled by a globe valve.....	109
16.3.2	DHW heating in the storage tank charging system.....	110
16.3.2.1	Cold charging protection.....	113
16.3.3	DHW heating in instantaneous heating system.....	113
16.3.4	Domestic hot water with solar system.....	113
16.3.5	Intermediate heating.....	114
16.3.6	Parallel pump operation.....	114
16.3.7	Circulation pump during storage tank charging.....	115
16.3.8	Priority circuit.....	115
16.3.8.1	Reverse control.....	115
16.3.8.2	Set-back operation.....	116

16.3.9	Forced charging of DHW storage tank.....	116
16.3.10	Thermal disinfection of DHW storage tank.....	116
16.4	System-wide functions.....	118
16.4.1	Automatic summer/standard time switchover.....	118
16.4.2	Frost protection.....	118
16.4.3	Forced pump operation.....	119
16.4.4	Return temperature limitation.....	119
16.4.5	Condensate accumulation control.....	120
16.4.6	Three-step control.....	120
16.4.7	On/off control.....	121
16.4.8	Continuous control in control circuit RK1.....	121
16.4.9	Releasing a control circuit/heating controller with binary input.....	121
16.4.10	Speed control of the charging pump.....	122
16.4.11	Processing an external demand.....	123
16.4.12	External demand using a 0 to 10 V signal.....	124
16.4.13	Creep feed rate limitation with a binary input.....	124
16.4.14	Connecting potentiometers for valve position input.....	125
16.4.15	Locking manual level.....	125
16.4.16	Locking the rotary switch.....	125
16.4.17	Feeder pump operation.....	125
16.4.18	External demand for heat due to insufficient heat supply.....	126
16.5	Communication.....	127
16.5.1	RS-485 communication module.....	127
16.5.2	Memory module/mini module.....	128
16.5.3	Data logging.....	129
16.6	Function block lists.....	130
16.7	Parameter lists.....	140
16.8	Customer-specific data.....	146
<b>17</b>	<b>Appendix B.....</b>	<b>154</b>
17.1	Accessories.....	154
17.2	After-sales service.....	154

### 1 Safety instructions and measures

#### Intended use

The TROVIS 5573 Heating and District Heating Controller is used to control up to two control circuits:

- Control of a primary heat exchanger or boiler with one mixing heating circuit and one non-mixing heating circuit (both outdoor-temperature-compensated) and control of DHW heating in the secondary circuit
- Outdoor-temperature-compensated buffer tank control with solid fuel boiler and solar circuit control
- Outdoor-temperature-compensated buffer tank control with up to two mixing heating circuits and continuous-flow hot water module
- Control of one outdoor-temperature-compensated heating circuit and a DHW heating with two valves in the primary circuit
- Control of two outdoor-temperature-compensated heating circuits with two valves in the primary circuit

The TROVIS 5573 Heating and District Heating Controller is designed to operate under exactly defined conditions. Therefore, operators must ensure that the heating controller is only used in operating conditions that meet the specifications used at the ordering stage. In case operators intend to use the heating and district heating controller in applications or conditions other than those specified, contact SAMSON.

SAMSON does not assume any liability for damage resulting from the failure to use the device for its intended purpose or for damage caused by external forces or any other external factors.

⇒ Refer to the technical data for limits and fields of application as well as possible uses (see Chapter 3.3).

#### Reasonably foreseeable misuse

The product (TROVIS 5573) is not suitable for the following applications:

- Use outside the limits defined during sizing and by the technical data

Furthermore, the following activities do not comply with the intended use:

- Use of non-original spare parts
- Performing service and repair work not described

#### Qualifications of operating personnel

The product (TROVIS 5573) must be mounted, started up, serviced and repaired by fully trained and qualified personnel only; the accepted industry codes and practices must be observed. According to the mounting and operating instructions, trained personnel refers to individuals who are able to judge the work they are assigned to and recognize possible hazards due to their specialized training, their knowledge and experience as well as their knowledge of the applicable standards.

#### Personal protective equipment

No personal protective equipment is required for the direct handling of the product (TROVIS 5573).

#### Revisions and other modifications

Revisions, conversions or other modifications of the product (TROVIS 5573) are not authorized by SAMSON. They are performed at the user's own risk and may lead to safety hazards, for example. Furthermore, the product may no longer meet the requirements for its intended use.

#### Warning against residual hazards

The heating controller has direct influence on controlled components of the heating system (e.g. control valves and pumps). To avoid personal injury or property damage, plant operators and operating personnel must prevent hazards that could be caused in the plant components by the process medium, the operating pressure, the signal pressure or by moving parts by taking appropriate precautions. Plant operators and operating personnel must observe all hazard statements, warnings and caution notes in the referenced documents.

#### Responsibilities of the operator

Operators are responsible for proper use and compliance with the safety regulations. Operators are obliged to provide these mounting and operating instructions to the operating personnel and to instruct them in proper operation. Furthermore, operators must ensure that operating personnel or third parties are not exposed to any danger.

The operator must ensure that the heating controller is always operated with the latest firmware version.

- ⇒ Update the heating controller on a regular basis.
- ⇒ Download the currently valid firmware at
  - ▶ [www.samsongroup.com](http://www.samsongroup.com) > DOWNLOADS > Software & Drivers > Firmware.

### Responsibilities of operating personnel

Operating personnel must read and understand these mounting and operating instructions as well as the specified hazard statements, warnings and caution notes. Furthermore, operating personnel must be familiar with the applicable health, safety and accident prevention regulations and comply with them.

### Referenced standards, directives and regulations

The product (TROVIS 5573) with a CE marking fulfills the requirements of the following Directives:

- RoHS Directive 2011/65/EU
- EMC Directive 2014/30/EU
- Low-voltage Directive 2014/35/EU

The declarations of conformity and certificates are included in Chapter 15.

The product (TROVIS 5573) with a CE marking is designed for use in low voltage installations.

- ⇒ For wiring, maintenance and repair, observe the relevant safety regulations.

## 1.1 Notes on possible severe personal injury

### **⚠ DANGER**

#### **Risk of fatal injury due to electric shock.**

- ⇒ Before connecting wiring, performing any work on the device or opening the device, disconnect the supply voltage and protect it against unintentional reconnection.
- ⇒ Only use protective equipment that can be protected against unintentional reconnection of the power supply.
- ⇒ Do not remove any covers to perform adjustment work on live parts.

## 1.2 Notes on possible property damage

### **ⓘ NOTICE**

#### **Risk of damage to the heating controller due to the supply voltage exceeding the permissible tolerances.**

The heating controller is designed for use in low voltage installations.

- ⇒ Observe the permissible tolerances of the supply voltage.

### **ⓘ NOTICE**

#### **Malfunction due to a configuration that does not meet the requirements of the application.**

The heating controller is configured for specific applications by setting functions and parameters. Function and parameter settings have a direct effect on final control elements.

- ⇒ Perform the configuration for the specific application.

### **ⓘ NOTICE**

#### **Manipulation of the configuration due to unauthorized access.**

The heating controller can be protected against unauthorized access through entering a key number. The key number for first start-up can be found at the back of these mounting and operating instructions.

- ⇒ Do not pass the key number on to unauthorized persons. Keep it in a safe place inaccessible to unauthorized persons.

### **ⓘ NOTICE**

#### **Risk of heating controller damage due to large differences in temperature.**

- ⇒ Before start-up, wait until the heating controller has reached the ambient temperature.

### NOTICE

#### **System damage caused by frost.**

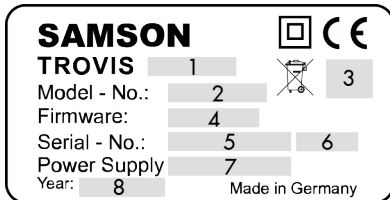
Frost protection is deactivated in the manual mode.

- ⇒ Do not run the heating during cold weather in the manual mode for long periods of time.

## 2 Markings on the device

### 2.1 Nameplate

The nameplate shown was up to date at the time of publication of this document. The nameplate on the device may differ from the one shown.



- 1 Type designation
- 2 Model number
- 3 Other mark of conformity
- 4 Firmware version
- 5 Serial number
- 6 Fuse protection
- 7 Supply voltage
- 8 Date of manufacture

### 2.2 Firmware versions

Firmware revisions	
Old	New
1.80	1.82
	Internal revisions
1.82	1.90
	In the configuration level CO1, the <b>four-point characteristic</b> function can also be configured for systems 3.x (see CO1 → F11).
	The demand for the maximum flow set point issued by a 0 to 10 V signal can be made with an adjustable boost (see CO1 → F18 - 1).
	The controller can be connected to an optional Modbus gateway.
1.90	1.95
	The priority operation (reverse control or set-back operation) can be set independently from the time and temperature course of the system (see Chapter 16).
	The CO1 → F20 - 1 setting allows an external demand for heat to be made when insufficient heat is supplied (see Chapter 16).
1.95	2.00
	The limit switch for creep feed rate limitation can also be connected to input RÜF1. In previous versions, it could only be connected to terminals 04/12 (see Chapter 16).
2.00	2.12
	New hydraulic system 11.6 (see Chapter 16).
	New <b>cooling control</b> function (see Chapter 16). The cooling control function causes a reversal of the operating direction and a minimum limitation of the return temperature in RK1/RK2.
	The demand processing using a 0 to 10 V signal can be applied variably to the 0 to 130 °C transmission range (see Chapter 16).

## Markings on the device

Firmware revisions	
Old	New
2.12	<b>2.13</b>
	The priority operation functions ( <b>reverse control</b> and <b>set-back operation</b> ) can be activated for system 4.5 either for one heating circuit (RK1 or RK2) or for both heating circuits (RK1 and RK2). See Chapter 16.
	New function to <b>control the speed of the charging pump</b> based on the charging progress (see Chapter 16).
2.13	<b>2.14</b>
	Error messages can be issued over binary inputs BE1 and/or BE2 with the binary input as a make or break contact (see Chapter 16).
2.14	<b>2.20</b>
	New hydraulic systems 16.x (buffer tank systems). See Chapter 16.
	In this firmware version and higher, the drying of jointless floors is not canceled due to a deviation in the flow temperature (see Chapter 16).
2.20	<b>2.24</b>
	Internal revisions
2.24	<b>2.26</b>
	Function to <b>receive outdoor temperature as 0 to 10 V signal</b> extended (CO5 → F23) Outdoor temperatures can be received or sent using a 0 to 10 V signal.
2.26	<b>2.28</b>
	New system 11.5 (see Chapter 16).
2.28	<b>2.30</b>
	It is possible to connect PTC and Ni1000 sensors (Pt1000 sensors could only be connected in previous firmware versions)
2.30	<b>2.41</b>
	New functions and parameters for buffer tank systems (see Chapter 16). <ul style="list-style-type: none"> <li>- CO1 → F22: SLP depending on return temperature</li> <li>- CO5' → F01: AA1 reverse</li> <li>- CO5' → F07: Zero shift CO5'</li> </ul>
	New parameters in PA1 parameter level: <ul style="list-style-type: none"> <li>- Minimum set point to charge buffer tank</li> <li>- Stop charging of the buffer tank</li> <li>- Charging temperature boost</li> <li>- Lag time for storage tank charging pump</li> </ul>
	New parameters in PA4 parameter level: <ul style="list-style-type: none"> <li>- Maximum buffer tank temperature</li> </ul>
	New <b>differential temperature control</b> function (CO1 → F23) in systems 1.0 and 16.0 (see Chapter 16). Restrictions when a mini module (order no. 1400-7436) is used (see Chapter 16).
2.41	<b>2.45</b>
	An active <b>cold charging protection</b> function allows the valve position to be determined between 1 and 100 % (default 10 %).
2.45	<b>2.48</b>
	Internal revisions

Firmware revisions	
Old	New
2.48	2.51
	Meaning of CO1, CO2 → F02 changed: F02 - 1 = Outdoor-temperature-compensated control active
	Buffer tank systems: The measured value SF1 is now also relevant to end charging
	Discharging protection for DHW storage tank and buffer tank
	Separate boost adjustable for underfloor heating circuits
	Heating circuits can be configured to be circuits only processing demand with the settings CO1' → F00 - 1 and CO2' → F00 - 1
	Transmission range setting for 0 to 10 V signal to process external demand changed to CO5' → F07
	Default setting of heating characteristic 1.2 (0.5 for underfloor heating)
	Default setting of the maximum flow temperature: 70 °C
Delayed outdoor temperature adaptation adjustable in steps of 0.1 °C	
2.51	2.61
	New <b>variable night set-back</b> function can be configured separately for each heating circuit (setting: CO1', CO2' → F04 - 1)
	Function blocks CO1' → F03 and CO4' → F03 added to activate the discharging protection
	Free assignment of analog output: the CO5' → F10 setting is used to determine which output signal is to be issued at the 0 to 10 V output.
2.61	2.63
	New option configurable: 14 = 3 V supply for analog outputs
2.63	3.00.xx
	Harmonization of versions
3.00.xx	3.05.xx
	Internal optimization
3.05.xx	3.06.xx
	Remote start of drying of jointless floors over Modbus register
	Display all active and resolved error messages in the alarm log
	Internal optimization

### NOTICE

#### **Mandatory update for digital products and software.**

The firmware is being constantly developed further. In some cases, an older firmware version than that described in this chapter may be installed in a heating controller in the delivered state.

⇒ Update the heating controller on a regular basis.

⇒ Download the currently valid firmware at ► [www.samsongroup.com](http://www.samsongroup.com) > DOWNLOADS > Software & Drivers > Firmware and install it.

### Tip

The SAMSON NE53 newsletter keeps users up to date on any software or hardware revisions in accordance with NAMUR Recommendation NE 53. You can subscribe to the newsletter at ► [www.samsongroup.com](http://www.samsongroup.com) > SERVICE > NE53 newsletter.

### 3 Design and principle of operation

The TROVIS 5573 Heating and District Heating Controller is used to control up to two control circuits.

- Control of a primary heat exchanger or boiler with one mixing heating circuit and one non-mixing heating circuit (both outdoor-temperature-compensated) and control of DHW heating in the secondary circuit
- Outdoor-temperature-compensated buffer tank control with solid fuel boiler and solar circuit control
- Control of one outdoor-temperature-compensated heating circuit and a DHW heating with two valves in the primary circuit
- Control of two outdoor-temperature-compensated heating circuits with two valves in the primary circuit

The heating controller is adapted to the specific system by setting the appropriate system code number. Additional sensors and/or functions which are not part of the system's basic configuration can be selected in the function blocks. The switch positions ⇄ and entry of the key number allow access to the corresponding levels. For trained personnel, the configuration levels used to set function blocks are indicated by 'CO' and the parameter levels are indicated by 'PA'. Data is retrieved and entered at the heating controller using a rotary pushbutton.

Data input is facilitated by icons displayed on the LCD.

The rotary switch is used to set the operating mode and the key parameters required for individual circuits.

#### 3.1 Configuration using the TROVIS-VIEW software

The heating controller can be configured with the TROVIS-VIEW software.

In this case, the TROVIS 5573 Heating and District Heating Controller is connected to the computer at the RJ-45 port on the side of the controller.

The TROVIS-VIEW software enables the user to easily configure the heating controller as well as view process parameters online.

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#### **i Note**

*TROVIS-VIEW can be downloaded free of charge from the SAMSON website at ► [www.samsongroup.com](http://www.samsongroup.com) > DOWNLOADS > Software & Drivers > TROVIS-VIEW. Further information on TROVIS-VIEW (e.g. system requirements) is available on our website and in the Data Sheet ► T 6661 as well as in the Operating Instructions ► EB 6661.*

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#### 3.2 Connection to SAM DISTRICT ENERGY

The heating controller can be configured and operated on a computer, smartphone or tablet computer using the SAM DISTRICT ENERGY industry-specific application.

The heating controller is connected to SAM DISTRICT ENERGY over the Modbus interface using a communication gateway.

SAM DISTRICT ENERGY allows the remote start-up and set-up of the heating controllers. Key information of the heating controller and entire heating system is clearly visualized at one central location.

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#### **i Note**

*SAM DISTRICT ENERGY is a web-based solution for managing, controlling and optimizing heating systems in the local heat supply and district heating networks. You can find more information and test SAM DISTRICT ENERGY using a demo account on our website at ► [www.samsongroup.com](http://www.samsongroup.com) > PRODUCTS > Digital solutions > SAM DISTRICT ENERGY.*

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### 3.3 Technical data

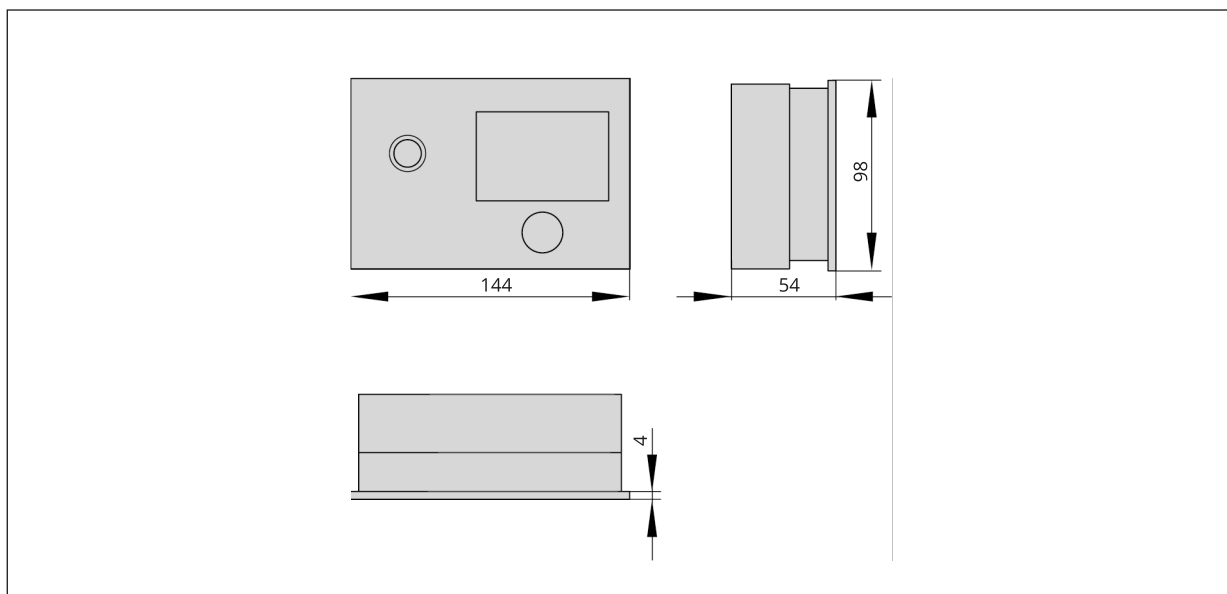
**Table 1:** *Technical data*

TROVIS 5573		
Inputs	8x inputs for Pt1000, PTC or Ni1000 temperature sensors and 2x binary inputs Terminal 11 as 0 to 10 V input (e.g. for external demand or outdoor temperature signal)	
Outputs <sup>1)</sup>	2x three-step signal: rating max. 250 V AC, 2 A, alternatively 2x on/off signal: rating max. 250 V AC, 2 A 3x pump output: rating max. 250 V AC, 2 A; All outputs are relay outputs with varistor suppression Terminal 11 as 0 to 10 V output (e.g. for continuous closed loop control, outdoor temperature, signal for external demand or pump speed control) Load >5 kΩ	
Optional interfaces	1x Modbus RS-485 interface for two-wire bus using RS-485 communication module (Modbus RTU protocol, data format 8N1, RJ-45 port at the side)	
Supply voltage	85 to 250 V	
Power line frequency	48 to 62 Hz	
Power consumption	Max. 4.7 VA, typical: 2.3 VA	
Permissible ambient temperature range		
	Operation	0 to 55 °C
	Transportation and storage	-10 to +60 °C
Degree of protection	IP40 according to EN 60529	
Class of protection	II according to EN 61140	
Degree of contamination	2 according to EN 61010-1	
Overvoltage category	II according to EN 60664-1	
Noise immunity	According to EN 61000-6-1	
Noise emission	According to EN 61000-6-3	
Conformity		
Weight	Approx. 0.5 kg	

<sup>1)</sup> For systems with one control circuit, a maximum of four pumps are available

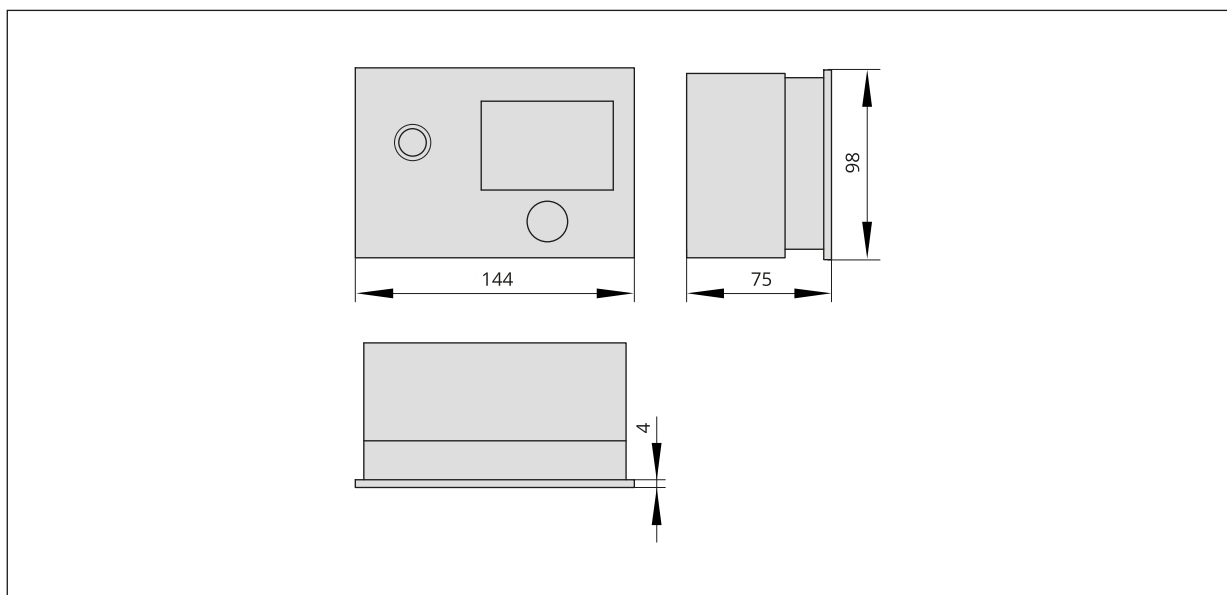
### 3.4 Dimensions

Panel cut-out: 138 x 92



**Fig. 1:** Dimensions in mm · Heating and district heating controller with standard base

Panel cut-out: 138 x 92



**Fig. 2:** Dimensions in mm · Heating and district heating controller with high housing base

### 3.5 Values for resistance thermometers

#### Pt1000 sensors

Temperature in °C	-100	-90	-80	-70	-60	-50	-40	-35	-30	-25	-20
Resistance in Ω	602.6	643.0	683.3	723.3	763.3	803.1	842.7	862.5	882.2	901.9	921.6
Temperature in °C	-15	-10	-5	0	+5	+10	+15	+20	+25	+30	+35
Resistance in Ω	941.2	960.9	980.4	1000.0	1019.5	1039.0	1058.5	1077.9	1097.3	1116.7	1136.1
Temperature in °C	+40	+45	+50	+55	+60	+65	+70	+75	+80	+85	+90
Resistance in Ω	1155.4	1174.7	1194.0	1213.2	1232.4	1251.6	1270.8	1289.9	1309.0	1328.1	1347.1
Temperature in °C	+95	+100	+105	+110	+115	+120	+125	+130	+135	+140	+145
Resistance in Ω	1366.1	1385.1	1404.0	1422.9	1441.8	1460.7	1479.5	1498.3	1517.1	1535.8	1554.6
Temperature in °C	+150	+155	+160	+165	+170	+175	+180	+185	+190	+195	+200
Resistance in Ω	1573.3	1591.9	1610.5	1629.1	1647.7	1666.3	1684.8	1703.3	1721.7	1740.2	1758.6

#### PTC sensors

Temperature in °C	-20	-10	0	+10	+20	+30	+40	+50
Resistance in Ω	693	756	824	896	971	1050	1133	1220
Temperature in °C	+60	+70	+80	+90	+100	+110	+120	
Resistance in Ω	1311	1406	1505	1606	1713	1819	1925	

#### Type 5244 Remote Control Unit

Switch position ☉, terminals 1 and 2

Temperature in °C	10	15	20	25	30
Resistance in Ω	679	699	720	741	762

#### Ni1000 sensors

Temperature in °C	-60	-50	-40	-30	-20	-10	0	+10	+20	+30	+40
Resistance in Ω	695	743	791	841	893	946	1000	1056	1112	1171	1230
Temperature in °C	+50	+60	+70	+80	+90	+100	+110	+120	+130	+140	+150
Resistance in Ω	1291	1353	1417	1483	1549	1618	1688	1760	1833	1909	1986
Temperature in °C	+160	+170	+180	+190	+200	+210	+220	+230	+240	+250	
Resistance in Ω	2066	2148	2232	2318	2407	2498	2592	2689	2789	2892	

### 4 Shipment and on-site transport

The work described in this chapter is to be performed only by personnel appropriately qualified to carry out such tasks.

#### 4.1 Accepting the delivered goods

After receiving the shipment, proceed as follows:

1. Compare the shipment received with the delivery note.
2. Check the shipment for transportation damage. Report any damage to SAMSON and the forwarding agent (refer to delivery note).

#### 4.2 Removing the packaging from the heating controller

##### **i Note**

*Do not remove the packaging until immediately before mounting and start-up.*

1. Remove the packaging from the heating controller.
2. Check scope of delivery (see Table 2).
3. Dispose and recycle the packaging in accordance with the local regulations.

**Table 2:** Scope of delivery

1x TROVIS 5573 Heating and District Heating Controller
1x Document IP 5573 (Important Product Information)

#### 4.3 Transporting the heating controller

##### Transport instructions

- Protect the heating controller against external influences (e.g. impact).
- Protect the heating controller against moisture and dirt.
- Observe transport temperature depending on the permissible ambient temperature (see Chapter 3).

#### 4.4 Storing the heating controller

##### **NOTICE**

**Risk of heating controller damage due to improper storage.**

- ⇒ Observe the storage instructions.
- ⇒ Avoid longer storage periods.
- ⇒ Contact SAMSON in case of different storage conditions.

##### **i Note**

*SAMSON recommends to regularly check the prevailing storage conditions during long storage periods.*

##### Storage instructions

- Protect the heating controller against external influences (e.g. impact).
- Protect the heating controller against moisture and dirt. Store it at a relative humidity of less than 75 %. In damp spaces, prevent condensation. If necessary, use a drying agent or heating.
- Make sure that the ambient air is free of acids or other corrosive media.
- Observe transport temperature depending on the permissible ambient temperature range (see Chapter 3).
- Do not place any objects on the heating controller.

## 5 Installation

The work described in this chapter is to be performed only by personnel appropriately qualified to carry out such tasks.

### 5.1 Installation conditions

#### Work position

The work position is the front view onto the operating controls on the heating controller seen from the position of operating personnel.

Operators must ensure that, after installation of the heating controller, the operating personnel can perform all necessary work safely and easily access the heating controller from the work position.

### 5.2 Preparation for installation

Before mounting, make sure that the following conditions are met:

- The heating controller is not damaged.

Proceed as follows:

- ⇒ Lay out the necessary material and tools to have them ready during mounting.

### 5.3 Mounting the heating controller

The heating controller consists of the housing with the electronics and the base with the terminals. It is suitable for panel, wall and rail mounting.

- ⇒ See Fig. 3.

#### Panel mounting

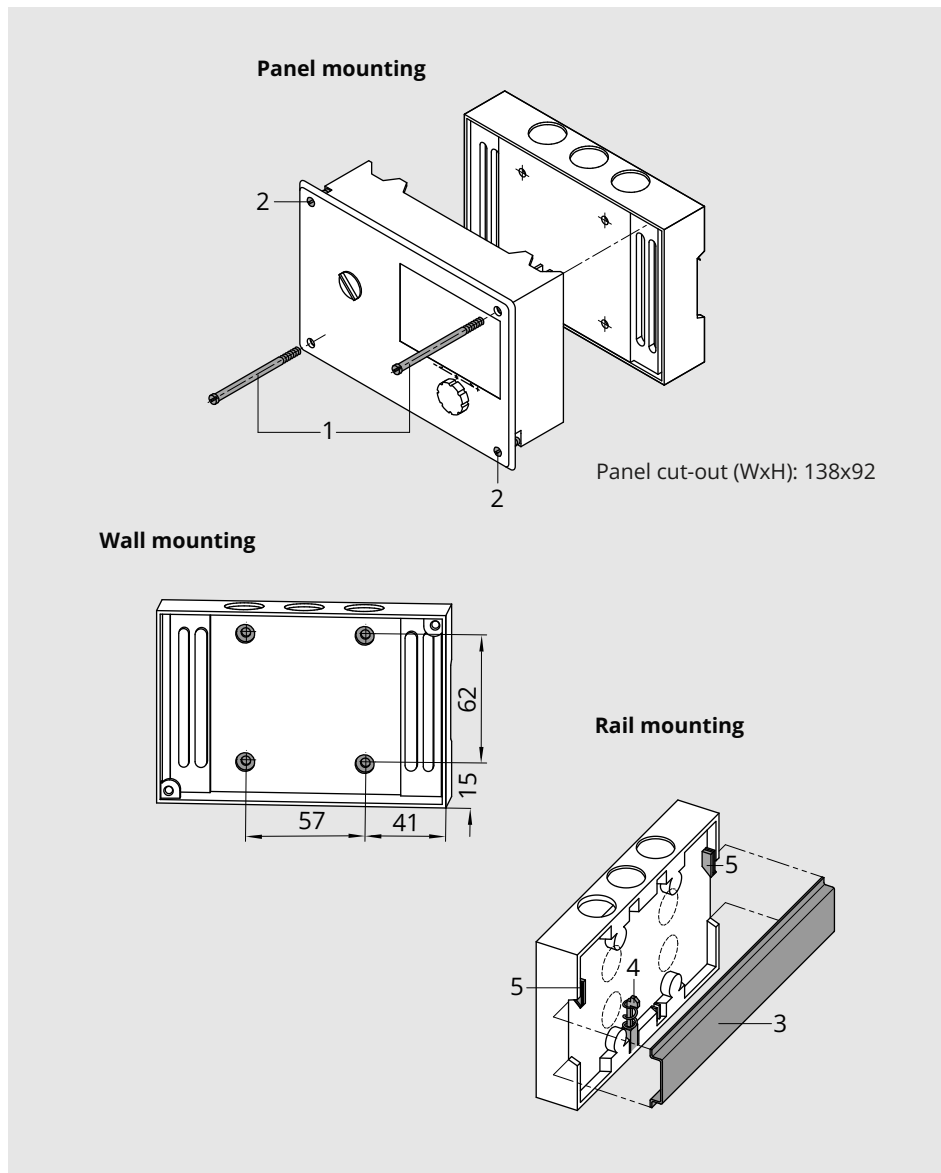
1. Undo the two screws (1).
2. Pull apart the controller housing and the base.
3. Make panel cut-out with the dimensions 138x92 mm (WxH).
4. Push the controller housing through the panel cut-out.
5. Tighten the two screws (2) to clamp the controller housing against the control panel.
6. Perform the electric wiring on the base as described in Chapter "Electrical connection".
7. Remount the controller housing.
8. Tighten the two screws (1).

#### Wall mounting

1. Undo the two screws (1).
2. Pull apart the controller housing and the base.
3. If necessary, drill holes with the specified dimensions in the appropriate places. Fasten the base with four screws.
4. Perform the electric wiring on the base as described in Chapter "Electrical connection".
5. Remount the controller housing.
6. Tighten the two screws (1).

#### Rail mounting

1. Fasten the spring-loaded hook (4) at the bottom of the top hat rail (3).
2. Slightly push the controller upwards and pull the top hook (5) over the top hat rail. Undo the two screws (1).
3. Pull apart the controller housing and the base.
4. Perform the electric wiring on the base as described in Chapter "Electrical connection".
5. Remount the controller housing.
6. Tighten the two screws (1).



**Fig. 3:** Mounting · Dimensions in mm

## 5.4 Electrical connection

### **⚠ DANGER**

#### **Risk of fatal injury due to electric shock.**

For wiring and connecting the heating controller, observe the relevant electrotechnical regulations of the country of use as well as the technical connection requirements of the grid operator in charge. Therefore, such work must be performed by properly trained and experienced personnel.

The terminals 20, 22, 25 and 28 allow the integration of safety equipment which have a direct influence on individual electric actuators and pumps. If this is not the case, connect a jumper from terminal 18 to terminals 20, 22, 25 and 28.

- ⇒ Do not connect ELV cables (according to DIN-VDE 0100) to these terminals.
- ⇒ Before performing any work on the terminals, disconnect the voltage supply from the heating controller.
- ⇒ Protect it against unintentional reconnection.

#### **Notes on electric wiring**

- ⇒ Install the 230 V power supply lines and the signal lines separately and with sufficient space between them.
- ⇒ To increase immunity, keep a minimum distance of 10 cm between the lines. Make sure the minimum distance is also kept when the lines are installed in a cabinet.
- ⇒ Install the lines for digital signals (bus lines) and analog signals (sensor lines, analog outputs) separately and with sufficient space between them.
- ⇒ In systems with a high electromagnetic noise level, use shielded cables for the analog signals.
- ⇒ Ground the shield at one side, either at the control cabinet inlet or outlet, using the largest possible cross-section. Connect the central grounding point and the PE grounding conductor with a cable with at least 10 mm<sup>2</sup> wire cross-section using the shortest route.
- ⇒ Inductances in the control cabinet (e.g. contactor coils) must be equipped with suitable interference suppressors (RC elements).

- ⇒ Shield control cabinet elements with high field strength (e.g. transformers or frequency converters) with separators providing a good connection to the PE grounding conductor.

- ⇒ Use wires with wire cross-section as listed in Table 3 for the terminals.

#### **Overvoltage protection**

- ⇒ If signal lines are installed outside buildings or over large distances, make sure appropriate surge or overvoltage protection measures are taken. Such measures are indispensable for bus lines.
- ⇒ The shield of signal lines installed outside buildings must have current conducting capacity and must be grounded on both sides.
- ⇒ Install surge diverters at the entry of the control cabinet.

#### **Connecting the heating controller**

- ⇒ If the controller housing and the base have not yet been separated, undo the screws on the bottom left and top right of the front housing. Pull the controller off the base to connect the wiring.
- ⇒ To feed through cables, make holes in the marked locations at the top, bottom or back of the base of the housing and fit suitable grommets or cable glands.
- ⇒ For wall mounting: Ensure that the cables are not subject to torsion or bending by taking suitable precautions (e.g. use cable ducts) before inserting them into the base.

#### **Connecting sensors**

The wire cross-section of the sensor cables must not be smaller than 0.5 mm<sup>2</sup>.

#### **Wiring of a room panel**

- ⇒ Connect as shown in Fig. 6 and Fig. 7.

#### **Connecting electric actuators**

- ⇒ 0 to 10 V output: Use cables with a minimum wire cross-section of 0.5 mm<sup>2</sup>.
- ⇒ Three-step or on/off outputs: Connect cables with a minimum wire cross-section of 1.5 mm<sup>2</sup> suitable for damp locations to the terminals of the controller output. We recommend checking the operating direction on start-up.

## Installation

### Connecting pumps

- ⇒ Connect all cables with at least a 1.5 mm<sup>2</sup> wire cross-section to the terminals of the heating controller as illustrated in the wiring diagram.

---

#### **i Note**

*The electric actuators and pumps are not automatically supplied with a voltage by the heating controller. They can be connected over terminals 20, 22, 25 and 28 to an external voltage supply. For an internal power supply, place a jumper from terminal 18 to terminals 20, 22, 25 and 28.*

---

#### **⚠ DANGER**

***Risk of fatal injury as a result of failing to observe the permissible touch voltage.***

*Separation of the circuits is absolutely essential when SELV equipment is connected to terminals 20, 22, 25 and 28 as this equipment has a different intended use of the supply voltage than specified in the technical data (230 V AC).*

*The creepage and clearance present in the base and heating controller do not guarantee the required dielectric strength and the safe separation of the 230 V supply voltage and the other circuits.*

- ⇒ *Take appropriate safety precautions (e.g. by using coupling relays for the control of electric actuators operated with 24 V or for ELV fault signaling contacts).*
  - ⇒ *Only connect 230 V equipment.*
-

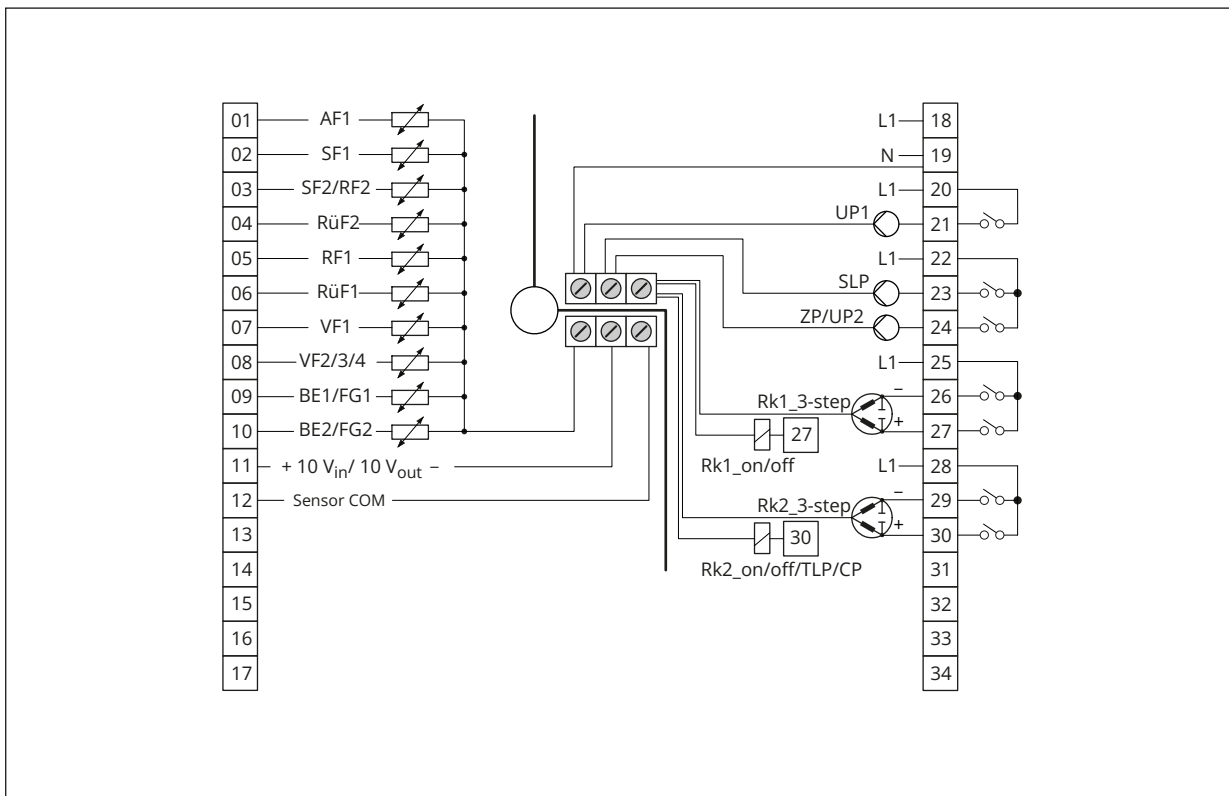


Fig. 4: Wiring of TROVIS 5573 Controller with standard base

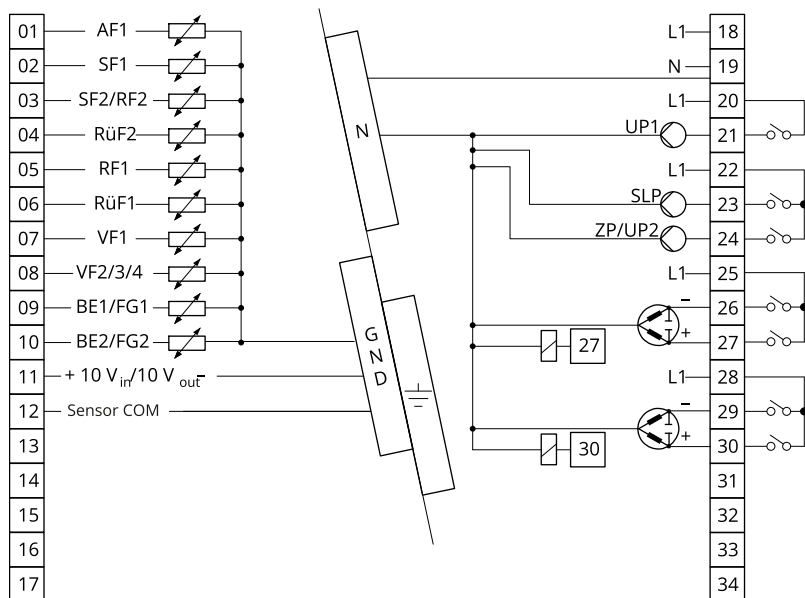
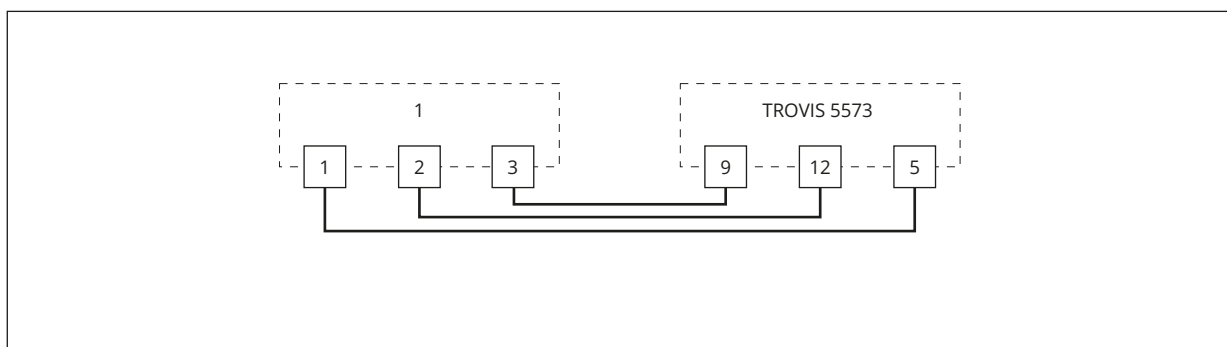


Fig. 5: Wiring of TROVIS 5573 Controller with high base

## Installation

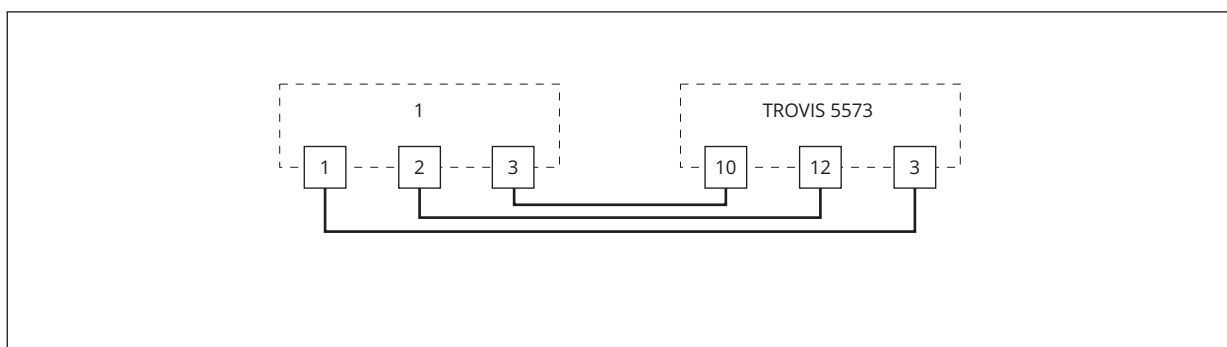
### Abbreviations

AF	Outdoor sensor
BE	Binary input
CP	Solar circuit pump
FG	Potentiometer
RF	Room sensor
RK	Control circuit
RüF	Return sensor
SF	Storage tank sensor
SLP	Storage tank charging pump
TLP	Heat exchanger charging pump
UP	Circulation pump (heating)
VF	Flow sensor
ZP	Circulation pump (DHW)



**Fig. 6:** Wiring of a room panel for RK1

1 Type 5257-5(x) Room Panel; Type 5244 no longer available.



**Fig. 7:** Wiring of a room panel for RK2

1 Type 5257-5(x) Room Panel; Type 5244 no longer available.

**Table 3:** Permissible conductor cross-section for terminals

Cable	Conductor cross-section
Single-wire	0.33 to 2 mm <sup>2</sup>
Multi-wire	0.33 to 2 mm <sup>2</sup>

Length of insulation to be stripped off the conductor ends: 6 mm

## 6 Operation

The heating controller is operated on site using the operating controls on the front.

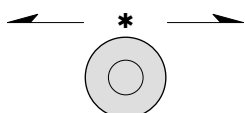
### 6.1 Operating controls

The operating controls are located in the front panel of the heating controller.

The rotary pushbutton is used to select readings, parameters and function blocks.

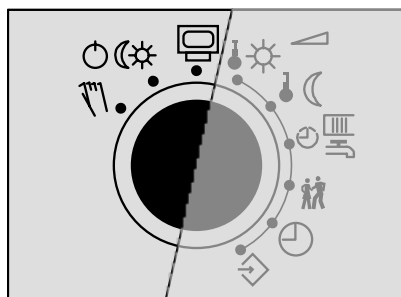
The rotary switch is used to set the operating mode and the key parameters for each control circuit.

#### Rotary pushbutton

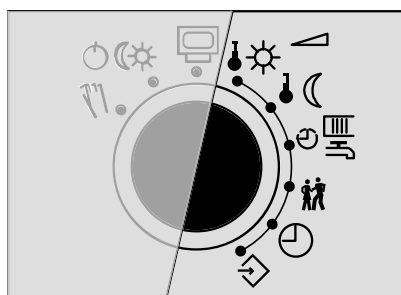


- ↻ Turn  
Select readings, parameters and function blocks.
- \* Press  
Confirm adjusted selection or settings.

#### Rotary switch




- ☰ Operating level
- ☀☾ Operating modes
- 👤 Manual level







- ☀ Day set point (rated room temperature)
- ☾ Night set point (reduced room temperature)
- 🕒 Times-of-use for heating/DHW
- 👤 Special time-of-use
- 🕒 Time/date
- ⚙ Settings (parameter and configuration level)

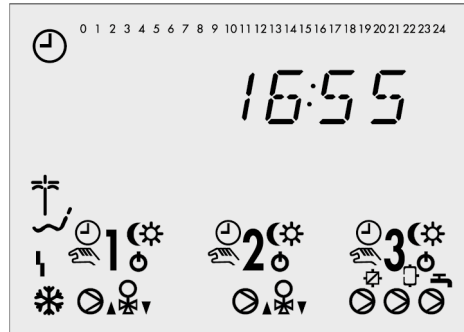
## Operation

### 6.2 Display









In the normal switch position  (operating level), the time as well as information on the controller are indicated on the display. Turn the rotary knob to read the times-of-use together with the temperature values of the various control circuits. They are represented by black squares below the row of numbers. Icons indicate the operating status of the controller.

#### Icons









-  Public holiday mode
-  Vacation mode
-  Error during operation
-  Frost protection











#### Heating circuit 1

-  Automatic mode
-  Night mode
-  Day mode
-  Manual mode
-  Control operation deactivated
-  Circulation pump (heating) UP1 <sup>1)</sup>
-  Valve RK1 OPEN
-  Valve RK1 CLOSED

#### Heating circuit 2

-  Automatic mode
-  Night mode
-  Day mode
-  Manual mode
-  Control operation deactivated
-  Circulation pump (heating) UP2 <sup>1)</sup>
-  Valve RK2 OPEN
-  Valve RK2 CLOSED

#### DHW circuit

-  Automatic mode
-  Night mode
-  Day mode
-  Manual mode
-  Control operation deactivated
-  Pump output TLP/CP <sup>1)</sup>
-  Storage tank charging pump SLP <sup>1)</sup>
-  Circulation pump ZP <sup>1)</sup>

<sup>1)</sup> UP1, UP2, TLP, CP, SLP and ZP indicate possible choices for pump selection in manual mode.

### 6.3 Optional interfaces

#### Two-wire bus system

The optional RS-485 communication module is required to connect the controller to a two-wire bus network for Modbus RTU communication with a process control system.

## 6.4 Accessories

**Table 4:** *Accessories*

Memory module	Order no. 1400-9379
Mini module	Order no. 1400-7436
Data logging module	Order no. 1400-9378
USB Converter 3	Order no. 1400-9377
TROVIS-VIEW software (free of charge)	▶ <a href="http://www.samsunggroup.com">www.samsunggroup.com</a> > DOWNLOADS > Software & Drivers > TROVIS-VIEW
4-port bus hub	Order no. 1400-7140
RS-485 communication module	Order no. 8812-2002
Surge arrester SA 5000	Order no. 1400-9868
▶ SAM HOME Gateway for communication via Ethernet	Type 5660
▶ SAM MOBILE Gateway for communication via mobile phone network	Type 5655

## 7 Start-up and configuration

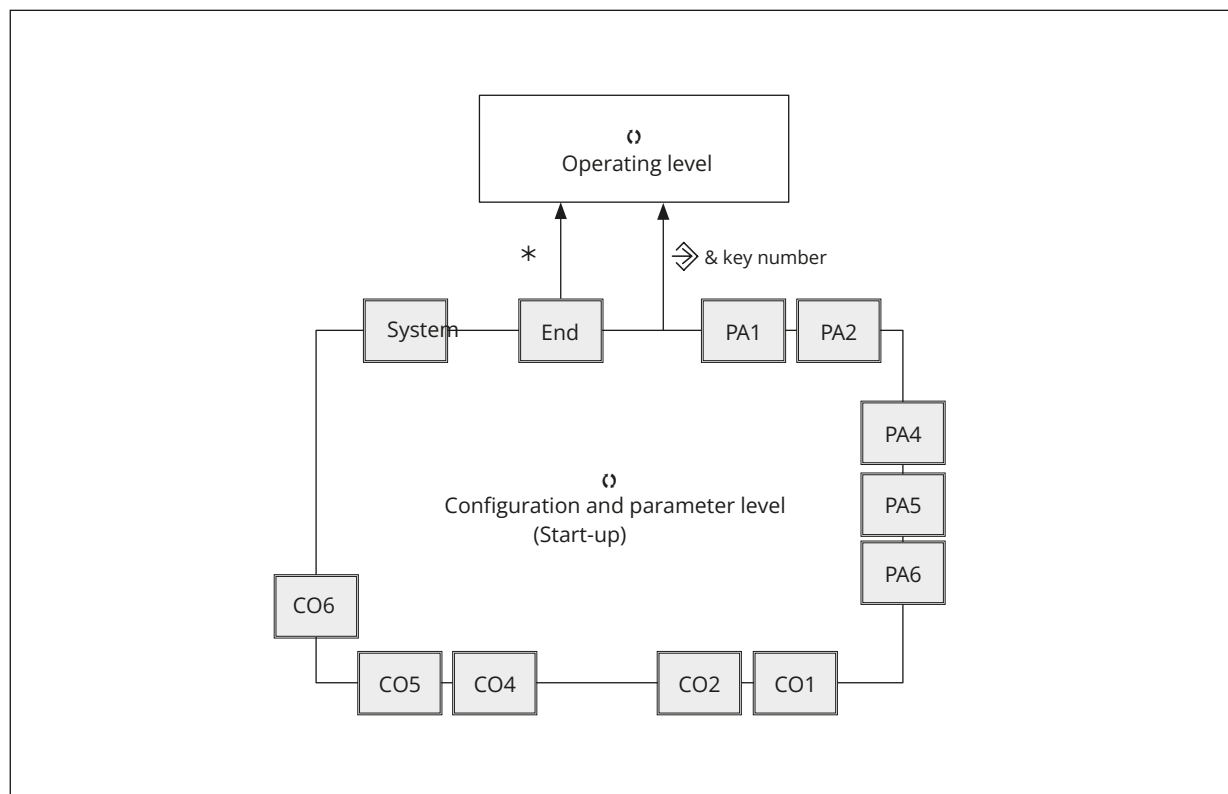


Fig. 8: Level structure of TROVIS 5573

### Legend for level structure

PA1/CO1:	HC1 (heating circuit 1)
PA2/CO2:	HC2 (heating circuit 2)
PA4/CO4:	DHW circuit
PA5/CO5:	System-wide
CO5:	System-wide
PA6/CO6:	Communication
System:	System code number

The work described in this chapter is to be performed only by personnel appropriately qualified to carry out such tasks.

#### ⇒ Before start-up, make sure the following conditions are met:

- The heating controller is properly mounted according to the instructions.
- The electrical connection is properly performed.
- The firmware corresponds to the version that is currently available.

The currently valid firmware can be downloaded at ► [www.samsongroup.com](http://www.samsongroup.com) > DOWNLOADS > Software & Drivers > Firmware (see Chapter 10).

The heating controller is adapted to its control task by performing start-up. Start-up usually involves performing several steps:

1. Select the hydraulic schematics (see Chapter 7.1).
2. Change functions and parameters to adapt the system (see Chapters 7.2 and 7.3).
3. Calibrate the sensors (see Chapter 7.4).

The modifications of the controller configuration and parameter settings described in this chapter can only be performed after the valid key number has been entered.

The valid key number for first start-up can be found at the back of these mounting and operating instructions. To avoid unauthorized use of the service key number, remove the page or make the key number unreadable. In addition, it is possible to enter a new, customized key number (see Chapter 7.5).

## 7.1 Setting the system code number

Different hydraulic schematics are available. Each hydraulic schematic is represented by a system code number. The systems are shown together with their ready-configured functions (see Chapter 16).


A system is adapted to individual requirements by setting the functions and parameters. Changing the system code number resets previously adjusted function blocks to their default settings. Function block parameters and parameter level settings remain unchanged.

The system code number is set in the configuration and parameter level.




### Procedure

Set the rotary switch to  (parameter and configuration level).


Reading: **0 0 0 0**

-  Enter valid key number.
- \* Confirm key number.

Reading: **PA\_**

-  Select **Anl.**
- \* Activate editing mode for the system.  
Reading:  blinks.
-  Select system code number.
- \* Confirm.

Reading: **End**

Turn the rotary switch to  (operating level).

## 7.2 Activating and deactivating functions

A function is activated or deactivated in the associated function block. Appendix A (configuration instructions) contains a detailed description of all functions.

0 to 24 at the top of the display represent the function block numbers. When a configuration level is opened, the activated function blocks are indicated by a black square on the right-hand side below the function block number. For more details on function blocks (see Appendix A (configuration instructions)).


The functions are grouped by topics.

- CO1: HC1 (heating circuit 1)
- CO2: HC2 (heating circuit 2)
- CO4: DHW circuit
- CO5: System-wide
- CO6: Modbus communication

### Procedure

Set the rotary switch to  (parameter and configuration level).

Reading: **0 0 0 0**

-  Enter valid key number.

## Start-up and configuration

\* Confirm key number.

Reading: **PA\_**

⌚ Select configuration level.

\* Open the configuration level.

⌚ Select function block.

Activated function blocks are marked '- 1'.

Deactivated function blocks are marked '- 0'.

\* Activate editing mode for function block.

Reading: **←** blinks.

⌚ Activate function block.

Reading: **F\_-1**

An activated function block is indicated by a black square below (right) the function block number at the top of the controller display.

**or:**

⌚ Deactivate function block.

Reading: **F\_-0**

\* Confirm setting.

If the function block is not closed, further function block parameters can be adjusted.

a) Set function block parameter.

b) Confirm function block parameter.

If applicable, the next function block parameter is displayed.


Confirm all function block parameters to exit the opened function block.

To configure further function blocks in the opened configuration level, repeat the steps 'Select configuration level.' onwards.

⌚ Select **End**.

\* Exit the configuration level.

To configure further function blocks in other configuration levels, repeat steps highlighted in gray.


Turn the rotary switch to  (operating level).

---

### **i Note**

*All parameter settings are saved in a non-volatile memory in the heating controller.*

---

Set the rotary switch to  (parameter and configuration level).

Reading: **0 0 0 0**

⌚ Enter valid key number.

\* Confirm key number.

Reading: **PA\_**

### 7.3 Changing parameters

Depending on the system code number selected and the activated functions, not all parameters listed in the parameter list in the appendix (see Annex A) might be accessible.

The parameters are grouped by topics.

PA1: HC1 (heating circuit 1)  
 PA2: HC2 (heating circuit 2)  
 PA4: DHW circuit  
 PA5: System-wide  
 PA6: Communication parameters

#### Procedure

Set the rotary switch to  $\diamond$  (parameter and configuration level).

Reading: **0 0 0 0**

⌂ Enter valid key number.

\* Confirm key number.

Reading: **PA\_**

- ⌂ Select the parameter level.
- \* Open the parameter level.
- ⌂ Select the parameter.
- \* Activate editing mode for function block.  
Reading:  $\blacktriangleleft$  blinks.
- ⌂ Change parameter.
- \* Confirm parameter.  
To configure further function blocks in the opened configuration level, repeat the steps "Select the parameter." onwards.

⌂ Select **End**.

\* Exit the parameter level.

To configure further function blocks in other configuration levels, repeat steps highlighted in gray.

Turn the rotary switch to  $\square$  (operating level).

---

#### **i** Note

*All parameter settings are saved in a non-volatile memory in the heating controller.*

---

### 7.4 Calibrating sensors

Temperature sensors are used to measure various temperatures. These sensors are connected to the heating controller. The heating controller is designed for connection of Pt1000, PTC and Ni1000 sensors.

- CO5 → F01 - 1, F02 - 0: Pt 1000
- CO5 → F01 - 0, F02 - 0: PTC
- CO5 → F01 - 1, F02 - 1: Ni 1000

⇒ See Chapter 3.5 for sensor resistance tables.

If the temperature values displayed at the heating controller differ from the actual temperatures, the measured values of all connected sensors can be recalibrated. To calibrate a sensor, the currently displayed value must be changed to match the temperature (reference temperature) measured directly at the point of measurement.

⇒ Activate calibration in CO5 with F20.

⇒ Delete the incorrectly performed calibration with F20 - 0.

#### Procedure











Set the rotary switch to  $\diamond$  (parameter and configuration level).


Reading: **0 0 0 0**

◊ Enter valid key number.

\* Confirm key number.

Reading: **PA\_**

- ⌚ Select CO5 configuration level.
- \* Open CO5 configuration level.
- ⌚ Select function block F20.
- \* Activate editing mode for function block F20.
- ⌚ Select sensor symbol.
  -  Room sensor RF, heating circuit 1 and 2
  -  Outdoor sensor AF1
  -  Flow sensor VF, heating circuit 1 and 2
  -  Flow sensor VF1, primary heat exchanger circuit
  -  Flow sensor VF2 and VF4, DHW circuit
  -  Solar collector sensor VF3
  -  Return sensor RüF
  -  Storage tank sensor SF1
  -  Storage tank sensor SF2
  -  Storage tank sensor of solar circuit SF2

- \* Display measured value.  
Reading: °C blinks.
  - ⌚ Correct measured value.  
Read the actual temperature directly from the thermometer at the point of measurement and enter this value as the reference temperature.
  - \* Confirm corrected measured value.
  - ⌚ Select **End**.
- Turn the rotary switch to  (operating level).


## 7.5 Entering customized key number

To prevent the function and parameter settings being changed by unauthorized users, a customized key number can be added to the fixed service key number. You can select a customized key number between 0100 and 1900.

### Procedure

Set the rotary switch to  (parameter and configuration level).

Reading: **0 0 0 0**

- ⌚ Enter key number 1995.
  - \* Confirm key number.
  - ⌚ Enter valid key number.
  - \* Confirm key number.
  - ⌚ Enter customized key number.
  - \* Confirm customized key number.  
This number is the new valid key number.
- Turn the rotary switch to  (operating level).

# 8 Operation

## 8.1 Selecting the operating mode

The heating controller can be operated in the following modes:

### Day mode (rated operation):

Regardless of the programmed times-of-use and summer mode, the set points relevant to rated operation are used by the controller.

Icon: 

### Night mode (reduced operation):

Regardless of the programmed times-of-use, the set points relevant to reduced operation are used by the controller.



### Control operation deactivated:

Regardless of the programmed times-of-use, control operation of the heating circuits and DHW heating remains deactivated. The frost protection is activated, if need be.

Icon: 

### Automatic mode:

During the programmed times-of-use, the controller works in day mode (rated operation). Outside these times-of-use, the controller is in night mode (reduced operation), provided control operation has not been deactivated due to the outdoor temperature. The heating controller switches automatically between both operating modes.

Icon: 


### Manual mode:

Valves and pumps can be controlled manually (see Chapter 8.6 for further details).

Icon: 

The heating controller is usually in the automatic mode.

Turn the rotary switch to  (operating modes). See Chapter "Operation".

Reading:  blinks.

In systems with only one control circuit (e.g. system 1.0), steps "Select the control circuit." and "Confirm the selected control circuit." are not required.





- ⌚ Select the control circuit.

Select the control circuit for which the operating mode is to be set.


1. Heating circuit 1
2. Heating circuit 2
3. DHW heating/circulation pump

Only the control circuits that can be controlled by the selected system are available for selection.




- \* Confirm the selected control circuit.

- ⌚ Select operating mode: , ,  or 

- \* Confirm the selected operating mode.

Turn the rotary switch to  (operating level).

**i Note**

*In automatic operation, the current phase of the time program ( for day mode or  for night mode) is displayed in the operating level together with the  icon.*

## Operation

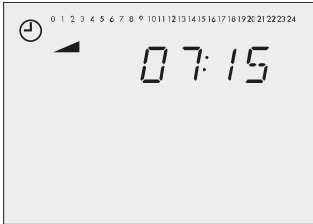
### 8.2 Schedules

The controller operates according to the programmed schedules in automatic mode.

#### 8.2.1 Setting the time and date

The current time and date need to be set immediately after start-up and after a power failure lasting more than 24 hours. This is the case when the time blinks on the display.

##### Procedure



Turn the rotary switch to (time/date).

Reading: Time, and blink.

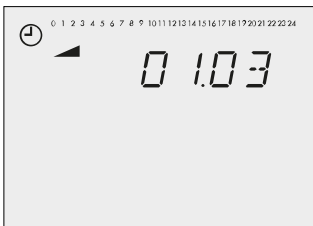
Change the time.



\* Confirm the time setting.

Reading: Year

Change the year.



\* Confirm the year setting.

Reading: Date (day.month)

Change date.

\* Confirm the date setting.

Reading: Time

Turn the rotary switch to (operating level).

##### Note

The correct time remains displayed after a power failure of 24 hours. Normally, the time is still correct at least 48 hours after a power failure.

#### 8.2.2 Setting the times-of-use

Three times-of-use can be programmed for each day of the week.

Parameters	Default <sup>1)</sup>	Value range
Period/day	1-7	1-7, 1, 2, 3, 4, 5, 6, 7 with 1-7 daily
Start first time-of-use	06:00	1 = Monday, 2 = Tuesday, ..., 7 = Sunday
Stop first time-of-use	22:00	00:00 to 24:00 h (in steps of 15 minutes)
Start second time-of-use	22:15	00:00 to 24:00 h (in steps of 15 minutes)
Stop second time-of-use	22:15	00:00 to 24:00 h (in steps of 15 minutes)
Start third time-of-use	--:--	00:00 to 24:00 h (in steps of 15 minutes)
Stop third time-of-use	--:--	00:00 to 24:00 h (in steps of 15 minutes)

<sup>1)</sup> Default settings only applicable to the heating circuits

## Procedure

Set the rotary switch to ☉ (times-of-use).

Reading: ◀ blinks.

In systems with only one control circuit (e.g. system 1.0), steps "Select the control circuit." and "Confirm the selected control circuit." are not required.

- ☺ Select the control circuit.

Select the control circuit for which the operating mode is to be set.

1. Heating circuit 1
2. Heating circuit 2
3. DHW heating/circulation pump

Only the control circuits that can be controlled by the selected system are available for selection.

- \* Confirm the selected control circuit.

- ☺ Configure DHW circuit.

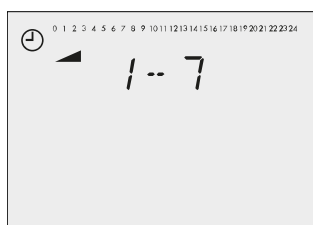


DHW heating



Circulation pump  
(DHW)

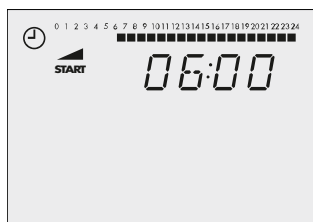
- \* Confirm setting.



- ☺ Select period/day for which the times-of-use are to be valid.

1-7 = daily

1 = Monday, 2 = Tuesday, ..., 7 = Sunday

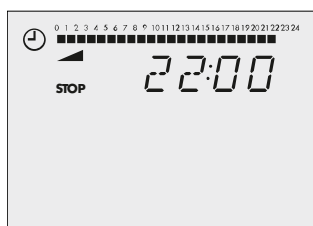


- \* Activate editing mode for the period/day.

Reading: **START**, ☉ and ◀ blink.

- ☺ Change start time.

The time is set in steps of 15 minutes.



- \* Confirm start time setting.

Reading: **STOP**

- ☺ Change stop time.

The time is set in steps of 15 minutes.

- \* Confirm stop time setting.

Reading: **START**

The displayed time is the stop time of the first time-of-use period plus 15 minutes.

⇒ To set the second and third times-of-use periods, repeat steps "Change start time." onwards.

⇒ If no further times-of-use are to be programmed for the selected time period/day, exit the menu by confirming the indicated start time twice (2x \*).

⇒ To program the times-of-use for every day separately, repeat steps highlighted in gray.

After programming all vacation periods, Turn the rotary switch to ☼ (operating level).

### **NOTICE**

#### **Programmed times-of-use can be accidentally overwritten.**

Do not use the 1-7 menu to check the programmed times-of-use. If this menu is opened after the times-of-use have been programmed, the schedule programmed for Monday is also adopted for all other days of the week.


### 8.2.3 Setting the party timer (special time-of-use)

Using the **Party mode** function, the controller continues or activates the rated operation of the controller during the time when the party timer is active, regardless of the programmed times-of-use. After the party timer has counted down, the party time function is reset to 00:00

Parameters	Default	Value range
Continue or activate rated operation	0 h	0 to 48 h

#### **Procedure**

Set the rotary switch to  (party mode).

Reading:  blinks.

In the systems 1.0, 1.9 and 3.5, 00:00 or the remaining time of the party time are displayed. The following steps "Select the control circuit." and "Confirm the selected control circuit." are not required.

- ⌚ Select the control circuit.

Select the control circuit for which the operating mode is to be set.

1. Heating circuit 1
2. Heating circuit 2
3. DHW heating/circulation pump


Only the control circuits that can be controlled by the selected system are available for selection.

- \* Confirm the selected control circuit.

Reading: **00:00** or the remaining time of the party time

- ⌚ Extend day mode as required.

The time is set in steps of 15 minutes.

Turn the rotary switch to  (operating level).

### **Note**

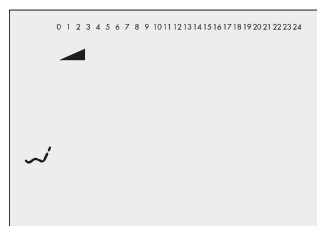
The party timer runs down in steps of 15 minutes.





## 8.2.4 Programming public holidays (special times-of-use)

On public holidays, the times-of-use specified for Sunday apply. A maximum of 20 public holidays can be entered.

Parameters	Default	Level: value range
Public holidays	-	Extended operating level: 01.01 to 31.12

### Procedure



- ⌚ In the extended operating level (normal switch position ) select 'Public holidays'.
- Reading: 
- \* Open 'Public holidays'.
- ⌚ If applicable, select - .- -
- \* Activate the editing mode for public holidays.  
Reading:  and  blink.
- ⌚ Select public holiday.
- \* Confirm the public holiday setting.

⇒ To enter additional public holidays, select - .- - again and repeat the steps highlighted in gray.

### **i** Note

Public holidays can also be entered in PA5 parameter level (see Chapter 7).

### Deleting a public holiday

- ⌚ In the 'Public holidays' menu, select the holiday you wish to delete.
  - \* Confirm.
  - ⌚ Select - .- -.
  - \* Confirm.
- The public holiday is deleted.

### **i** Note

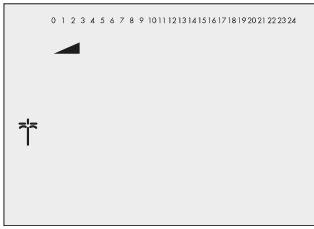
SAMSON recommends deleting public holidays that are not assigned to a specific date by the end of the year. Otherwise, the public holidays are automatically carried over to the next year.


## 8.2.5 Programming vacation periods (special times-of-use)

On public holidays, the times-of-use specified for Sunday apply. A maximum of 20 public holidays can be entered.

Parameters	Default	Level: value range
Vacation period (START, STOP)	-	Extended operating level: 01.01 to 31.12

## Procedure



⌚ In the extended operating level (normal switch position ) select 'Vacations'.

Reading: †

\* Open 'Vacations'.

Reading: **START**

⌚ If applicable, select -.-.-.

\* Activate the editing mode for vacations.

Reading: † and ◀ blink.

⌚ Set the start date of the vacation.

\* Confirm the start date setting.

Reading: **STOP**

⌚ Set the end date of the vacation.

\* Confirm the end date setting.

Black squares at the top of the display indicate the assignment of the vacation periods to the individual control circuits.

⌚ Select the control circuit to which the current vacation period is to apply.

1 ■ Current vacation period applies to heating circuit 1

2 ■ Current vacation period applies to heating circuit 2

3 ■ -

4 ■ Current vacation period applies to DHW circuit

The vacation period can be assigned to a single control circuit or any combination of all three control circuit (RK1, RK2, DHW circuit).

⇒ To enter additional public holidays, select -.-.- again and repeat the steps highlighted in gray.

### **i Note**

Vacations can also be entered in PA5 parameter level (see Chapter 7).

## Deleting vacations

⌚ In the 'Vacations' menu, select the start date of the vacation period you wish to delete.

\* Confirm.

⌚ Select -.-.-.

\* Confirm.

The public holiday is deleted.

### **i Note**

SAMSON recommends deleting vacation periods by the end of the year. Otherwise, the vacation periods are automatically carried over to the next year.

### 8.3 Entering day and night set points

For the heating circuits, the desired room temperatures during the day ('Day set point') and during the night ('Night set point') can be entered into the controller. In the DHW circuit, the temperature you wish the DHW to be heated to can be set.

#### Switch position ↕\*

Parameters	Default	Value range
Day set point RK1, RK2	20 °C	-5.0 to +150.0 °C
DHW temperature set point	60 °C	Min. to max. DHW temperature

#### Switch position ↕⌚

Parameters	Default	Value range
Night set point RK1, RK2	15 °C	-5.0 to +150.0 °C
DHW temperature set point	40 °C	Min. to max. DHW temperature

Set the rotary switch to the required position.

- ↕\* Day set point and DHW temperature set point
- ↕⌚ Night set point and DHW temperature sustaining value

Reading: ◀ blinks.

In systems 1.0, 1.9 and 3.5, the current set point is directly displayed. As a result, steps "Select the control circuit." and "Confirm the selected control circuit." (to select the control circuit) are not required.

- ⌚ Select the control circuit.  
Select the control circuit for which the operating mode is to be set.
  1. Heating circuit 1
  2. Heating circuit 2
  3. DHW heating/circulation pump

Only the control circuits that can be controlled by the selected system are available for selection.

- \* Confirm the selected control circuit.  
Reading: Current set point
- ⌚ Adjust the set point.

Turn the rotary switch to ☐ (operating level).

### 8.4 Reset to default settings


All parameters configured using the rotary switch as well as parameters in the PA1, PA2 and PA5 parameter levels can be reset to their default settings. This does not apply to the maximum flow temperature and the return temperature limits in PA1 and PA2.

Set the rotary switch to ⬠ (parameter and configuration level).

Reading: **0 0 0 0**


- ⌚ Enter key number 1991.
- \* Confirm key number.  
The controller loads the default settings.  
Reading: **0 0 0 0**

### 8.5 Information readings

In the normal switch position  (operating level), the time, date, public holidays and vacation periods as well as the temperatures of connected sensors and their set points can be displayed.

---

**i Note**

The data can also be read in the operating level  (manual mode). In this case, select and confirm InFo on the display and proceed as described below.











---

**Procedure**

- ⌚ Select value.

Depending on how the controller is configured, the current values of the following data points appear one after the other on the display:

- ⌚ Select CO5 configuration level.
- \* Open CO5 configuration level.
- ⌚ Select function block F20.
- \* Activate editing mode for function block F20.
- ⌚ Select sensor symbol.

	Time
	Room temperature of heating circuit 1 and 2
	Outdoor temperature
	Temperature at flow sensor VF, heating circuit 1 and 2
	Temperature at flow sensor VF1, primary heat exchanger circuit
	Temperature at flow sensor VF2 and VF4, DHW circuit
	Temperature at return sensor RÜF
	Temperature at storage tank sensor SF1
	Temperature at storage tank sensor SF2
	Temperature at storage tank sensor SF2 of solar circuit

- \* The associated set point/limit is displayed.  
The date is displayed when the time reading appears.

## 8.6 Operating the heating controller in manual mode

All of the outputs for the heating controller are performed in manual mode.

---

### **NOTICE**


#### **System damage caused by frost in manual mode.**

*The frost protection function is deactivated in the manual mode.*

⇒ *Do not run the heating during cold weather in the manual mode for long periods of time.*

---

### **Procedure**

Set the rotary switch to  (manual level).

- ⌚ Select output depending on the control circuit.

POS\_ Correction value adjusted in percent

UP\_ Switching of the circulation pump (heating)

SLP Switching of the storage tank charging pump

TLP Switching of the heat exchanger charging pump

CP Switching of the solar circuit pump

ZP Switching of the circulation pump (DHW)


- \* Confirm the output.

The reading blinks.

- ⌚ Change the positioning value/switching state.

- \* Confirm change.


The modified values remain active as long as the controller is in manual mode.

Turn the rotary switch to  (operating level).

The manual mode is deactivated.


---

### **Note**

*The outputs of the controller are not affected by merely turning the rotary switch to  (manual level). The outputs are only changed by entering or changing the positioning values or switching states.*

---

### 9 Malfunctions

A malfunction is indicated by the blinking  icon on the display. Additionally, the display is illuminated for one second every 10 seconds.

The 'Error' message appears on the display. Press the rotary pushbutton to open the error level. Turn the rotary knob to read the error(s). As long as an operational malfunction exists, the error message is included in the reading loop, even when it has not been opened by pressing the rotary pushbutton.

The error message is displayed in the error level as specified in the following list (see Chapter 9.1).

---

#### **DANGER**

**Risk of fatal injury due to electric shock while performing electrical connection.**

*For wiring and connecting the heating controller, observe the relevant electrotechnical regulations of the country of use as well as the technical connection requirements of the grid operator in charge.*

⇒ *Only allow properly trained and experienced personnel perform the electrical connection.*

---

#### **NOTICE**

**Risk of damage to the heating controller due to incorrectly performed work.**

⇒ *Only properly trained personnel appropriately qualified to carry out such tasks must be allowed to perform corrective action.*

---

#### **Note**

*After the system code number has been changed or after restarting the heating controller, any error messages are suppressed for approx. three minutes.*

---

### 9.1 Error list

Err 1	=	Sensor failure (see Chapter 9.2)
Err 2	=	Reserved
Err 3	=	Disinfection temperature not reached (see Chapter 16.3.10)
Err 4	=	Max. charging temperature reached (see Chapter 16.3.2)
Err 6	=	Temperature monitor alarm (see Chapter 9.3)
Err 7	=	Unauthorized access occurred (see Chapter 9.4)
Err 8	=	Error message of a binary input

All error messages, except for Err 1 can be confirmed in the error level.

#### **Confirming error messages**

- ⌂ Select **Clr** on the display.
- \* Confirm error message.

## 9.2 Sensor failure

As described in the error list, sensor failures are indicated by displaying 'Err 1' error message in the error level. For detailed information, exit the error level and view the different temperature values in the operating level:

Each sensor icon displayed together with three dashes instead of the measured value indicates a defective sensor. The following list explains how the heating controller responds to the failure of the different sensors.

- **Outdoor sensor AF1:**

In the event that the outdoor sensor fails, the controller uses a flow temperature set point of 50 °C or the 'Max. flow temperature' (set in PA1, 2) if the 'Max. flow temperature' is lower than 50 °C. With the setting CO1, 2 → F05 - 1 (under-floor heating), the flow temperature set point is 30 °C in the event of a malfunction.

- **Flow sensor(s) in heating circuit(s):**

In the event that the flow sensors in the heating circuits fail, the associated valve moves to 30 % travel. DHW heating which use such a sensor to measure the charging temperature is suspended.

- **Flow sensors in the DHW circuit with control valve:**

In the event that the flow sensor VF4 fails, the controller behaves as if VF4 has not been configured. As soon as the control of the charging temperature/DHW temperature becomes impossible (VF2 failed), the associated valve is closed.

- **Return sensor RüF1/RüF2:**

In the event that the return sensor fails, the controller continues operation without return temperature limitation.

- **Room sensor RF1/RF2**

In the event that the room sensor fails, the heating controller uses the settings for operation without room sensor. For example, the controller switches from optimizing mode to night mode. The adaptation mode is canceled. The last determined heating characteristic remains unchanged.

- **Storage tank sensors SF1/SF2:**

In the event that one of the two sensors fails, the storage tank is no longer charged (exception: solar system).

- **Solar circuit sensors SF, VF/RüF:**

In the event that one of the two sensors fails, the storage tank is no longer charged by the solar system.

### 9.3 Temperature monitoring

When a system deviation greater than 10 °C persists in a control circuit for 30 minutes, the 'Err 6' error message is generated.

Function	Default	Configuration
Monitoring	0	CO5 → F19 - 1

### 9.4 Error status register

Error message	Meaning	Decimal value	
Err 1	Sensor failure	1	1
Err 2	-	2	
Err 3	Disinfection temperature not reached	4	
Err 4	Max. charging temperature reached	8	
Err 5	-	16	
Err 6	Temperature monitor alarm	32	32
Err 7	Unauthorized access occurred	64	
Err 8	Error message of a binary input	128	
Err 9	-	256	
			Total
Example: Value of error status register when a sensor fails and a temperature monitoring alarm =			33

## 10 Servicing

The work described in this chapter is to be performed only by personnel appropriately qualified to carry out such tasks.

### 10.1 Recommended inspection and testing

SAMSON recommends inspection and testing according to the following table:

**Table 5:** *Recommended inspection and testing*

Inspection and testing	Action to be taken in the event of a negative result
Check the markings, labels and nameplates on the device for their readability and completeness.	⇒ Immediately renew damaged, missing or incorrect nameplates or labels.
	⇒ Clean any inscriptions that are covered with dirt and are illegible.
Check the electric wiring.	⇒ Tighten any loose terminal screws (see Chapter 5). ⇒ Renew damaged wires.
Check whether the firmware is up to date.	⇒ Download the currently valid firmware at ▶ <a href="http://www.samsongroup.com">www.samsongroup.com</a> > DOWNLOADS > Software & Drivers > Firmware and install it (see Chapter 10.2).
Compare the temperature values displayed at the heating controller with the actual temperatures at the point of measurement.	⇒ If the displayed and actual temperatures differ, calibrate the sensors (see Chapter 7).

#### Tip

The SAMSON NE53 newsletter keeps users up to date on any software or hardware revisions in accordance with NAMUR Recommendation NE 53. Subscribe to the NE53 newsletter at ▶ [www.samsongroup.com](http://www.samsongroup.com) > SERVICE > NE53 newsletter.

## 10.2 Firmware update

### 10.2.1 Update over RS-232 interface

#### Requirements

- Computer with Microsoft Windows® operating system
- USB/RS-232 adapter (order no. 8812-2001)
- RS-232 to computer communication module (order no. 8812-2003)

#### Procedure

1. Download the latest version of the tool to install firmware update files (boot manager) and the currently valid firmware file at ▶ [www.samsongroup.com](http://www.samsongroup.com) > DOWNLOADS > Software & Drivers > Firmware.
2. Connect the USB/RS-232 adapter to the USB port of the computer.
3. Connect the RS-232 to computer communication module to the USB/RS-232 adapter.
4. Connect the communication module using the supplied RJ45 patch cable to the controller (port at the side).

### **i Note**

The COM port assigned for the USB/RS-232 adapter must only have one digit. If a two-digit number has been assigned to the COM port, change it in the Device Manager in USB Serial Port > Properties > Port settings > Advanced... before starting the boot manager.

5. Start the boot manager and click **Wählen** (select) to select and load the firmware file.
6. Select 'COM-Port' in the **Verbindung** (connection) field.
7. Click **Erweitert** (advanced) button and enter the COM port assigned to the USB/RS-232 adapter.
8. Change the Baud rate to '19200' if it is not set by default.
9. Do not change any other settings. Click **Updaten** (update) button.

The software tool searches for the controller.

⇒ Disconnect the controller from the supply voltage and wait around five seconds before restarting it.

The update runs fully automatically.

During the update, **r S232** appears on the controller display. It takes around two minutes for the green progress bar in the boot manager to reach 100 %.

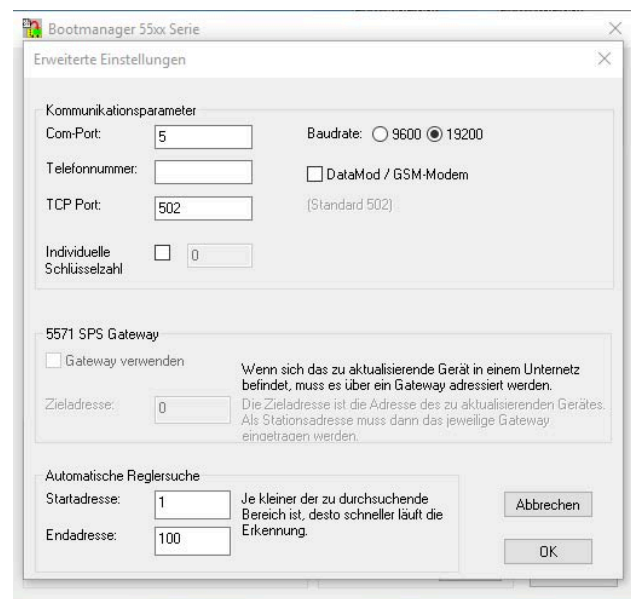
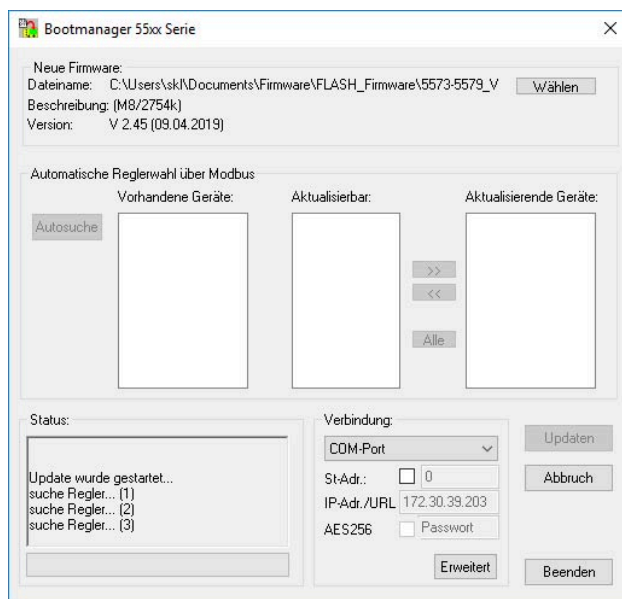
The message **Update wurde erfolgreich durchgeführt** (update completed) appears. The controller restarts.

⇒ If the update could not be completed properly (e.g. because the connection was interrupted during the update), click **Abbruch** (cancel) button and click **Updaten** (update) button to restart the procedure.

⇒ Contact SAMSON's After-Sales Service if the firmware update cannot be completed successfully.

For this purpose, submit the following information:

- Any error messages that appear
- All the data settings performed according to these instructions
- All the data settings made in the boot manager



## 10.2.2 Update over RS-485 bus

### Requirements

- Host computer
  - Firmware file
1. Download the latest version of the tool to install firmware update files (boot manager) and the currently valid firmware file at ► [www.samsongroup.com](http://www.samsongroup.com) > DOWNLOADS > Software & Drivers > Firmware.
  2. Install the boot manager tool on the host computer.
  3. Exit the active Modbus application running on the host computer.
  4. Start the boot manager and click **Wählen** (select) to select and load the firmware file.
  5. Select 'COM-Port' in the **Verbindung** (connection) field.
  6. In **Erweitert** (advanced), enter the same COM port and Baud rate as used in the Modbus RTU application.
  7. Check **St-Adr.** check box and enter the Modbus station address of the controller that is to be updated in the input field next to the box (Modbus station address = first parameter in **PA6**).
  8. Do not change any other settings. Click **Updaten** (update) button.

The update runs fully automatically. It takes around three minutes for the green progress bar in the boot manager to reach 100 %.

The message **Update wurde erfolgreich durchgeführt** (update completed) appears. The controller restarts.

- ⇒ If an update could not be completed properly (e.g. because the connection was interrupted during the update), click **Abbruch** (cancel) button, uncheck the 'Stationadressen-Modus' (station address mode) box and click **Updaten** (update) button to restart the procedure.

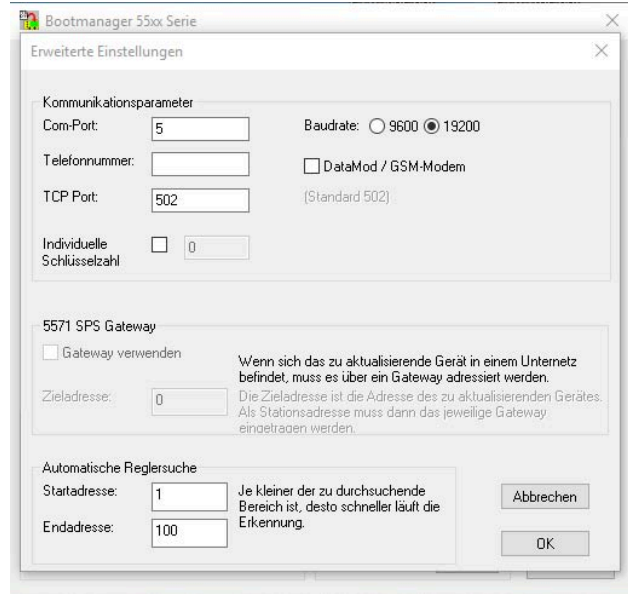
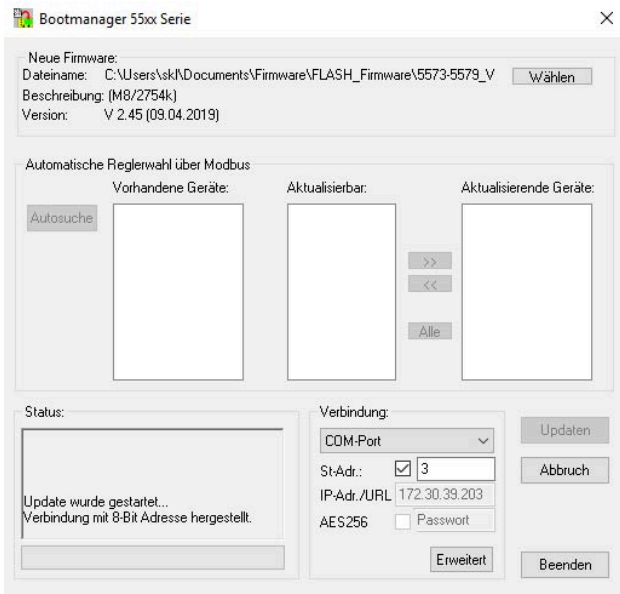
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### **i** Note

*It is not possible to restart the update process if another controller is connected to the RS-485 bus, which is in the boot mode after a failed update.*

---

- ⇒ Contact SAMSON's After-Sales Service if the firmware update cannot be completed successfully. For this purpose, submit the following information:
- Any error messages that appear
  - All the data settings performed according to these instructions
  - All the data settings made in the boot manager



### 10.2.3 Update over Ethernet

#### Requirements

- Host computer

#### Procedure

1. Download the latest version of the tool to install firmware update files (boot manager) and the currently valid firmware file at ► [www.samsunggroup.com](http://www.samsunggroup.com) > DOWNLOADS > Software & Drivers > Firmware.
2. Install the boot manager tool on the host computer.
3. Exit the active Modbus TCP application running on the host computer.
4. Start the boot manager and click **Wählen** (select) to select and load the firmware file.
5. Select 'Modbus-TCP-Gateway' in the **Verbindung** (connection) field.
6. If necessary, click **Erweitert** (advanced) button to change the TCP port (default: 502).

#### **i** Note

*The Baud rate does not need to be changed.*

1. Check **St-Adr.** check box and enter the Modbus station address of the controller that is to be updated in the input field next to the box (Modbus station address = first parameter in **PA6**).
2. Do not change any other settings. Click **Updaten** (update) button.

The update runs fully automatically.

It takes around seven minutes for the green progress bar in the boot manager to reach 100 %.

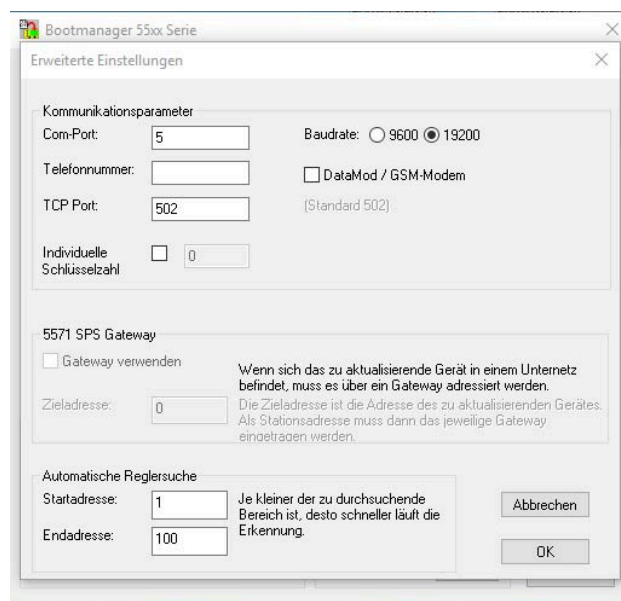
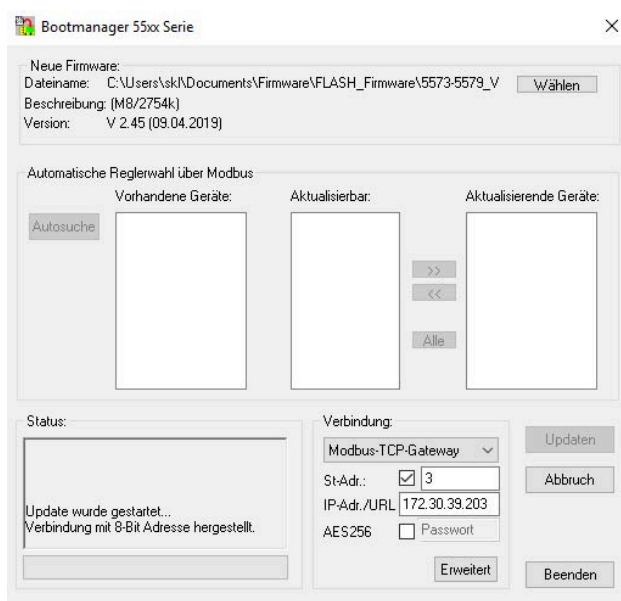
The message **Update wurde erfolgreich durchgeführt** (update completed) appears. The controller restarts.

- ⇒ If an update could not be completed properly (e.g. because the connection was interrupted during the update), click **Abbruch** (cancel) button, uncheck the 'Automatische Reglerwahl über Modbus' (automatic controller selection over Modbus) box and click **Updaten** (update) button to restart the procedure.

**i Note**

*It is not possible to restart the update process, if another controller exists in the network, which is in the boot mode after a failed update.*

- ⇒ Contact SAMSON's After-Sales Service if the firmware update cannot be completed successfully.  
 For this purpose, submit the following information:
- Any error messages that appear
  - All the data settings performed according to these instructions
  - All the data settings made in the boot manager



### 10.2.4 Automatic update for several controllers over RS-485 bus or Ethernet

- Host computer
  - Firmware file
1. Download the latest version of the tool to install firmware update files (boot manager) and the currently valid firmware file at ► [www.samsongroup.com](http://www.samsongroup.com) > DOWNLOADS > Software & Drivers > Firmware.
  2. Install the boot manager tool on the host computer.
  3. Exit the active Modbus application running on the host computer.
  4. Start the boot manager and click **Wählen** (select) to select and load the firmware file.
  5. RS-485 communication: Select 'COM-Port' in the **Verbindung** (connection) field.  
 Ethernet communication: Select 'Modbus-TCP-Gateway' in the **Verbindung** (connection) field.
  6. When 'Modbus-TCP-Gateway' is selected: Enter the IP address or URL of the Modbus TCP gateway or SAM HOME gateway in the 'IP-Adr./URL' field.
  7. When 'COM-Port' is selected: Click **Erweitert** (advanced) button and enter the same COM port and Baud rate as used in the application.  
 When 'Modbus-TCP-Gateway' is selected: Click **Erweitert** (advanced) button and change the TCP port (default: 502), if necessary.

---

### **i Note**

*The Baud rate does not need to be changed when Modbus TCP or a SAM HOME Gateway is used.*

---

### **Automatic controller search**

To optimize the automatic update process of several controllers, the applicable address range can be defined to include the controllers concerned by clicking **Erweitert (advanced) > Automatische Reglersuche** (automatic controller search).

⇒ Click **Autosuche** (auto search) button.

All the devices found by the 'Autosuche' (auto search) are listed under **Vorhandene Geräte** (existing devices). Station address, product number, firmware and hardware versions are shown.

All devices that can be updated are listed under the **Aktualisierbar** (updatable).

⇒ Select the devices to be updated.

- Click **Alle** (all) button.  
All devices that have been found are updated.
- or:**
- Select individual devices.

The selected devices are updated.

After the update is completed, all updated controllers are marked **OK**.

⇒ If an update could not be completed properly (e.g. because the connection was interrupted during the update), click **Abbruch** (cancel) button, uncheck the 'Automatische Reglerwahl über Modbus' (automatic controller selection over Modbus) box and click **Updaten** (update) button to restart the procedure.

---

### **i Note**

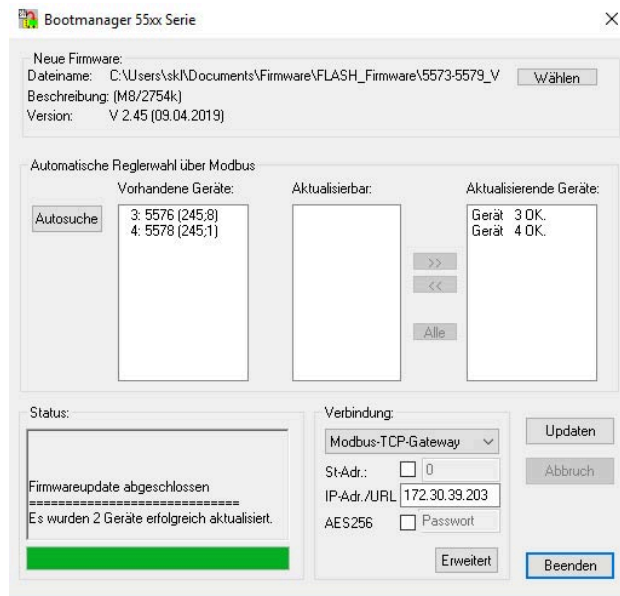
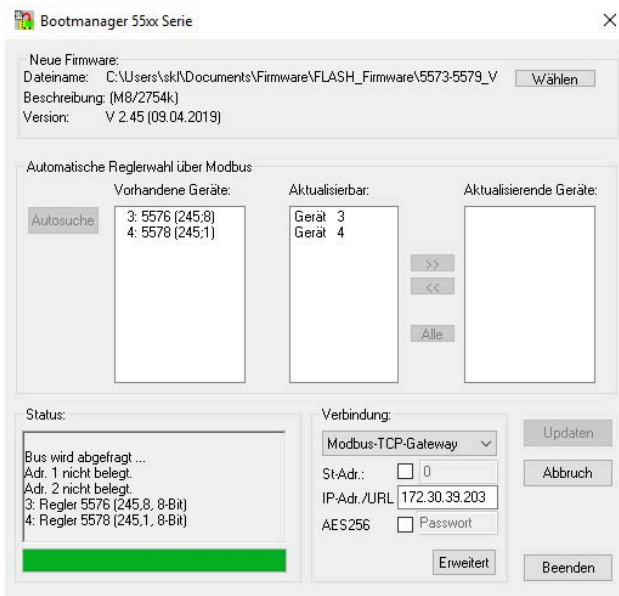
*It is not possible to restart the update process, if another controller exists in the network, which is in the boot mode after a failed update.*

---

⇒ Contact SAMSON's After-Sales Service if the firmware update cannot be completed successfully.

For this purpose, submit the following information:

- Any error messages that appear
- All the data settings performed according to these instructions
- All the data settings made in the boot manager



### 11 Decommissioning

The work described in this chapter is to be performed only by personnel appropriately qualified to carry out such tasks.

---

#### **⚠ DANGER**

##### ***Risk of fatal injury due to electric shock.***

⇒ *Before disconnecting live wires at the heating controller, switch off the supply voltage and protect it against unintentional reconnection.*

---

To put the heating controller out of operation, the heating controller must be disconnected from the voltage supply.

- ⇒ When the heating controller is connected to a control station, log off the heating controller from the control station and disconnect the communication cable.
- ⇒ When the heating controller is connected to TROVIS-VIEW, remove the connecting cable from the RJ-45 port.
- ⇒ Disconnect the supply voltage and protect it against unintentional reconnection.
- ⇒ Open the controller housing. To do so, unscrew the top left and right screws on the front of the controller.
- ⇒ Disconnect the wires from the terminals.
- ⇒ Pull the wires out of the cable ducts.

## 12 Removal

The work described in this chapter is to be performed only by personnel appropriately qualified to carry out such tasks.

### Panel mounting

1. Put the heating controller out of operation (see Chapter 11).
2. Unscrew the top left and bottom right screws to unfasten the controller housing from the panel.

### Wall mounting

1. Put the heating controller out of operation (see Chapter 11).
2. Unscrew the fastening screws and remove the back of the housing from the wall.

### Rail mounting

1. Put the heating controller out of operation (see Chapter 11).
2. Unscrew the top left and bottom right screws to unfasten the controller housing from the top-hat rail.

### 13 Repair

A defective heating controller must be repaired or replaced.

---

**NOTICE**

***Risk of damage to the heating controller due to incorrect service or repair work.***

- ⇒ *Do not perform any repair work on your own.*
- ⇒ *Contact SAMSON's After-sales Service for service and repair work.*

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#### 13.1 Returning devices to SAMSON

Defective heating controllers can be returned to SAMSON for repair. Proceed as follows to return devices to SAMSON:

1. Put the heating controller out of operation (see Chapter 11).
2. Remove the heating controller (see Chapter 12).
3. Proceed as described on the Returning goods page of our website (► [www.samsongroup.com](http://www.samsongroup.com) > SERVICE > After-sales Service > Returning goods).

## 14 Disposal



SAMSON is a producer registered in Europe, agency in charge

► [www.samsongroup.com](http://www.samsongroup.com) > About SAMSON > Environment, Social & Governance > Material Compliance > Waste electrical and electronic equipment (WEEE)  
WEEE reg. no.: DE 62194439

Information on substances listed as substances of very high concern (SVHC) on the candidate list of the REACH regulation can be found in the document "Additional Information on Your Inquiry/Order", which is added to the order documents, if applicable. This document includes the assigned SCIP number, which can be entered into the database on the European Chemicals Agency (ECHA) website to find out more information on the SVHC ► <https://www.echa.europa.eu/scip-database>.

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### **i Note**

*SAMSON can provide you with a recycling passport on request. Simply e-mail us at [aftersaleservice@samsongroup.com](mailto:aftersaleservice@samsongroup.com) giving details of your company address.*

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### **💡 Tip**

*On request, SAMSON can appoint a service provider to dismantle and recycle the product as part of a distributor take-back scheme.*

- ⇒ Observe local, national and international refuse regulations.
- ⇒ Do not dispose of components, lubricants and hazardous substances together with your other household waste.

## Certificates

### 15 Certificates

The following certificate is shown on the next page:

- EU declaration of conformity

The certificate shown was up to date at the time of publishing. The latest certificate can be found on our website at:

▶ [www.samsunggroup.com](http://www.samsunggroup.com) > Products > Automation Systems > 5573



## EU Konformitätserklärung / EU Declaration of Conformity / Déclaration UE de conformité

Die alleinige Verantwortung für die Ausstellung dieser Konformitätserklärung trägt der Hersteller/  
This declaration of conformity is issued under the sole responsibility of the manufacturer/  
La présente déclaration de conformité est établie sous la seule responsabilité du fabricant.  
Für das folgende Produkt / For the following product / Nous certifions que le produit

### Heizungsregler / Heating Controller / Régulateur de chauffage Typ/Type/Type TROVIS 5573

wird die Konformität mit den einschlägigen Harmonisierungsrechtsvorschriften der Union bestätigt /  
the conformity with the relevant Union harmonisation legislation is declared with/  
est conforme à la législation d'harmonisation de l'Union applicable selon les normes:

EMC 2014/30/EU	EN 61000-6-1:2007, EN 61000-6-3:2007 +A1:2011, EN 55022:2010
LVD 2014/35/EU	EN 60730-1:2016, EN 50344:2001
RoHS 2011/65/EU	EN 50581:2012

Hersteller / Manufacturer / Fabricant:

SAMSON AKTIENGESELLSCHAFT  
Weismüllerstraße 3  
D-60314 Frankfurt am Main  
Deutschland/Germany/Allemagne

Frankfurt / Francfort, 2017-07-29

Im Namen des Herstellers/ On behalf of the Manufacturer/ Au nom du fabricant.

Gert Nahler

Zentralabteilungsleiter/Head of Department/Chef du département  
Entwicklung Automation und Integrationstechnologien/  
Development Automation and Integration Technologies

Hanno Zager

Leiter Qualitätssicherung/Head of Quality Management/  
Responsable de l'assurance de la qualité

## 16 Appendix A (configuration instructions)

This Appendix contains information on the configuration of the TROVIS 5573 Heating and District Heating Controller.

### **i Note**

Experimental functions are marked by  $\neq$ . SAMSON has intentionally made them available.

However, the use of such functions may lead to unforeseen malfunctions or failure. Any functions and parameters marked by  $\neq$  are not adopted as standard until SAMSON can rule out malfunctions or failure caused by them. You are welcome to report any errors that you discover to SAMSON's After-sales Service by sending an e-mail to [aftersaleservice@samsongroup.com](mailto:aftersaleservice@samsongroup.com).

### 16.1 Systems

#### Boiler plants

Single-stage boiler systems can be configured to include any system whose heating circuits and DHW circuit include just one heat exchanger.

This applies to the following systems:

1.0, 1.5, 1.6, 2.x, 3.0, 3.5, 4.0, 4.1 and 16.x

The boiler can be controlled by an on/off output (CO1 → F12 - 0).

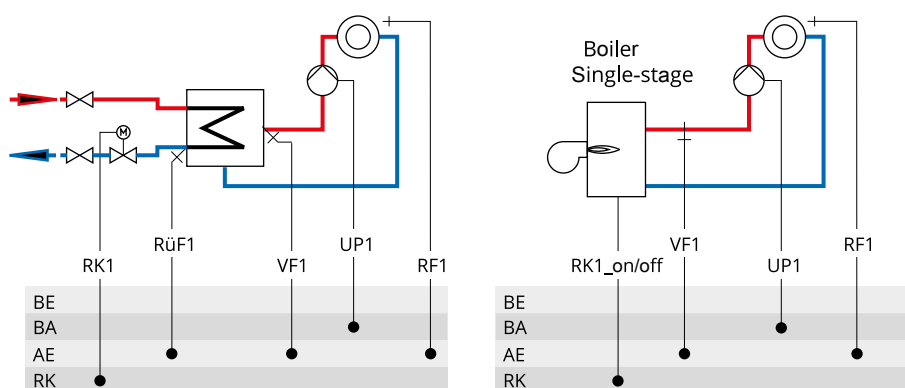


Fig. 9: Configuration of a boiler system

#### Primary and secondary systems

Different hydraulic schematics are available.

The systems can be designed as primary or secondary systems. The main hydraulic differences between the primary and second systems are shown in Fig. 10.

1. A mixing valve replaces the heat exchanger in the heating circuit/DHW circuit.
2. A storage tank charging pump replaces the solenoid valve or thermoelectric valve in the primary system.

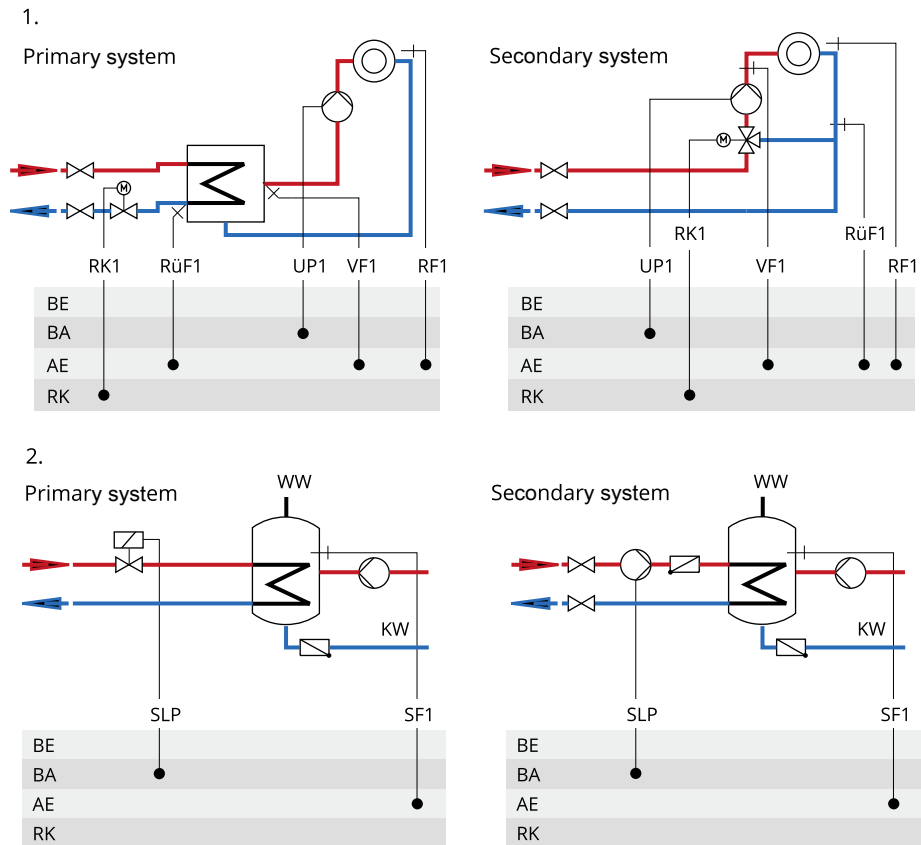
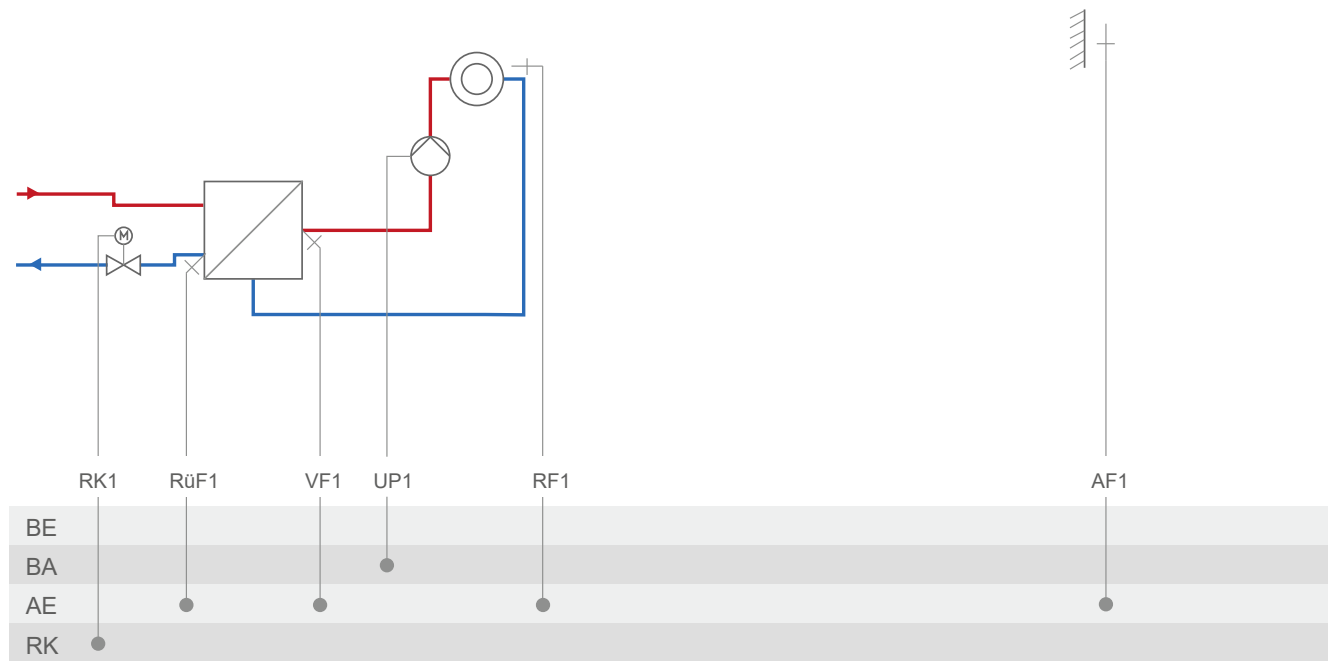


Fig. 10: Differences between primary and second systems

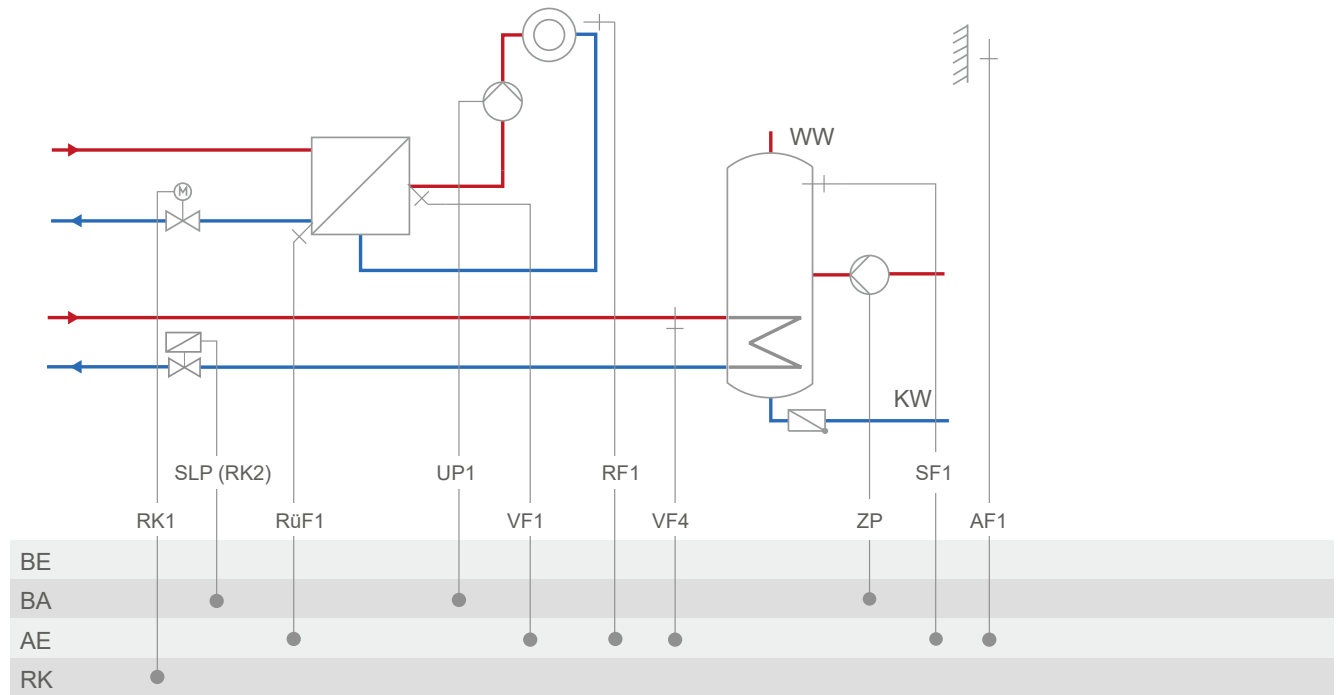
## Appendix A (configuration instructions)

### System 1.0



Default setting	
CO1 → F01	- 0 (without RF1)
CO1 → F02	- 1 (with AF1)
CO1 → F03	- 1 (with RüF1)
CO5' → F10	Function of the 0 to 10 V output: <ul style="list-style-type: none"> <li>- 1 = Control signal RK1</li> <li>- 9 = Differential temperature control      When CO1 → F23 - 1</li> <li>- 6 = External demand                      When CO1 → F18 - 1</li> <li>- 5 = Outdoor temperature                When CO5 → F23 - 1, Direction 'AA'</li> </ul>

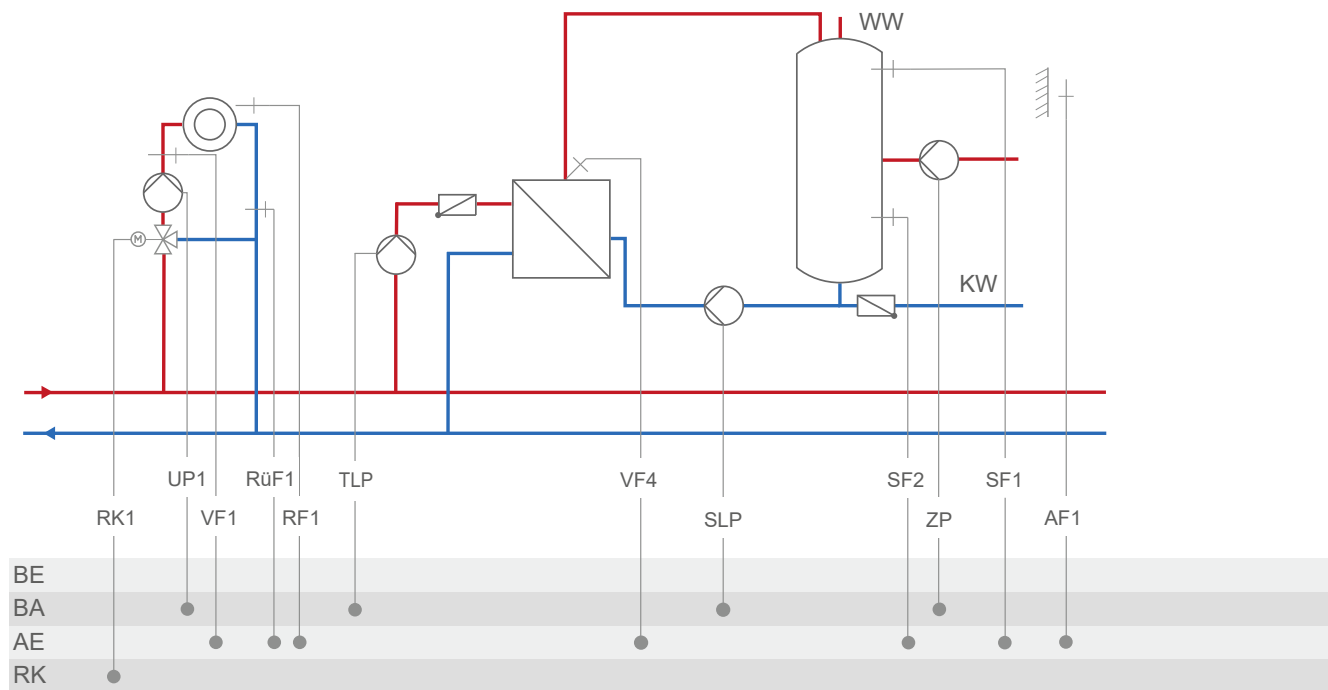
System 1.1



Default setting	
CO1 → F01	- 0 (without RF1)
CO1 → F02	- 1 (with AF1)
CO1 → F03	- 1 (with RüF1)
CO4 → F01	- 1 (with SF1)
CO4 → F02	- 0 (without SF2)
CO4 → F05	- 0 (without VF4)
CO5' → F10	Function of the 0 to 10 V output: - 1 = Control signal RK1 - 6 = External demand - 5 = Outdoor temperature When CO1 → F18 - 1 When CO5 → F23 - 1, Direction 'AA'

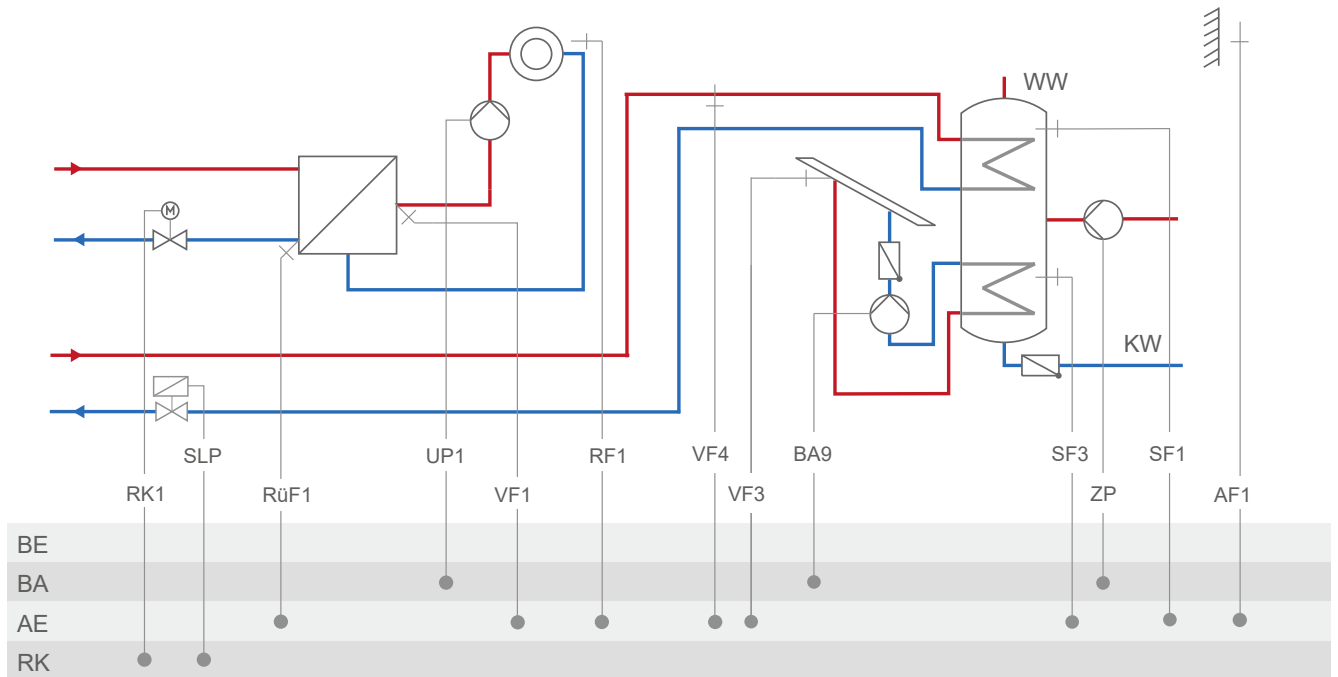
## Appendix A (configuration instructions)

### System 1.2



Default setting	
Note:	Secondary system only
CO1 → F01	- 0 (without RF1)
CO1 → F02	- 1 (with AF1)
CO1 → F03	- 1 (with RüF1)
CO4 → F01	- 1 (with SF1)
CO4 → F02	- 0 (without SF2)
CO4 → F05	- 0 (without VF4)
CO5' → F10	Function of the 0 to 10 V output: <ul style="list-style-type: none"> <li>- 1 = Control signal RK1</li> <li>- 6 = External demand</li> <li>- 7 = SLP speed</li> <li>- 5 = Outdoor temperature</li> </ul> <div style="display: flex; justify-content: space-between; margin-top: 10px;"> <div> <p>When CO1 → F18 - 1</p> <p>When CO4 → F21 - 1</p> <p>When CO5 → F23 - 1</p> <p>Direction 'AA'</p> </div> </div>

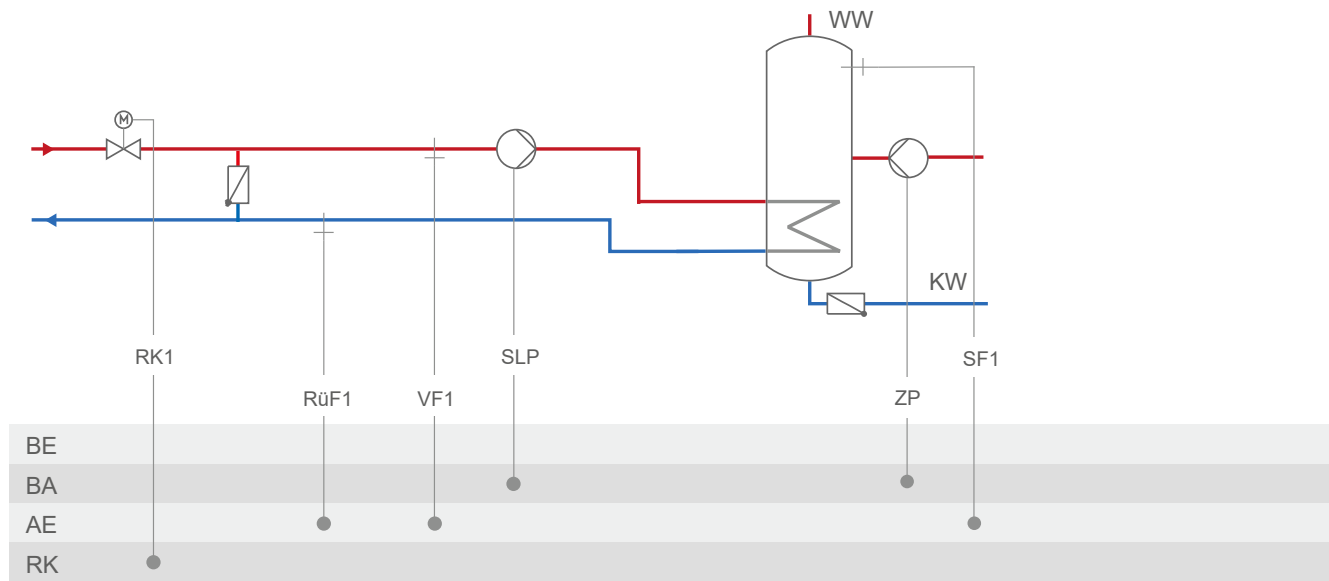
System 1.3



Default setting	
CO1 → F01	- 0 (without RF1)
CO1 → F02	- 1 (with AF1)
CO1 → F03	- 1 (with RüF1)
CO4 → F01	- 1 (with SF1)
CO5' → F10	Function of the 0 to 10 V output: - 1 = Control signal RK1 - 6 = External demand - 7 = SLP speed When CO1 → F18 - 1 When CO5 → F23 - 1 Direction 'AA'

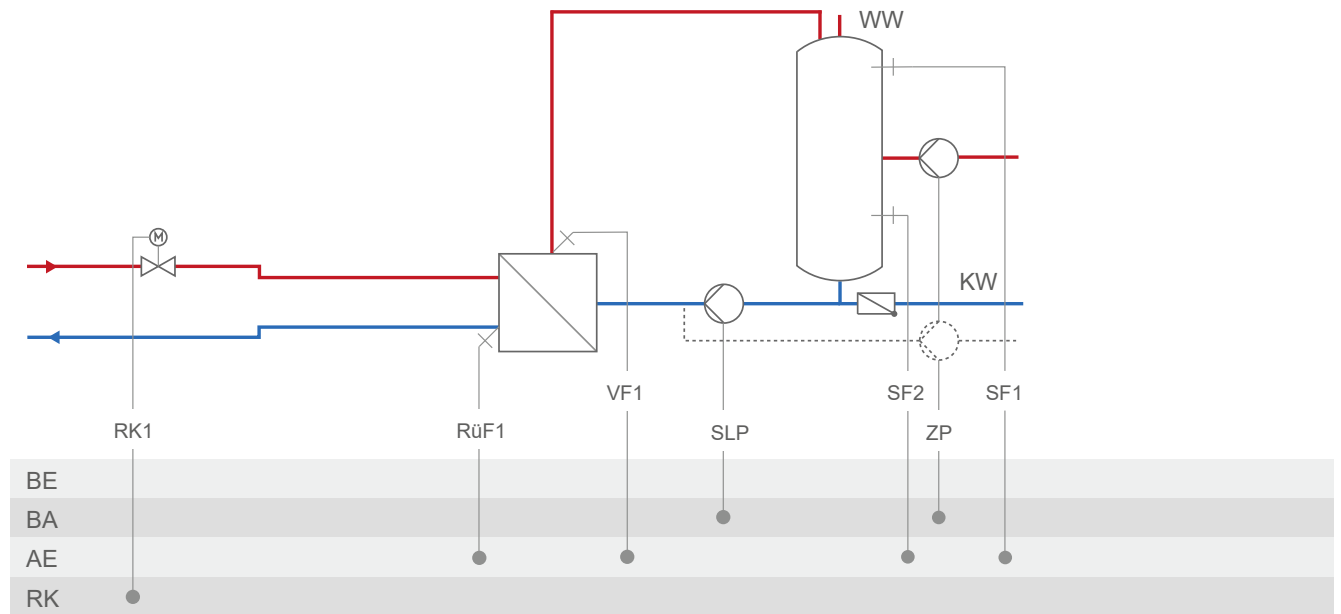
## Appendix A (configuration instructions)

### System 1.5



Default setting	
CO1 → F03	- 1 (with RüF1)
CO4 → F01	- 1 (with SF1)
CO4 → F02	- 0 (without SF2)
CO5' → F10	Function of the 0 to 10 V output: - 1 = Control signal RK1 - 6 = External demand - 7 = SLP speed When CO1 → F18 - 1 When CO4 → F21 - 1

System 1.6 without pre-control

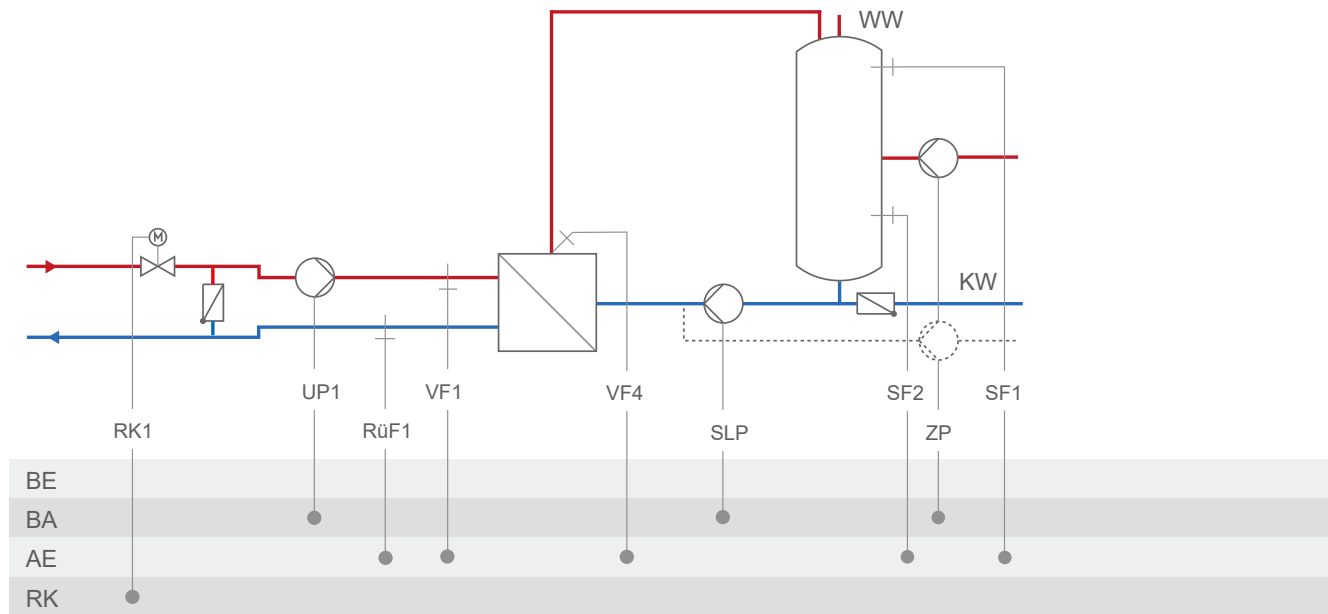


Default setting	
CO1 → F03	- 1 (with RüF1)
CO4 → F01	- 1 (with SF1)
CO4 → F02	- 1 (with SF2)
CO4 → F10	- 0 (DHW circulation return in storage tank)
CO5' → F10	Function of the 0 to 10 V output: - 1 = Control signal RK1 - 6 = External demand - 7 = SLP speed

When CO1 → F18 - 1  
When CO4 → F21 - 1

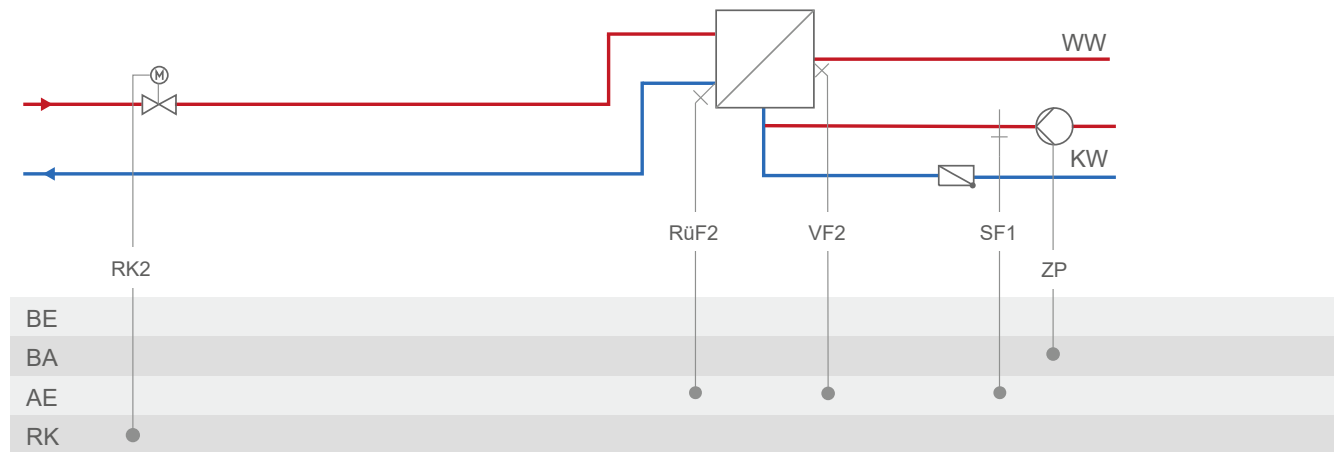
## Appendix A (configuration instructions)

### System 1.6 with pre-control



Default setting	
CO1 → F03	- 1 (with RüF1)
CO4 → F01	- 1 (with SF1)
CO4 → F02	- 1 (with SF2)
CO4 → F05	- 0 (without VF4; in this case, VF1 usually installed at the point of measurement of VF4)
CO4 → F10	- 0 (DHW circulation return in storage tank)
CO5' → F10	Function of the 0 to 10 V output: <ul style="list-style-type: none"> <li>- 1 = Control signal RK1</li> <li>- 6 = External demand</li> <li>- 7 = SLP speed</li> </ul> <div style="text-align: right; margin-top: 5px;">                     When CO1 → F18 - 1                      When CO4 → F21 - 1                 </div>

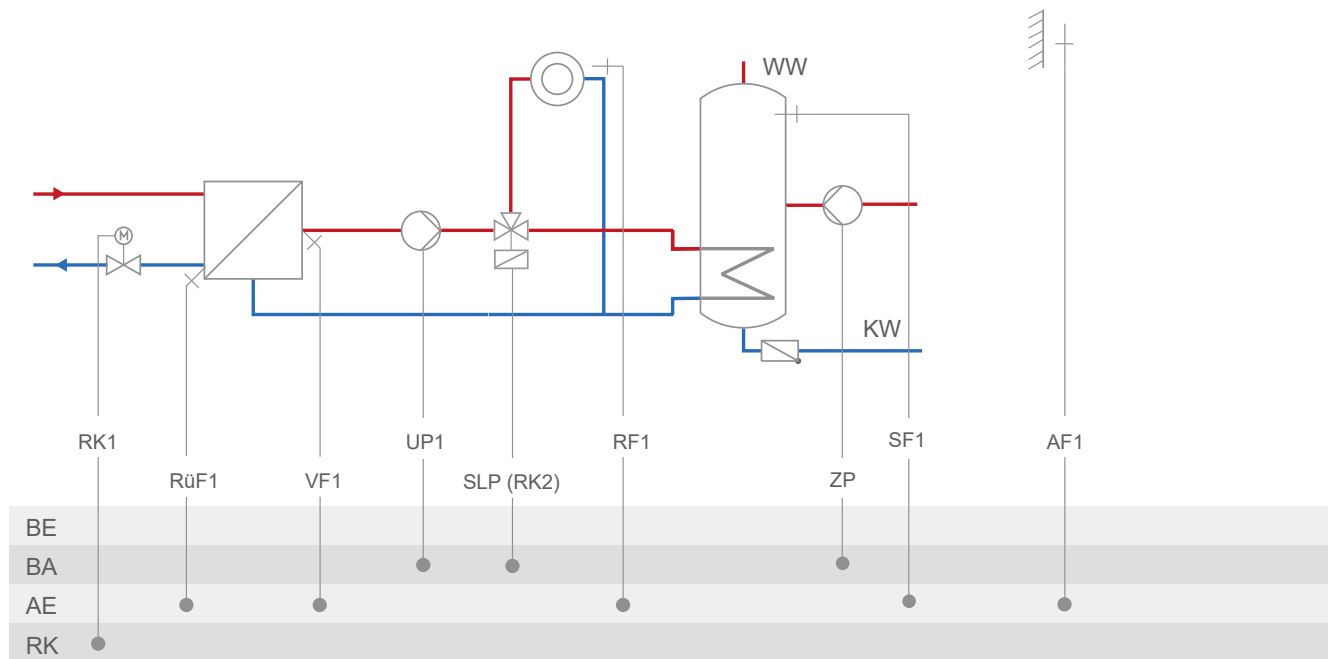
System 1.9



Default setting	
CO4 → F01	- 0 (without SF1)
CO4 → F03	- 0 (without RüF2)
CO5' → F10	Function of the 0 to 10 V output: - 2 = Control signal RK2 - 10 = 10 V supply - 6 = External demand When CO1 → F18 - 1

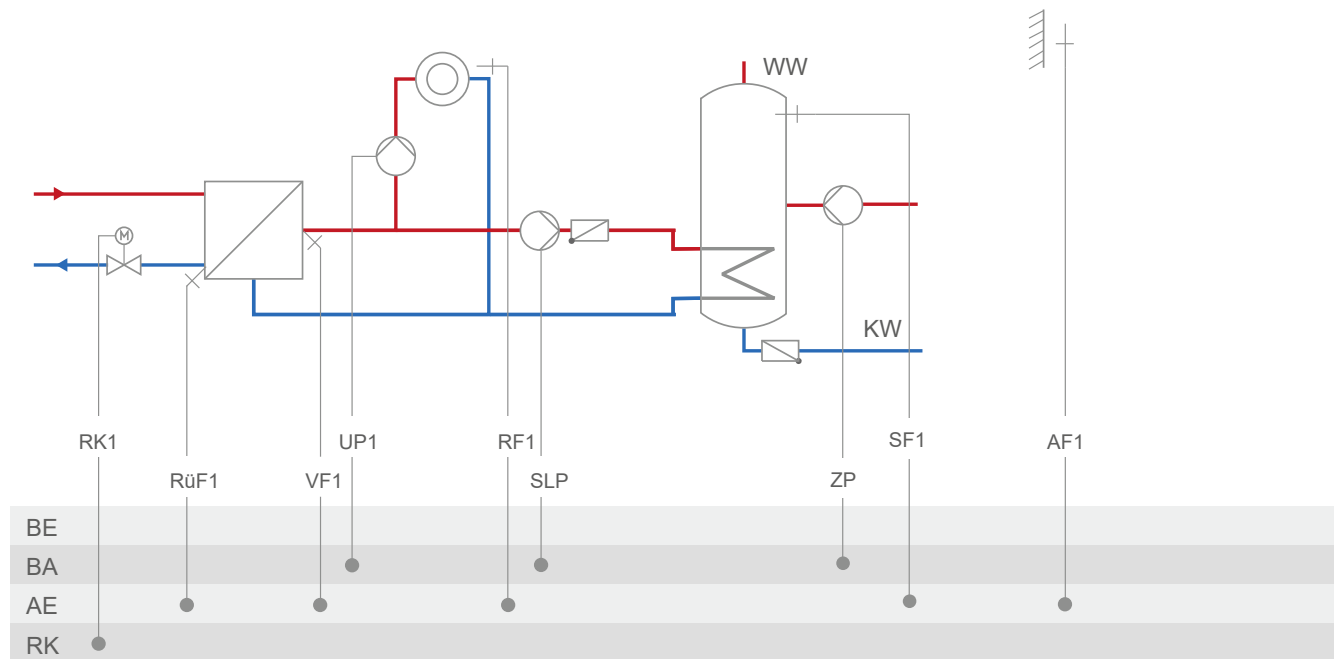
## Appendix A (configuration instructions)

### System 2.0



Default setting	
CO1 → F01	- 0 (without RF1)
CO1 → F02	- 1 (with AF1)
CO1 → F03	- 1 (with RüF1)
CO4 → F01	- 1 (with SF1)
CO4 → F02	- 0 (without SF2)
CO5' → F10	Function of the 0 to 10 V output: - 1 = Control signal RK1 - 6 = External demand - 5 = Outdoor temperature When CO1 → F18 - 1 When CO5 → F23 - 1 Direction 'AA'

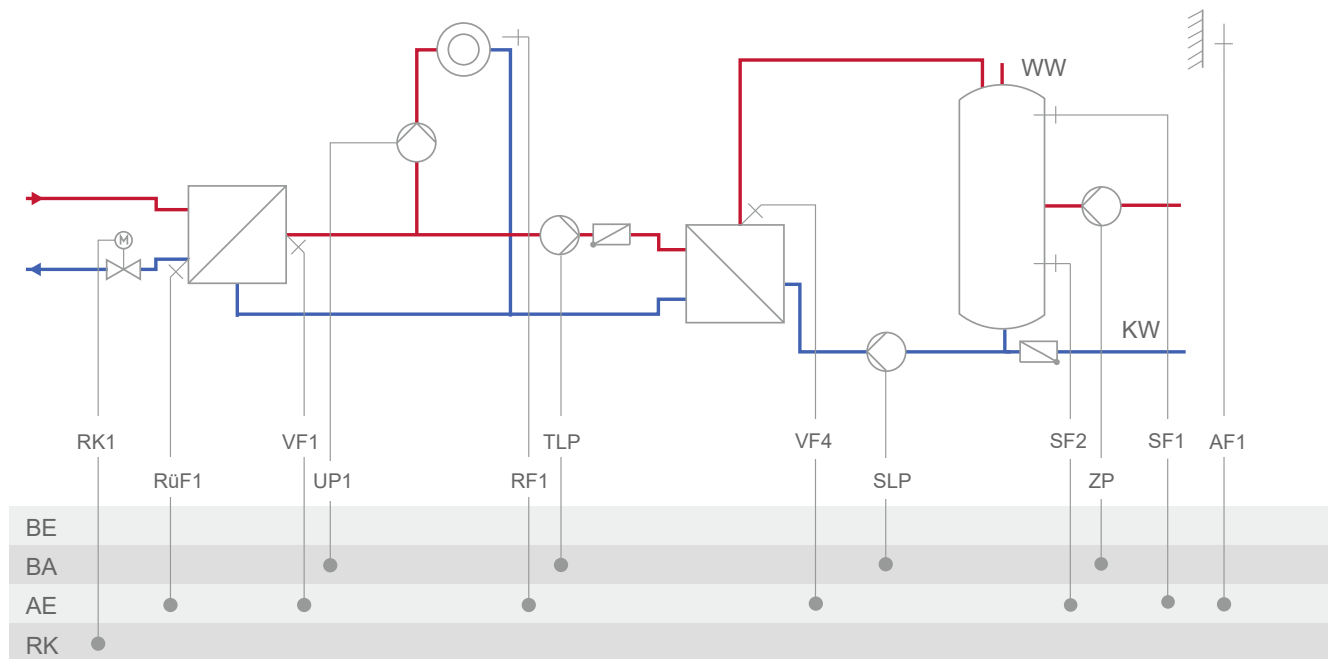
System 2.1



Default setting	
CO1 → F01	- 0 (without RF1)
CO1 → F02	- 1 (with AF1)
CO1 → F03	- 1 (with RüF1)
CO4 → F01	- 1 (with SF1)
CO4 → F02	- 0 (without SF2)
CO5' → F10	Function of the 0 to 10 V output: <ul style="list-style-type: none"> <li>- 1 = Control signal RK1</li> <li>- 6 = External demand</li> <li>- 7 = SLP speed</li> <li>- 5 = Outdoor temperature</li> </ul> <div style="display: flex; justify-content: space-between; margin-top: 5px;"> <div style="width: 60%;"></div> <div style="width: 35%;">                         When CO1 → F18 - 1                          When CO4 → F21 - 1                          When CO5 → F23 - 1                          Direction 'AA'                     </div> </div>

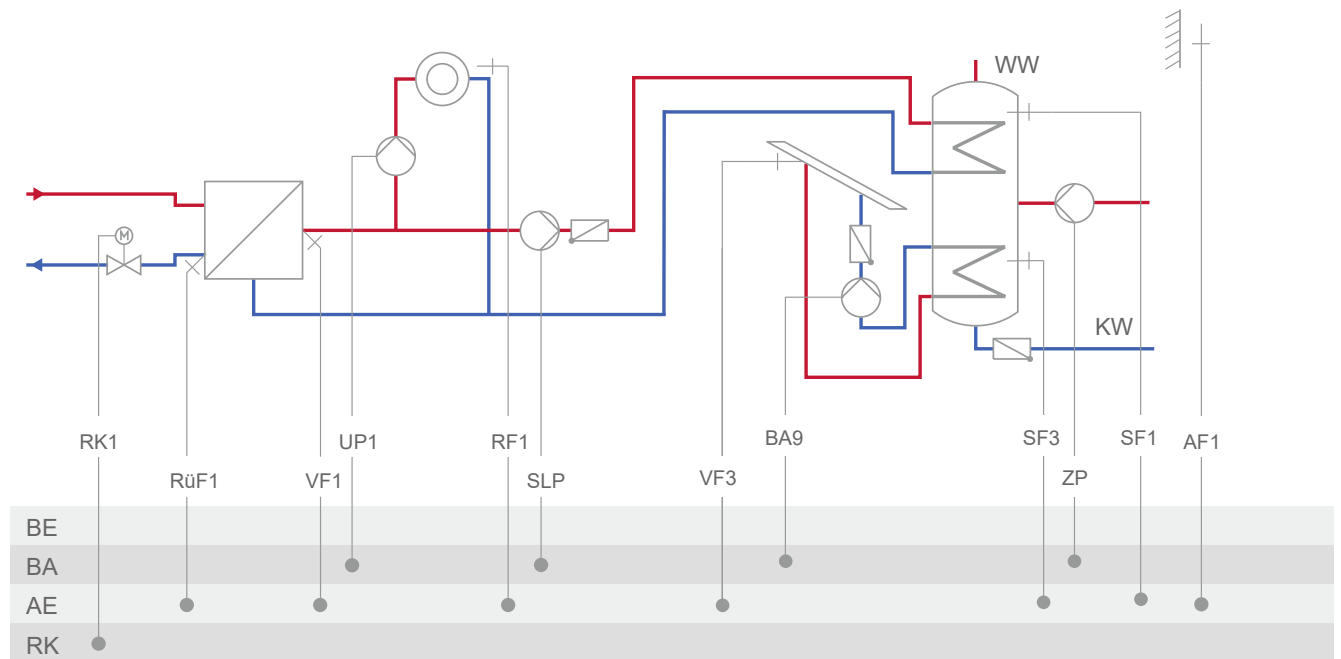
## Appendix A (configuration instructions)

### System 2.2



Default setting	
CO1 → F01	- 0 (without RF1)
CO1 → F02	- 1 (with AF1)
CO1 → F03	- 1 (with RüF1)
CO4 → F01	- 1 (with SF1)
CO4 → F02	- 1 (with SF2)
CO4 → F05	- 0 (without VF4)
CO5' → F10	Function of the 0 to 10 V output: <ul style="list-style-type: none"> <li>- 1 = Control signal RK1</li> <li>- 6 = External demand</li> <li>- 7 = SLP speed</li> <li>- 5 = Outdoor temperature</li> </ul> <div style="display: flex; justify-content: space-between; margin-top: 10px;"> <div>           When CO1 → F18 - 1            When CO4 → F21 - 1            When CO5 → F23 - 1            Direction 'AA'         </div> </div>

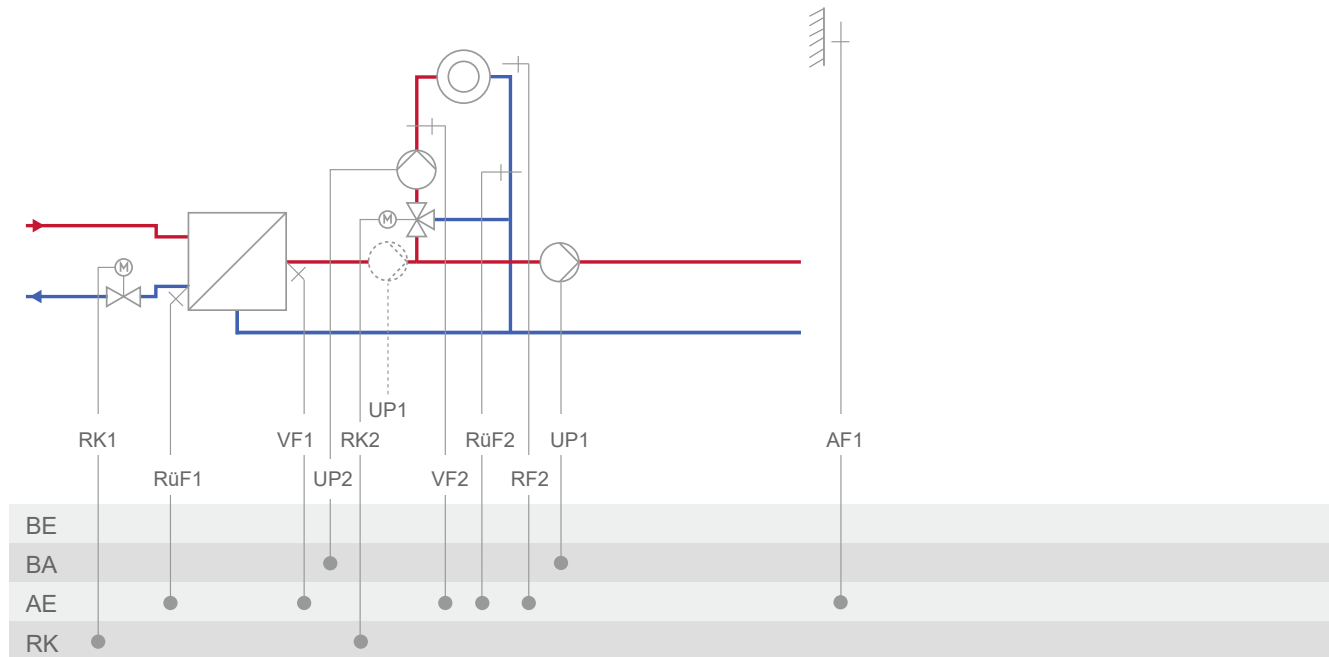
System 2.3



Default setting	
CO1 → F01	- 0 (without RF1)
CO1 → F02	- 1 (with AF1)
CO1 → F03	- 1 (with RüF1)
CO4 → F01	- 1 (with SF1)
CO5' → F10	Function of the 0 to 10 V output: <ul style="list-style-type: none"> <li>- 1 = Control signal RK1</li> <li>- 6 = External demand</li> <li>- 7 = SLP speed</li> <li>- 5 = Outdoor temperature</li> </ul> When CO1 → F18 - 1 When CO4 → F21 - 1 When CO5 → F23 - 1 Direction 'AA'

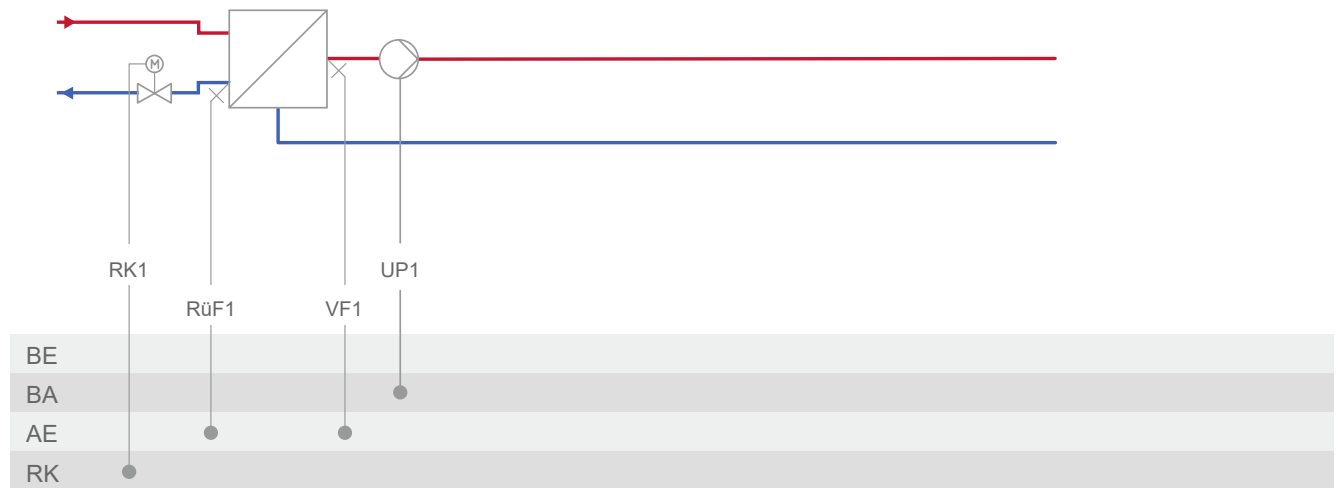
## Appendix A (configuration instructions)

### System 3.0



Default setting	
CO1 → F02	- 1 (with AF1)
CO1 → F03	- 1 (with RüF1)
CO2 → F01	- 0 (without RF2)
CO2 → F02	- 1 (with AF1)
CO2 → F03	- 0 (without RüF2)
CO5 → F14	- 0 (UP1 only active during the processing for an external demand)
CO5' → F10	Function of the 0 to 10 V output: <ul style="list-style-type: none"> <li>- 1 = Control signal RK1</li> <li>- 2 = Control signal RK2</li> <li>- 6 = External demand</li> <li>- 5 = Outdoor temperature</li> </ul> <div style="display: flex; justify-content: space-between; margin-top: 10px;"> <div>             When CO1 → F18 - 1              When CO5 → F23 - 1              Direction 'AA'           </div> </div>

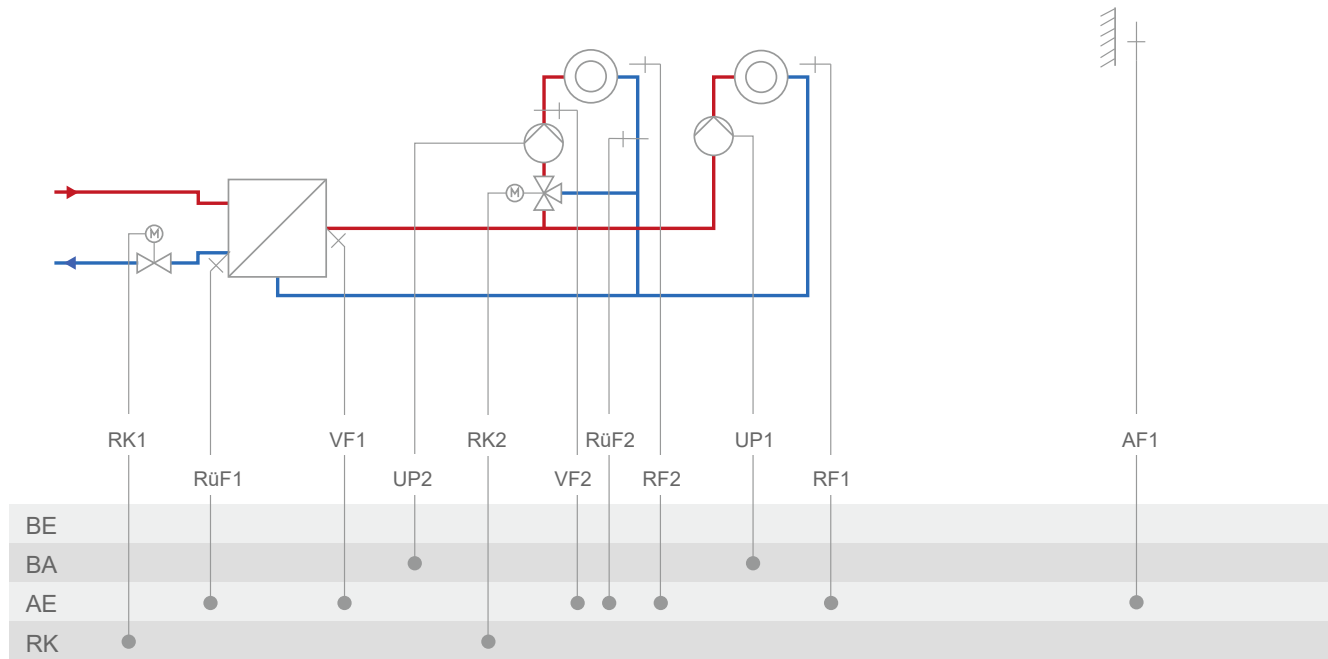
**System 3.5**



<b>Note:</b>	<b>Control operation and UP1 only active during the processing for an external demand.</b>
<b>Default setting</b>	
CO1 → F03	- 1 (with RüF1)
CO5' → F10	Function of the 0 to 10 V output: - 1 = Control signal RK1 - 6 = External demand When CO1 → F18 - 1

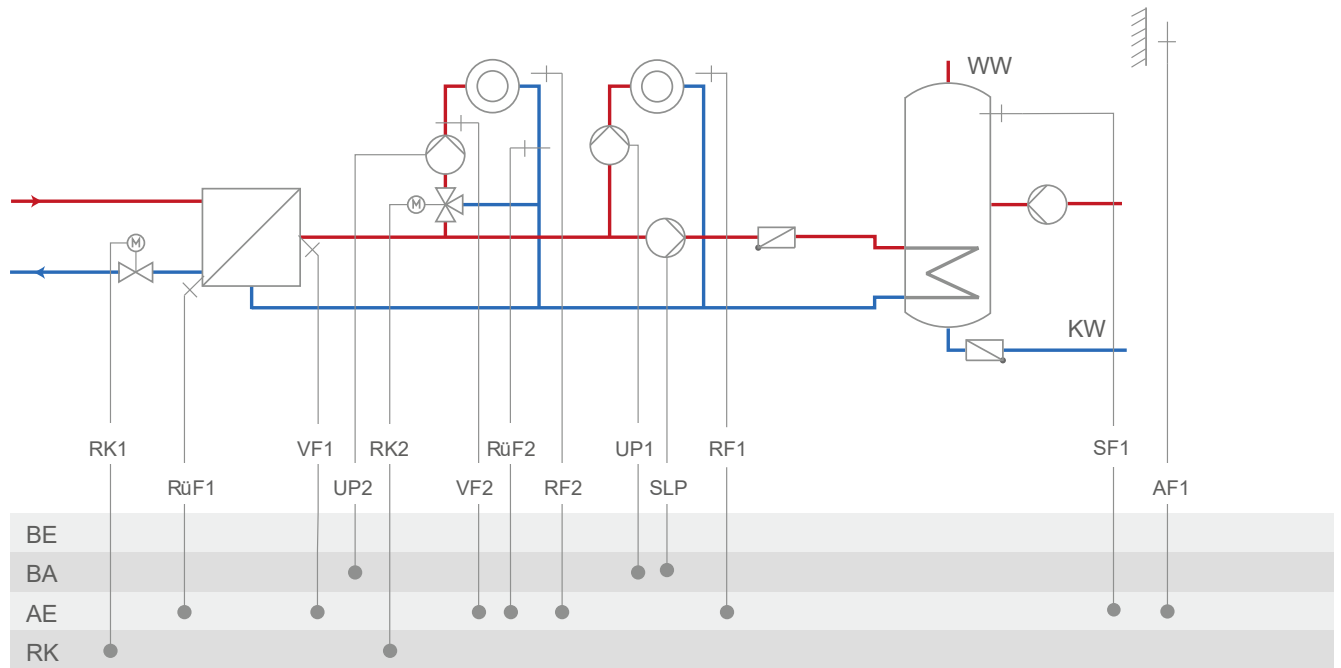
## Appendix A (configuration instructions)

### System 4.0



Default setting	
CO1 → F02	- 0 (without RF1)
CO1 → F03	- 1 (with AF1)
CO2 → F01	- 1 (with RüF1)
CO2 → F02	- 0 (without RF2)
CO2 → F03	- 1 (with AF1)
CO5' → F10	Function of the 0 to 10 V output: <ul style="list-style-type: none"> <li>- 1 = Control signal RK1</li> <li>- 2 = Control signal RK2</li> <li>- 6 = External demand</li> <li>- 5 = Outdoor temperature</li> </ul> <div style="text-align: right;">             When CO1 → F18 - 1              When CO5 → F23 - 1              Direction 'AA'           </div>

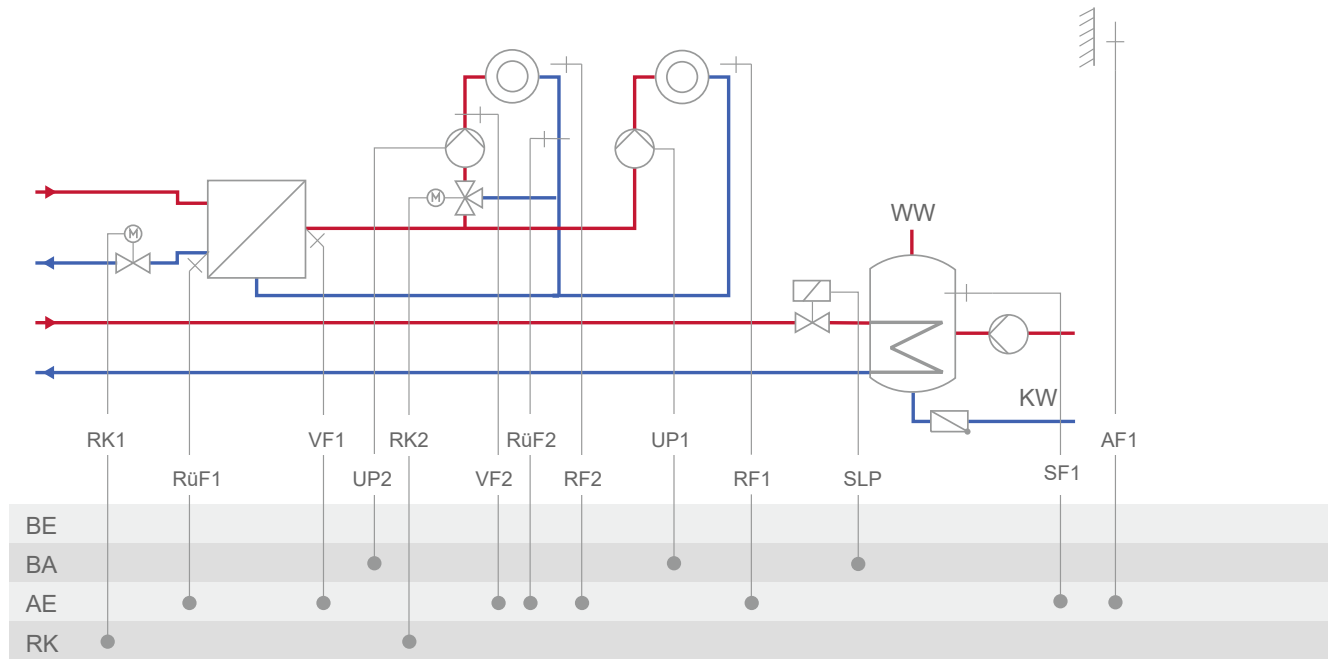
System 4.1



Default setting	
CO1 → F01	- 0 (without RF1)
CO1 → F02	- 1 (with AF1)
CO1 → F03	- 1 (with RüF1)
CO2 → F01	- 0 (without RF2)
CO2 → F02	- 1 (with AF1)
CO2 → F03	- 0 (without RüF2)
CO4 → F01	- 1 (with SF1)
CO4 → F02	- 0 (without SF2)
CO5' → F10	<p>Function of the 0 to 10 V output:</p> <ul style="list-style-type: none"> <li>- 1 = Control signal RK1</li> <li>- 2 = Control signal RK2</li> <li>- 6 = External demand</li> <li>- 7 = SLP speed</li> <li>- 5 = Outdoor temperature</li> </ul> <p style="text-align: right;">                     When CO1 → F18 - 1                      When CO4 → F21 - 1                      When CO5 → F23 - 1                      Direction 'AA'                 </p>

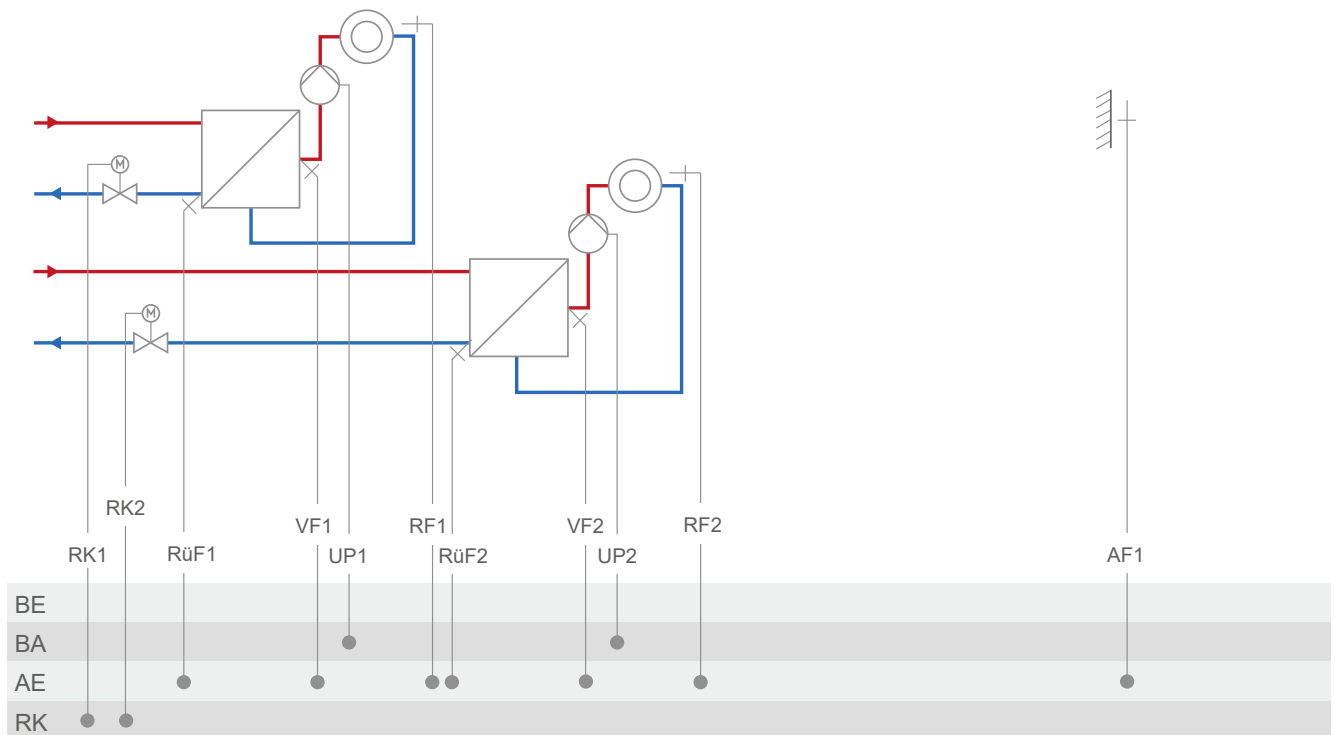
## Appendix A (configuration instructions)

### System 4.5



Default setting	
CO1 → F01	- 0 (without RF1)
CO1 → F02	- 1 (with AF1)
CO1 → F03	- 1 (with RüF1)
CO2 → F01	- 0 (without RF2)
CO2 → F02	- 1 (with AF1)
CO2 → F03	- 0 (without RüF2)
CO4 → F01	- 1 (with SF1)
CO4 → F02	- 0 (without SF2)
CO5' → F10	Function of the 0 to 10 V output: <ul style="list-style-type: none"> <li>- 1 = Control signal RK1</li> <li>- 2 = Control signal RK2</li> <li>- 6 = External demand</li> <li>- 5 = Outdoor temperature</li> </ul> <div style="text-align: right;">             When CO1 → F18 - 1              When CO5 → F23 - 1              Direction 'AA'           </div>

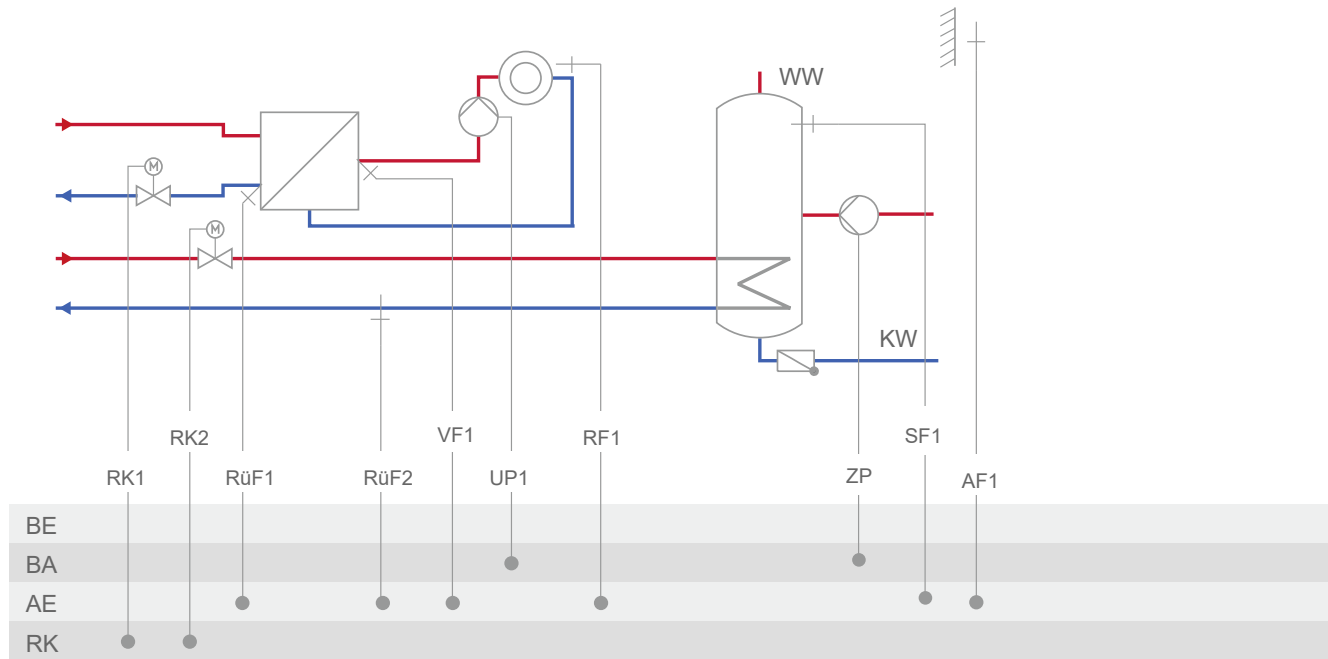
System 10.0



Default setting	
CO1 → F01	- 0 (without RF1)
CO1 → F02	- 1 (with AF1)
CO1 → F03	- 1 (with RüF1)
CO2 → F01	- 0 (without RF2)
CO2 → F02	- 1 (with AF1)
CO2 → F03	- 1 (with RüF2)
CO5' → F10	Function of the 0 to 10 V output: <ul style="list-style-type: none"> <li>- 1 = Control signal RK1</li> <li>- 2 = Control signal RK2</li> <li>- 6 = External demand</li> <li>- 5 = Outdoor temperature</li> </ul> <div style="text-align: right;">                         When CO1 → F18 - 1                          When CO5 → F23 - 1                          Direction 'AA'                     </div>

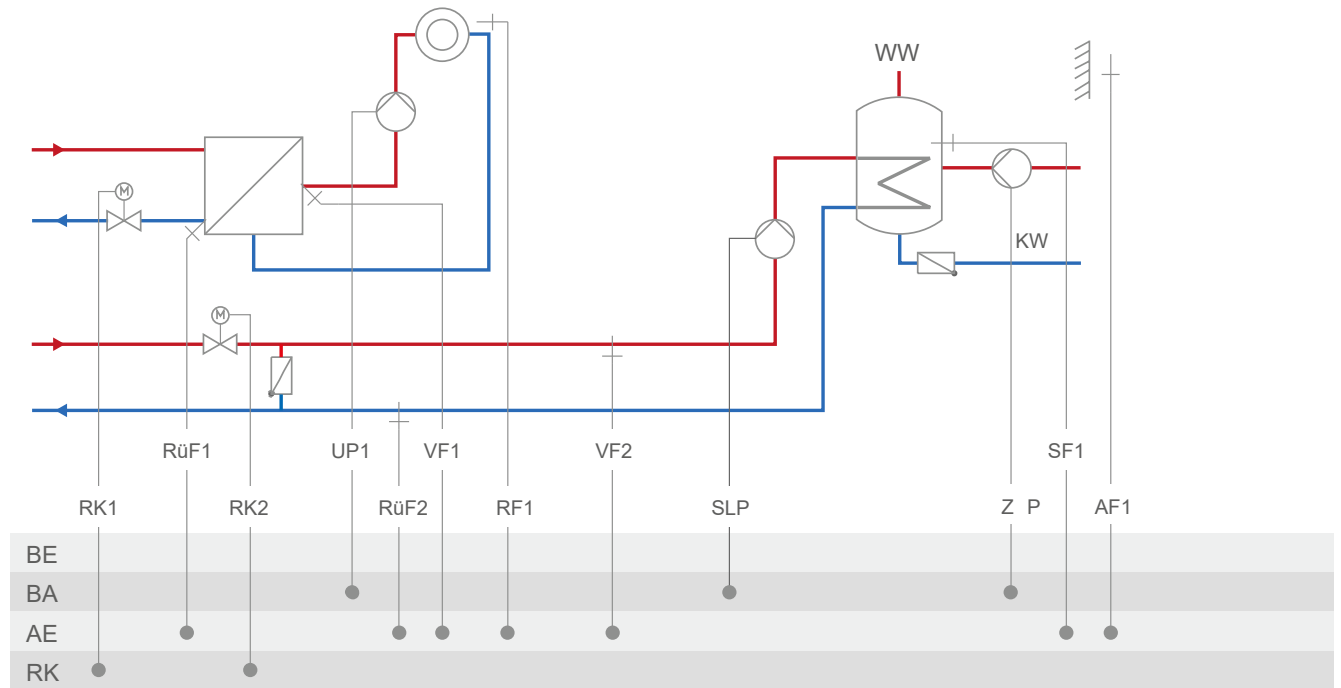
## Appendix A (configuration instructions)

### System 11.0



Default setting	
CO1 → F01	- 0 (without RF1)
CO1 → F02	- 1 (with AF1)
CO1 → F03	- 1 (with RüF1)
CO4 → F03	- 0 (without RüF2)
CO5' → F10	Function of the 0 to 10 V output: <ul style="list-style-type: none"> <li>- 1 = Control signal RK1</li> <li>- 2 = Control signal RK2</li> <li>- 6 = External demand</li> <li>- 5 = Outdoor temperature</li> </ul> <div style="text-align: right;">             When CO1 → F18 - 1              When CO5 → F23 - 1              Direction 'AA'           </div>

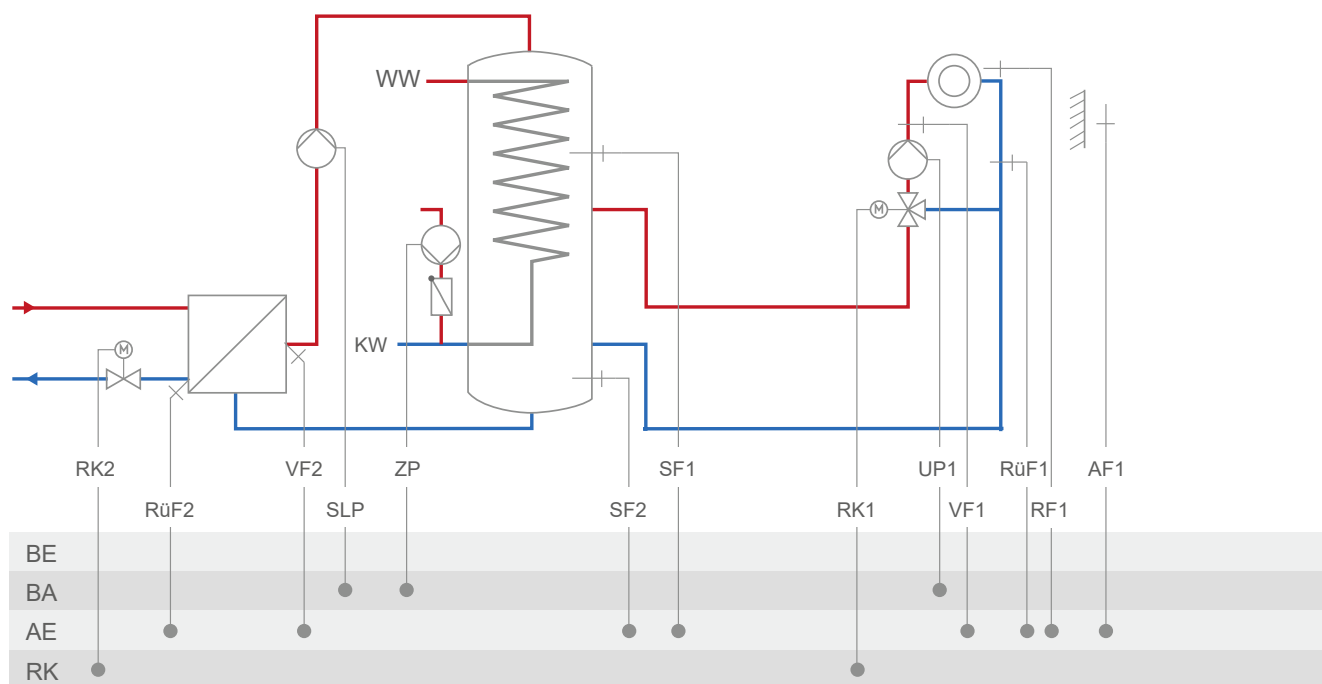
System 11.1



Default setting	
CO1 → F01	- 0 (without RF1)
CO1 → F02	- 1 (with AF1)
CO1 → F03	- 1 (with RüF1)
CO4 → F01	- 1 (with SF1)
CO4 → F02	- 0 (without SF2)
CO4 → F03	- 0 (without RüF2)
CO5' → F10	<p>Function of the 0 to 10 V output:</p> <ul style="list-style-type: none"> <li>- 1 = Control signal RK1</li> <li>- 2 = Control signal RK2</li> <li>- 6 = External demand</li> <li>- 7 = SLP speed</li> <li>- 5 = Outdoor temperature</li> </ul> <p style="text-align: right;">                     When CO1 → F18 - 1                      When CO4 → F21 - 1                      When CO5 → F23 - 1                      Direction 'AA'                 </p>

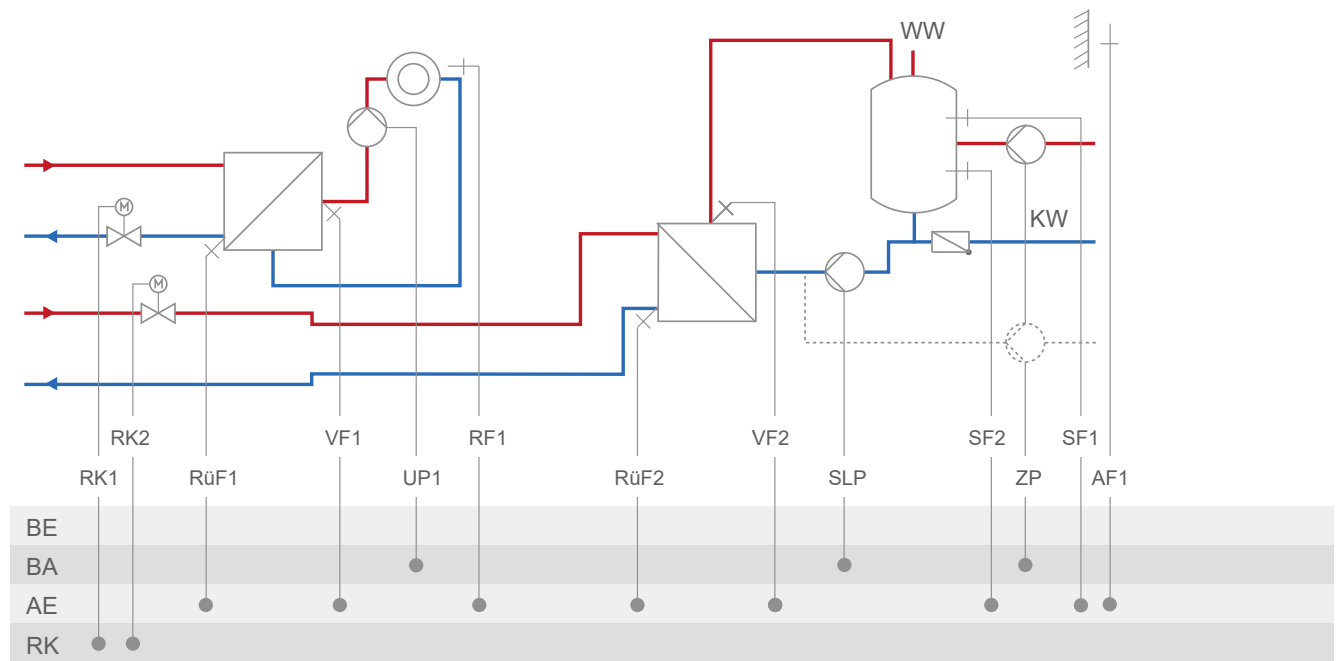
## Appendix A (configuration instructions)

### System 11.1 with buffer tank



Default setting	
CO1 → F01	- 0 (without RF1)
CO1 → F02	- 1 (with AF1)
CO1 → F03	- 1 (with RüF1)
CO4 → F01	- 1 (with SF1)
CO4 → F02	- 0 (without SF2)
CO4 → F03	- 0 (without RüF2)
CO5' → F10	Function of the 0 to 10 V output: <ul style="list-style-type: none"> <li>- 1 = Control signal RK1</li> <li>- 2 = Control signal RK2</li> <li>- 6 = External demand</li> <li>- 7 = SLP speed</li> <li>- 5 = Outdoor temperature</li> </ul> <div style="display: flex; justify-content: flex-end; margin-top: 10px;"> <div style="text-align: right; padding-right: 20px;">             When CO1 → F18 - 1              When CO4 → F21 - 1              When CO5 → F23 - 1              Direction 'AA'           </div> </div>

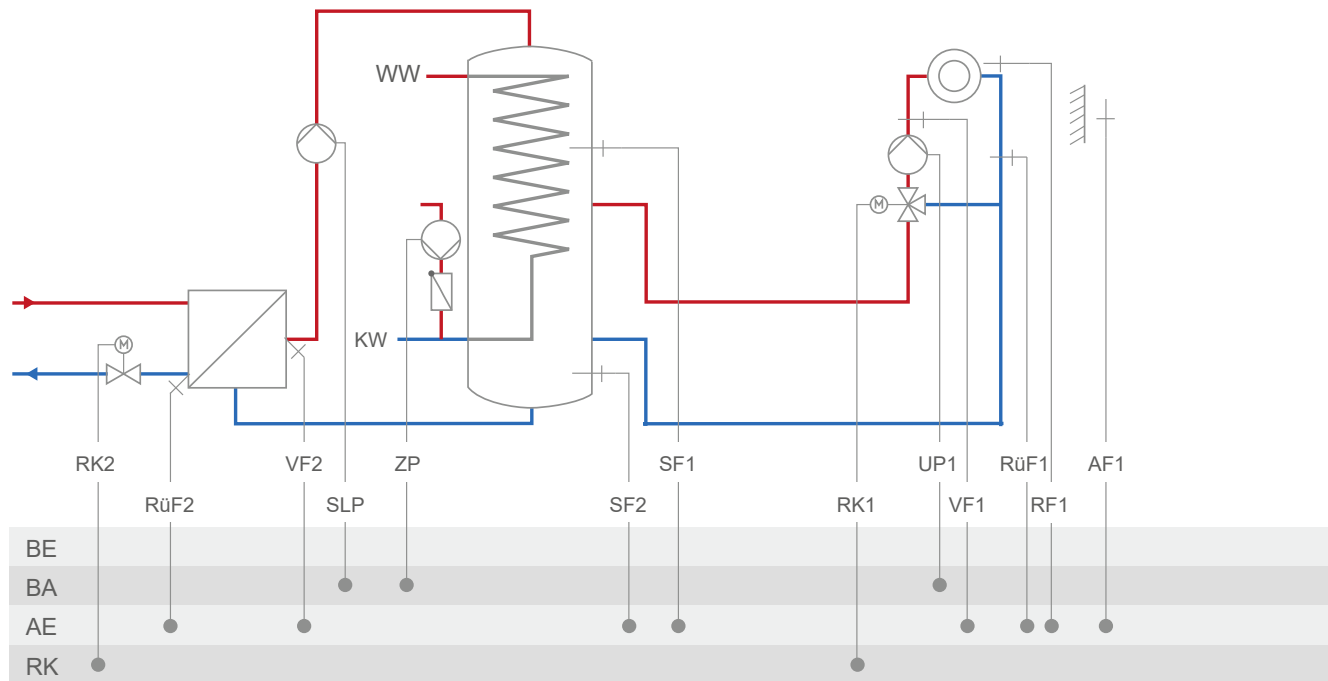
System 11.2



Default setting	
CO1 → F01	- 0 (without RF1)
CO1 → F02	- 1 (with AF1)
CO1 → F03	- 1 (with RüF1)
CO4 → F01	- 1 (with SF1)
CO4 → F02	- 1 (with SF2)
CO4 → F03	- 0 (without RüF2)
CO4 → F10	- 0 (DHW circulation return in storage tank)
CO5' → F10	Function of the 0 to 10 V output: <ul style="list-style-type: none"> <li>- 1 = Control signal RK1</li> <li>- 2 = Control signal RK2</li> <li>- 6 = External demand</li> <li>- 7 = SLP speed</li> <li>- 5 = Outdoor temperature</li> </ul> <div style="text-align: right; margin-top: 10px;">                         When CO1 → F18 - 1                          When CO4 → F21 - 1                          When CO5 → F23 - 1                          Direction 'AA'                     </div>

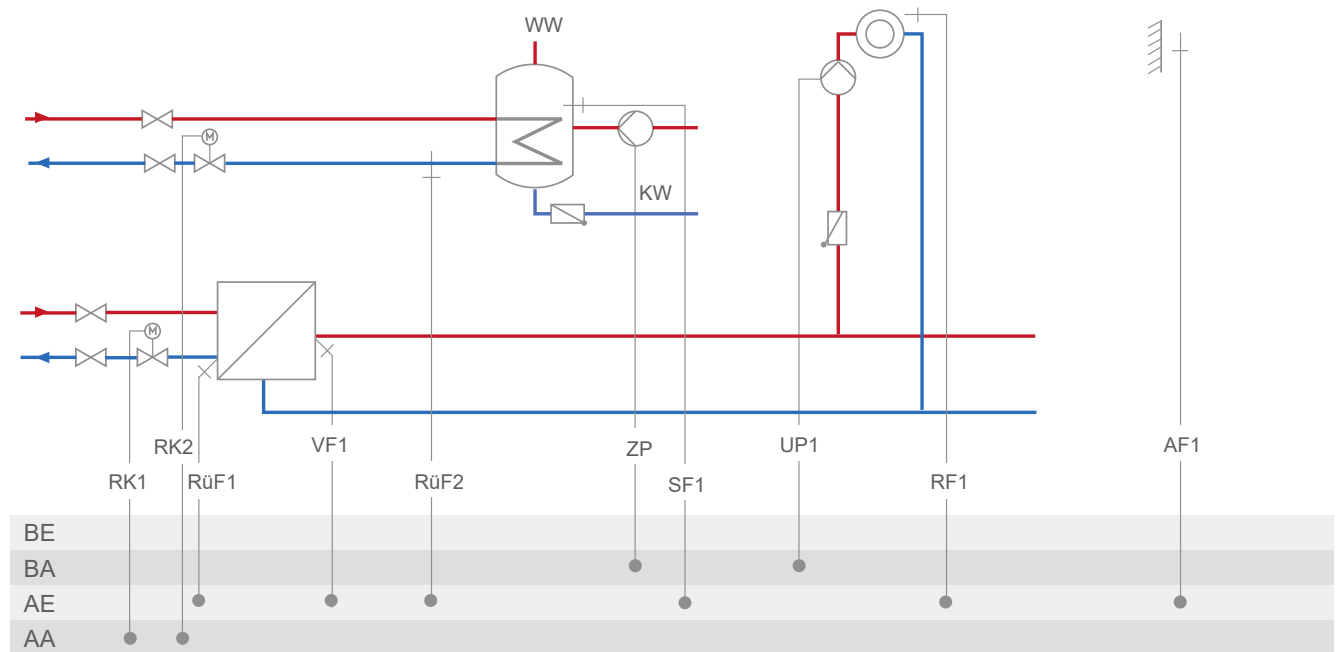
## Appendix A (configuration instructions)

### System 11.2 with buffer tank



Default setting	
CO1 → F01	- 0 (without RF1)
CO1 → F02	- 1 (with AF1)
CO1 → F03	- 1 (with RüF1)
CO4 → F01	- 1 (with SF1)
CO4 → F02	- 1 (with SF2)
CO4 → F03	- 0 (without RüF2)
CO5' → F10	Function of the 0 to 10 V output: <ul style="list-style-type: none"> <li>- 1 = Control signal RK1</li> <li>- 2 = Control signal RK2</li> <li>- 6 = External demand</li> <li>- 7 = SLP speed</li> <li>- 5 = Outdoor temperature</li> </ul> <div style="display: flex; justify-content: space-between; margin-top: 10px;"> <div> <p>When CO1 → F18 - 1</p> <p>When CO4 → F21 - 1</p> <p>When CO5 → F23 - 1</p> <p>Direction 'AA'</p> </div> </div>

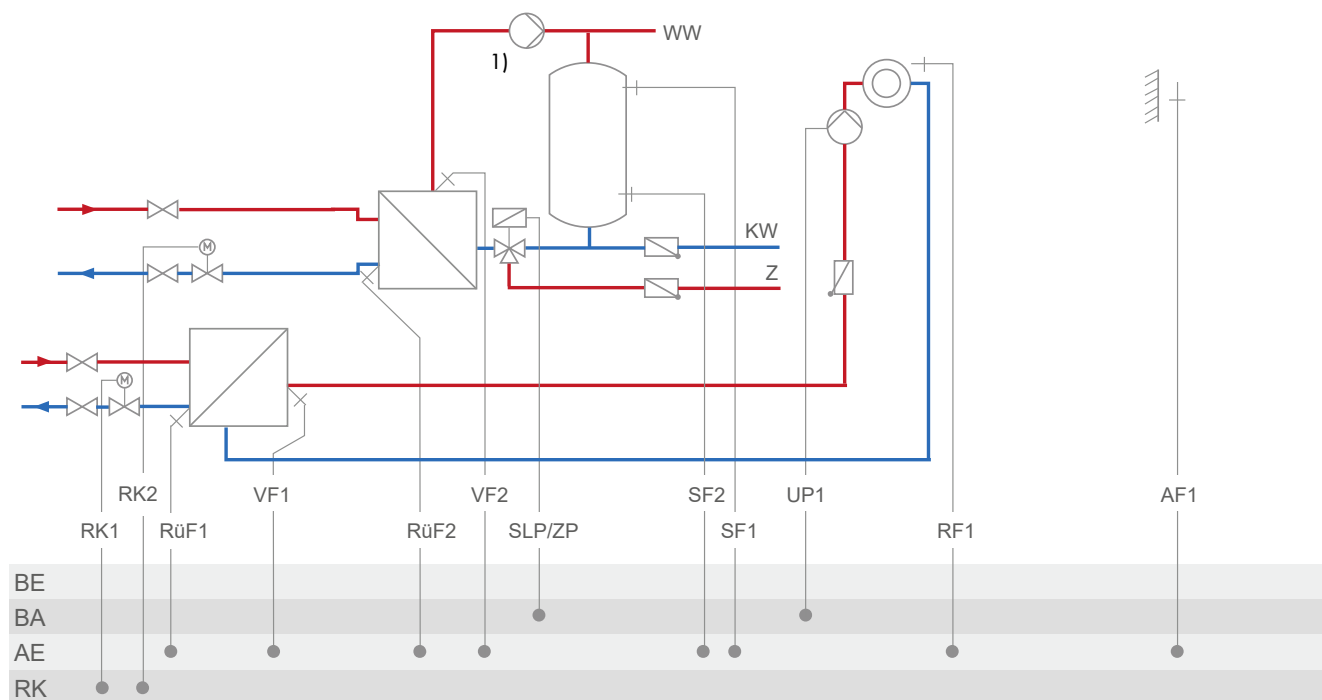
System 11.5



<b>Note:</b>	<b>DHW circuit with adjustable valve position for storage tank charging in absolute priority operation</b> <b>By using RüF2, the ready-adjusted valve position is subject to the return temperature limitation.</b>
<b>Default setting</b>	
CO1 → F01	- 0 (without RF1)
CO1 → F02	- 1 (with AF1)
CO4 → F02	- 0 (without SF2)
CO4 → F03	- 1 (with RüF2)
CO5' → F10	Function of the 0 to 10 V output: <ul style="list-style-type: none"> <li>- 1 = Control signal RK1</li> <li>- 2 = Control signal RK2</li> <li>- 6 = External demand</li> <li>- 5 = Outdoor temperature</li> </ul> <p style="text-align: right;">When CO1 → F18 - 1 When CO5 → F23 - 1 Direction 'AA'</p>

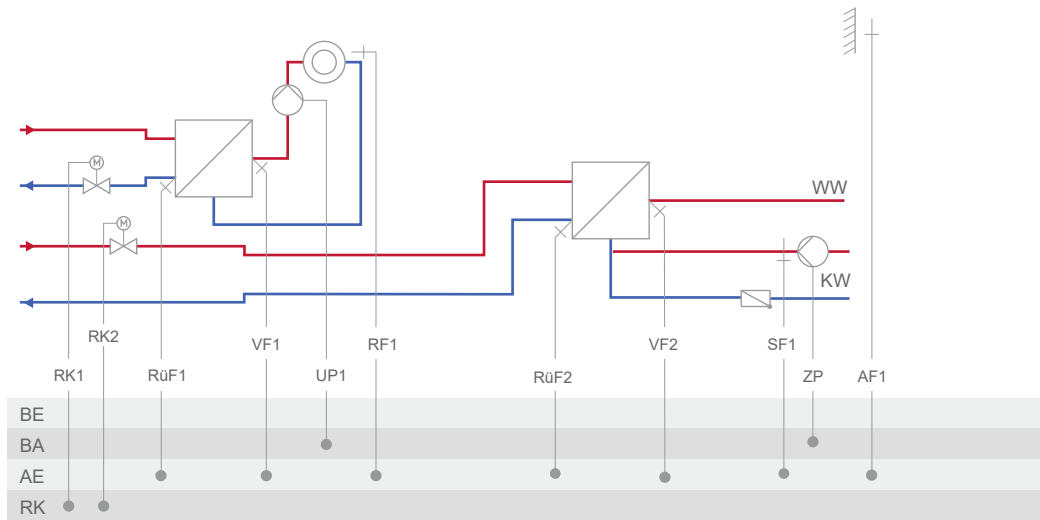
## Appendix A (configuration instructions)

### System 11.6



<b>1) Note:</b>	<b>Install a continuously running pump in the DHW circuit and connect it directly to the supply voltage.</b>
<b>Default setting</b>	
CO1 → F01	- 0 (without RF1)
CO1 → F02	- 1 (with AF1)
CO1 → F03	- 1 (with RüF1)
CO4 → F01	- 1 (with SF1)
CO4 → F02	- 1 (with SF2)
CO4 → F03	- 0 (without RüF2)
CO5' → F10	Function of the 0 to 10 V output: <ul style="list-style-type: none"> <li>- 1 = Control signal RK1</li> <li>- 2 = Control signal RK2</li> <li>- 6 = External demand</li> <li>- 5 = Outdoor temperature</li> </ul> <div style="text-align: right;">             When CO1 → F18 - 1              When CO5 → F23 - 1              Direction 'AA'           </div>

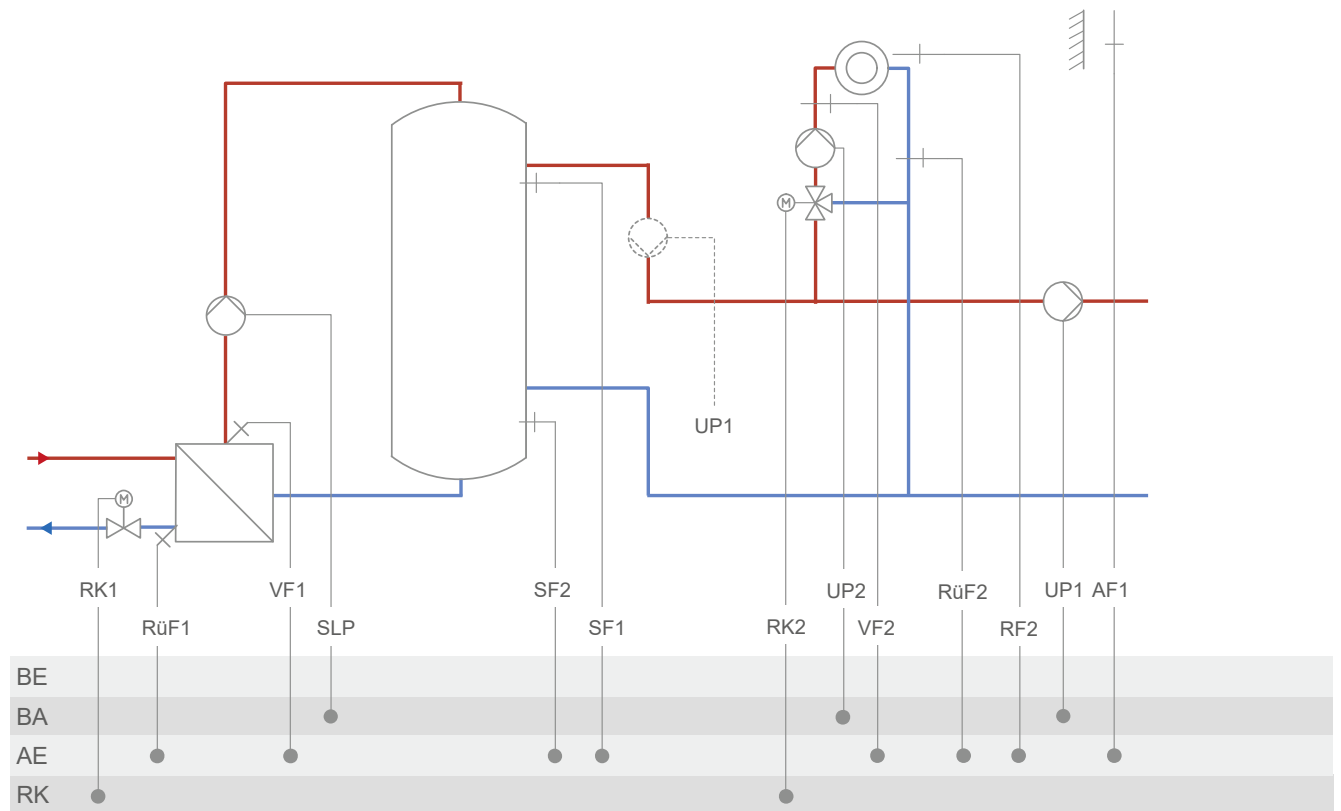
System 11.9



Default setting	
CO1 → F01	- 0 (without RF1)
CO1 → F02	- 1 (with AF1)
CO1 → F03	- 1 (with RüF1)
CO4 → F01	- 0 (without SF1)
CO4 → F03	- 0 (without RüF2)
CO5' → F10	0 to 10 V output function: <ul style="list-style-type: none"> <li>- 1 = Control signal RK1</li> <li>- 2 = Control signal RK2</li> <li>- 10 = 10 V supply</li> <li>- 6 = External demand</li> <li>- 5 = Outdoor temperature</li> </ul> When CO1 → F18 - 1 When CO5 → F23 - 1 Direction 'AA'

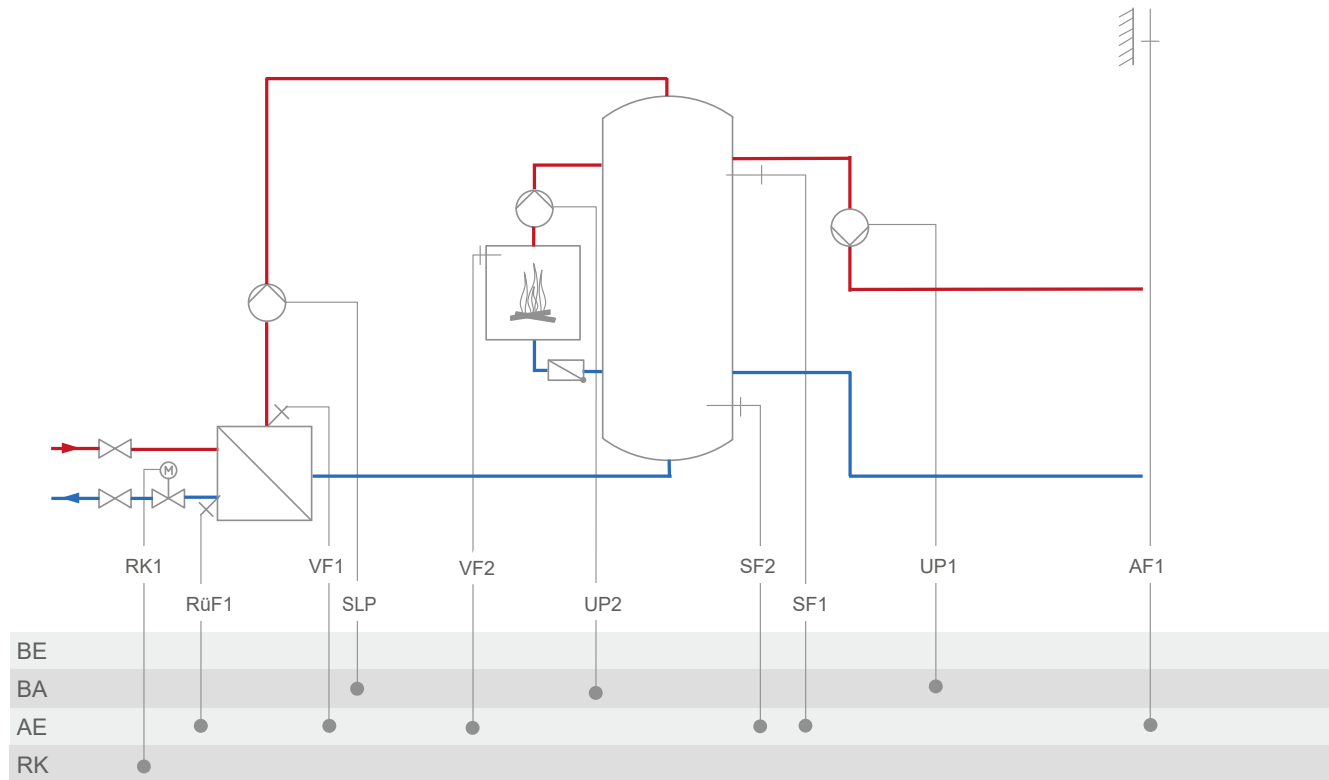


System 16.1



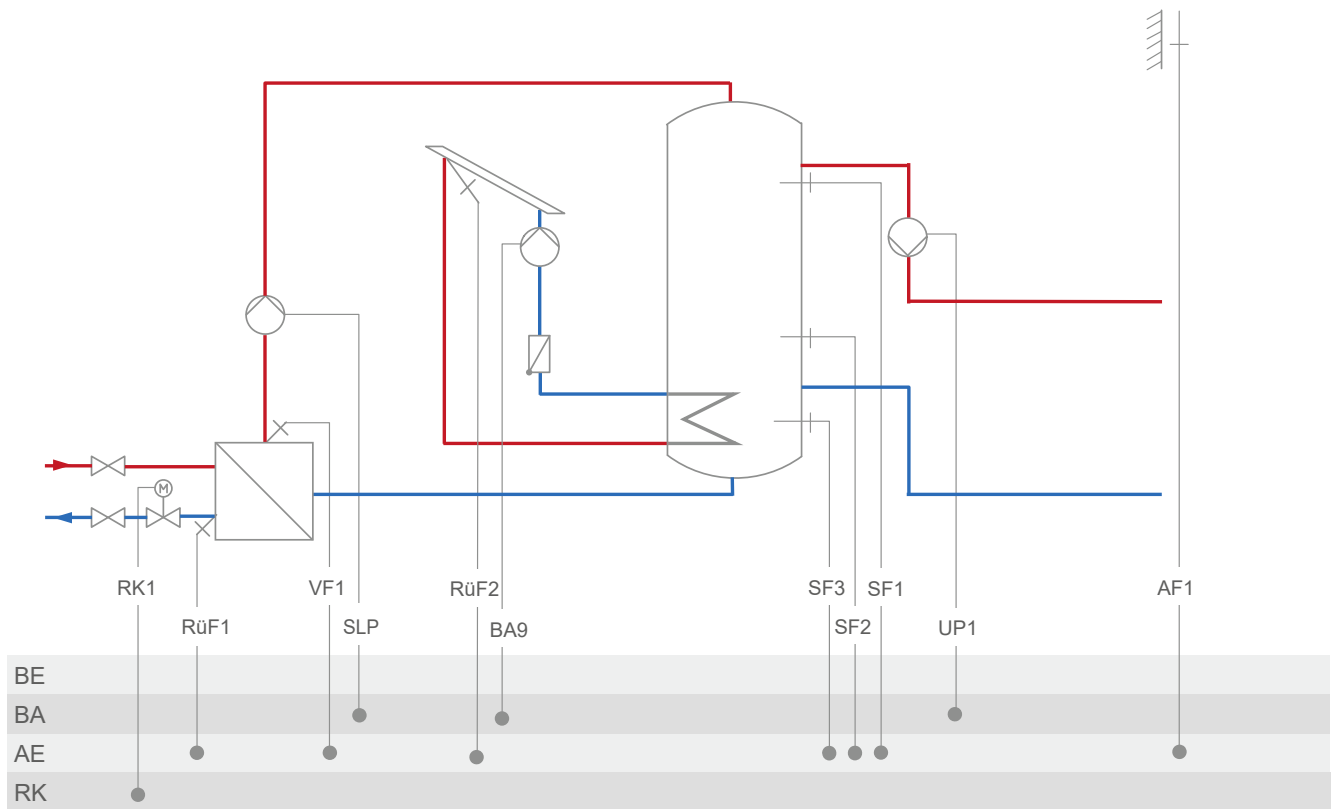
Default setting	
CO1 → F02	- 0 (without AF1)
CO1 → F03	- 1 (with RüF1)
CO1 → F06	- 1 (with SF2)
CO2 → F02	- 1 (with AF1)
CO2 → F03	- 0 (without RüF2)
CO5' → F10	Function of the 0 to 10 V output: <ul style="list-style-type: none"> <li>- 1 = Control signal RK1</li> <li>- 2 = Control signal RK2</li> <li>- 6 = External demand</li> <li>- 7 = SLP speed</li> <li>- 5 = Outdoor temperature</li> </ul> <div style="text-align: right; padding-right: 20px;">                         When CO1 → F18 - 1                          When CO1 → F21 - 1                          When CO5 → F23 - 1                          Direction 'AA'                     </div>

System 16.2



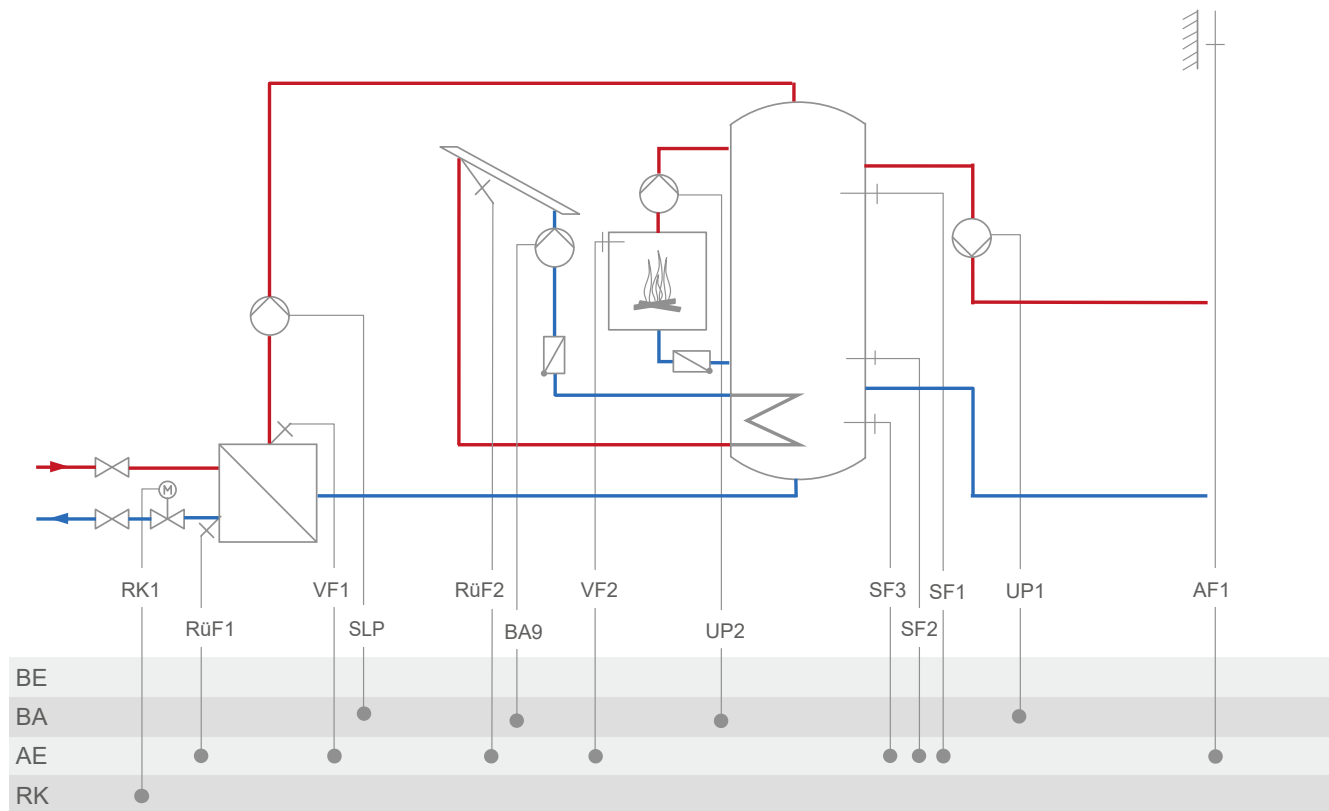
Default setting	
CO1 → F02	- 1 (with AF1)
CO1 → F03	- 1 (with RüF1)
CO1 → F06	- 1 (with SF2)
CO5' → F10	Function of the 0 to 10 V output: - 1 = Control signal RK1 - 6 = External demand - 7 = SLP speed - 5 = Outdoor temperature When CO1 → F18 - 1 When CO4 → F21 - 1 When CO5 → F23 - 1 Direction 'AA'

System 16.3



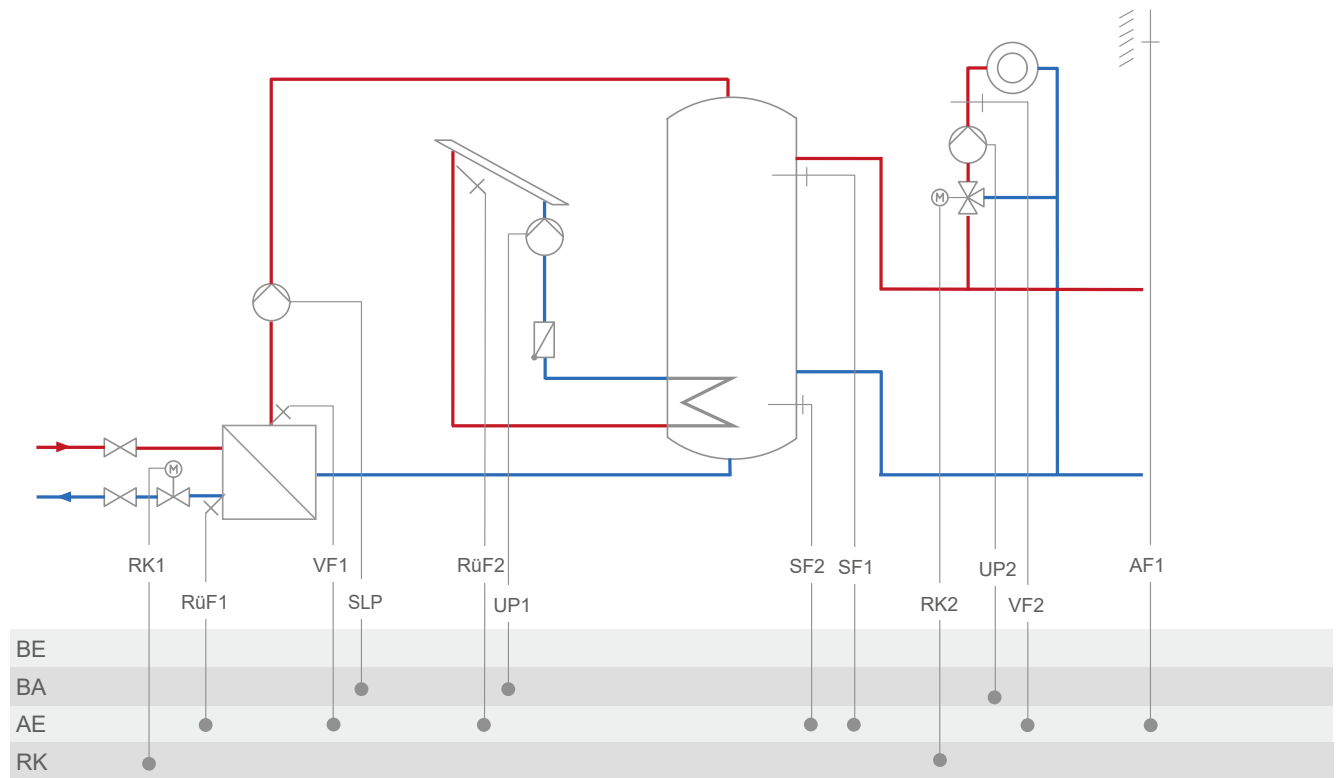
Default setting	
CO1 → F02	- 1 (with AF1)
CO1 → F03	- 1 (with RüF1)
CO1 → F06	- 1 (with SF2)
CO5' → F10	Function of the 0 to 10 V output: <ul style="list-style-type: none"> <li>- 1 = Control signal RK1</li> <li>- 6 = External demand</li> <li>- 7 = SLP speed</li> <li>- 5 = Outdoor temperature</li> </ul> <div style="display: flex; justify-content: flex-end; margin-top: 10px;"> <div style="text-align: right;">                         When CO1 → F18 - 1                          When CO1 → F21 - 1                          When CO5 → F23 - 1                          Direction 'AA'                     </div> </div>

System 16.4



Default setting	
CO1 → F02	- 1 (with AF1)
CO1 → F03	- 1 (with RüF1)
CO1 → F06	- 1 (with SF2)
CO5' → F10	Function of the 0 to 10 V output: <ul style="list-style-type: none"> <li>- 1 = Control signal RK1</li> <li>- 6 = External demand</li> <li>- 7 = SLP speed</li> <li>- 5 = Outdoor temperature</li> </ul> <div style="display: flex; justify-content: space-between; margin-top: 10px;"> <div> <ul style="list-style-type: none"> <li>When CO1 → F18 - 1</li> <li>When CO1 → F21 - 1</li> <li>When CO5 → F23 - 1</li> </ul> </div> <div>                     Direction 'AA'                 </div> </div>

System 16.6



Default setting	
CO1 → F02	- 1 (with AF1)
CO1 → F03	- 1 (with RüF1)
CO1 → F06	- 1 (with SF2)
CO2 → F02	- 1 (with AF1)
CO2 → F03	- 0 (without RüF2)
CO5' → F10	Function of the 0 to 10 V output: <ul style="list-style-type: none"> <li>- 1 = Control signal RK1</li> <li>- 2 = Control signal RK2</li> <li>- 6 = External demand</li> <li>- 7 = SLP speed</li> <li>- 5 = Outdoor temperature</li> </ul> <div style="text-align: right; margin-top: 10px;">             When CO1 → F18 - 1              When CO1 → F21 - 1              When CO5 → F23 - 1              Direction 'AA'           </div>

## 16.2 Functions of the heating circuit

Which controller functions are available depends on the selected system code number.

### 16.2.1 Outdoor-temperature-compensated control

When outdoor-temperature-compensated control is used, the flow temperature is controlled based on the outdoor temperature. The heating characteristic in the heating controller defines the flow temperature set point as a function of the outdoor temperature (see Fig. 11).

The outdoor temperature required for outdoor-temperature-compensated control can either be measured with an outdoor sensor or received over the 0 to 10 V input.

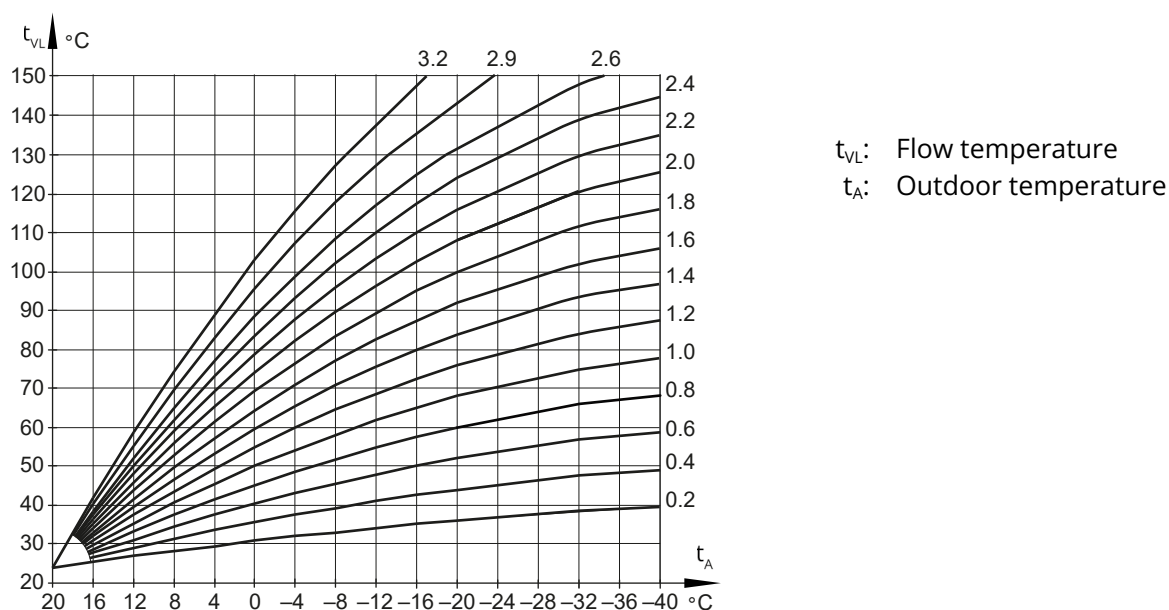


Fig. 11: Gradient characteristics

### 16.2.1.1 Outdoor temperature received or sent as 0 to 10 V signal

The outdoor temperature can be received at terminals 11 and 12 as a 0 to 10 V input signal or issued as a 0 to 10 V output signal.

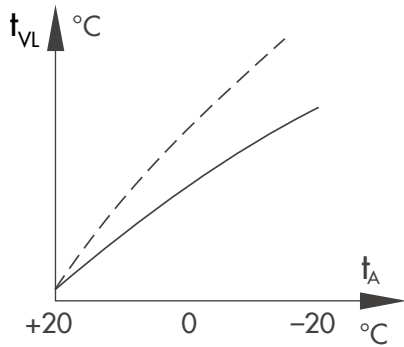
The zero of the 0 to 10 V input and output signals can be shifted, if required.

Function	Default	Configuration
Outdoor sensor AF1	1	CO1, 2 → F02 - 1
Send or receive outdoor temperature as 0 to 10 V signal	0	CO5 → F23 - 1
Send or receive outdoor temperature as 0 to 10 V signal	AE	Direction: AE (receive)
Send or receive outdoor temperature as 0 to 10 V signal	-20 °C	Lower transmission range: -50 to +100 °C
Send or receive outdoor temperature as 0 to 10 V signal	+50 °C	Upper transmission range: -50 to +100 °C
AE (terminals 11/12) Zero shift	0	CO5' → F07 - 1
	5 %	Zero: 5 to 20 %
Send or receive outdoor temperature as 0 to 10 V signal	0	CO5 → F23 - 1
Send or receive outdoor temperature as 0 to 10 V signal	AE	Direction: AA for sending
Send or receive outdoor temperature as 0 to 10 V signal	-20 °C	Lower transmission range: -50 to +100 °C
Send or receive outdoor temperature as 0 to 10 V signal	+50 °C	Upper transmission range: -50 to +100 °C
AA (terminals 11/12) reverse	0	CO5' → F01 - 0
	0 %	Zero: 0 to 50 %
AA (terminals 11/12) PWM	0	CO5' → F10 - 0
		Function: 5 = Outdoor temperature

### 16.2.1.2 Gradient characteristic

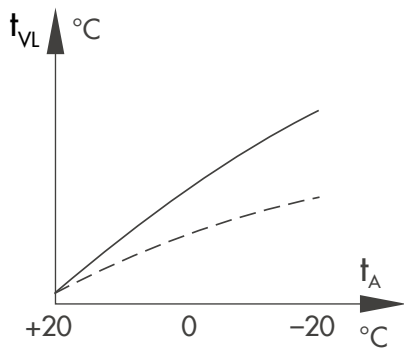
Basically, the following rule applies:

A decrease in the outdoor temperature causes the flow temperature to increase in order to keep the room temperature constant. By varying the 'Gradient' and 'Level' parameters, you can adapt the characteristic to your individual requirements.



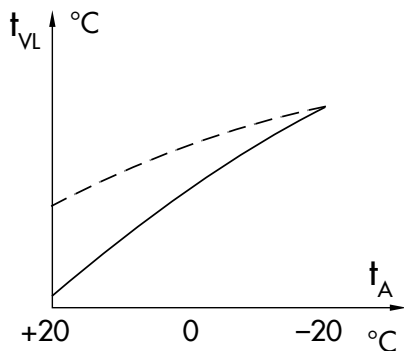
**Room temperature dropping in cold season**

⇒ Raise the gradient



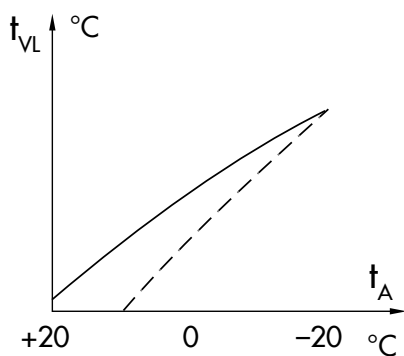
**Room temperature rising in cold season**

⇒ Decrease the gradient



**Room temperature dropping between seasons**

⇒ Raise the level and decrease the gradient



**Room temperature rising between seasons**

⇒ Decrease the level and raise the gradient

Outside the times-of-use, reduced set points are used for control:

The reduced flow set point is calculated as the difference between the adjusted values for 'Day set point' (rated room temperature) and 'Night set point' (reduced room temperature). The 'Max. flow temperature' and 'Min. flow temperature' parameters mark the upper and lower limits of the flow temperature. A separate gradient characteristic can be selected for the limitation of the return temperature.

**Examples for adjusting the characteristic:**

- Old building, radiator design 90/70: Gradient approx. 1.8
- New building, radiator design 70/55: Gradient approx. 1.4
- New building, radiator design 55/45: Gradient approx. 1.0
- Underfloor heating depending on arrangement: Gradient <0.5

**i Note**

*Particularly for control operation without room sensor, the room temperatures set for day ('Day set point') and night ('Night set point') only become effective satisfactorily when the heating characteristic has been adapted to the building/heating surface layout.*

Function	Default	Configuration
Four-point characteristic	0	CO1, 2 → F11 - 0

Parameters	Default	Switch position: value range
Day set point	20.0 °C	↕* 0.0 to 40.0 °C
Night set point	15.0 °C	↕ 0.0 to 40.0 °C

Parameters	Default	Parameter level: value range
Flow gradient		
Flow gradient	1, 2 <sup>1)</sup>	PA1, 2: 0.2 to 3.2
Flow level	0.0 °C	PA1, 2: -30.0 to +30.0 °C
Min. flow temperature	+20.0 °C	PA1, 2: -5.0 to +150.0 °C
Max. flow temperature	70.0 °C <sup>1)</sup>	PA1, 2: 5.0 to 150.0 °C
1) When CO1, 2 → F05 - 1, the following applies: Flow gradient: 0.2 to 1.0 (0.5) Max. flow temperature: 5.0 to 50.0 °C (50.0 °C)		

**16.2.1.3 Four-point characteristic**

The four-point characteristic allows you to define your own heating characteristic. It is defined by four points for the outdoor temperature, flow temperature, reduced flow temperature and return temperature. The 'Max. flow temperature' and 'Min. flow temperature' parameters mark the upper and lower limits of the flow temperature.

## Appendix A (configuration instructions)

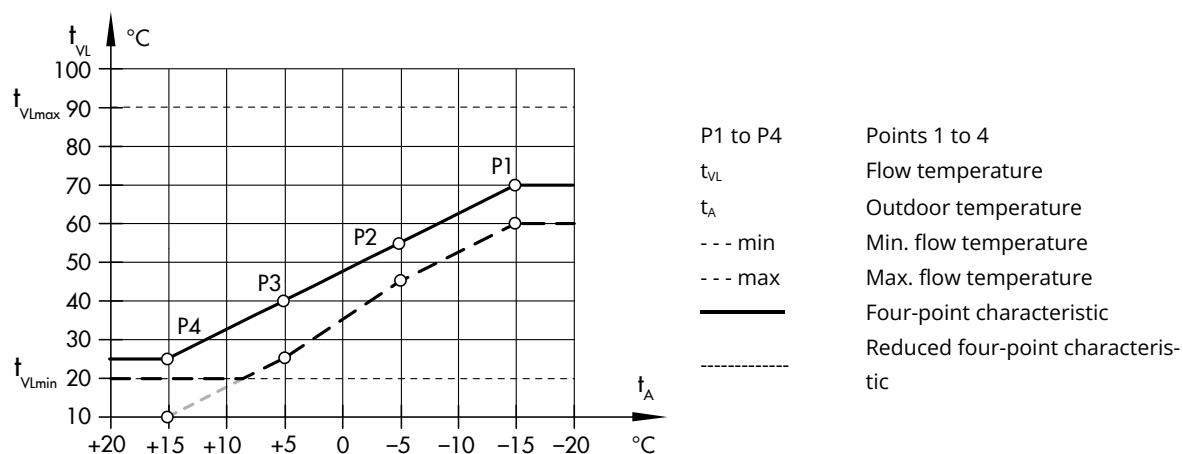


Fig. 12: Four-point characteristic

### **i** Note

- The 'Day set point' and 'Night set point' parameters are no longer available when the four-point characteristic has been selected when no additional functions (e.g. optimization, flash adaptation) have been selected.
- The Four-point characteristic function can only be activated when the adaptation function is not active (CO1, 2 → F08 - 0).

Function	Default	Configuration
Adaptation	0	CO1, 2 → F08 - 0 CO1, 2, 3, 11, 12, 13 → F08 - 0
Four-point characteristic	0	CO1, 2 → F011 - 1 CO1, 2, 3, 11, 12, 13 → F11 - 1

Parameters	Default	Parameter level: value range
Outdoor temperature	Point 1: -15.0 °C Point 2: -5.0 °C Point 3: +5.0 °C Point 4: +15.0 °C	PA1, 2: -50.0 to +50.0 °C
Flow temperature	Point 1: +70.0 °C Point 2: +55 °C Point 3: +40.0 °C Point 4: +25.0 °C	PA1, 2: -5.0 to +150.0 °C
Reduced flow temperature	Point 1: +60.0 °C Point 2: +40 °C Point 3: +20.0 °C Point 4: +20.0 °C	PA1, 2: -5.0 to +150.0 °C
Return temperature	Points 1 to 4: 65.0 °C	PA1, 2: 5.0 to 90.0 °C
Min. flow temperature	+20.0 °C	PA1, 2: -5.0 to +150.0 °C
Max. flow temperature	70.0 °C <sup>1)</sup>	PA1, 2: 5.0 to +150.0 °C
1) When CO1, 2 → F05 - 1, the following applies: Max. flow temperature: 5.0 to 50.0 °C (50 °C)		

## 16.2.2 Fixed set point control

During the times-of-use, the flow temperature can be controlled according to a fixed set point. Outside the times-of-use, the reduced flow temperature is controlled. Set the desired rated flow temperature as 'Day set point' and the reduced flow temperature as 'Night set point'.

Function	Default	Configuration
Outdoor sensor AF1	1	CO1, 2 → F02 - 0

Parameters	Default	Switch position: value range
Day set point	50.0 °C	↗* Min. to max. flow temperature
Night set point	30.0 °C	↘◀ Min. to max. flow temperature

Parameters	Default	Parameter level: value range
Min. flow temperature	+20.0 °C	PA1, 2: -5.0 to +150.0 °C PA1, 2 → P06: -5.0 to +150.0 °C PA1, 2, 3, 11, 12, 13 → P06: -5.0 to +150.0 °C
Max. flow temperature	70.0 °C	PA1, 2: 5.0 to 150.0 °C PA1, 2 → P07: 5.0 to 150.0 °C PA1, 2, 3, 11, 12, 13 → P07: 5.0 to 150.0 °C

## 16.2.3 Underfloor heating/drying of jointless floors

The CO1, 2 → F05 - 1 setting defines the respective heating circuit as an underfloor heating circuit. In doing so, the controller at first only limits the value ranges of the heating characteristic gradient and the maximum flow temperature in PA1 and 2 parameter levels:

- Value range of the gradient: 0.2 to 1.0
- Value range of the maximum flow temperature: 5 to 50 °C

Furthermore, it is possible to set a **Boost** between 0.0 to 50.0 °C, which is additionally taken into account when there is a heat demand for the underfloor heating circuit of an upstream control circuit.

The **Drying of jointless floors** function can be activated afterwards. The function block parameters (starting with the **Start temperature**) determine the drying process. The first heating up phase starts at the entered 'Start temperature', which has a flow temperature of 25 °C (default setting). The start temperature is kept constant for the days entered in 'Hold (days)'. Afterwards, this temperature is raised by the value entered in 'Temp. rise/day' within 24 hours, e.g. the default setting causes the flow temperature set point to rise to 30 °C 24 hours after the holding phase. If the maximum temperature is reached, it is kept constant for the number of days entered in 'Hold (days)'. The 'Temp. reduction/day' parameter determines the temperature reduction. If the 'Temp. reduction/day' is set to 0, the temperature holding phase changes directly to the automatic mode. If the function block parameter 'Start temperature' is set to 25 °C and 'Temp. rise/day' to 0.0 °C, the drying function runs as specified in DIN EN 1264-4:

The drying of jointless floors function starts with a flow temperature of 25 °C. This temperature is kept constant for three days. Afterwards, the controller switches to the maximum temperature adjusted. The process continues unchanged.

The **Drying of jointless floors** function is activated by changing the default setting 'STOP' to 'START'.

Reading: ■START

The following restarting stages can be selected to continue an interrupted drying process:

START Temperature build-up phase ■■START

## Appendix A (configuration instructions)

START Maximum temperature hold phase ■■■START  
 START Temperature reduction phase ■■■■START

The course of the drying process can be monitored in the operating level in the icon for the flow temperature reading (☐) of the associated heating circuit. For example:



When the additional reading in the icon for the flow temperature reading disappears after the last phase, this indicates that the drying process has been completed. Each time the supply voltage is interrupted while the function is running, the drying function automatically restarts from the beginning.

In systems in which the drying function had to be interrupted due to DHW heating (e.g. system 2.1), storage tank charging does not take place while the drying function is active, provided it is not used for frost protection of the storage tank.

### **i Note**

*The function block parameters can only be accessed after starting the function by deactivating and activating the function block again.*

Function	Default	Configuration
Underfloor heating/drying of jointless floors	0	CO1, 2 → F05 - 1
	0.0 °C	Boost: 0.0 to 50.0 °C
	25.0 °C	Start temperature: 20.0 to 60.0 °C
	0	Hold (days): 0 to 10 days
	5.0 °C	Temp. rise/day: 0.0 to 10.0 °C
	45.0 °C	Maximum temperature: 25.0 to 60.0 °C
	4	Hold (days): 0 to 30 days
	0.0 °C	Temp. reduction/day: 0.0 to 10.0 °C
SToP	■STArT, ■■STArT, ■■■STArT, ■■■■STArT,	

### 16.2.4 Night set-back

The night set-back (= difference between the target flow temperature in day and night mode) is calculated in all heating circuits with a gradient characteristic as follows:

$$2x \text{ Heating characteristic gradient } x (\text{day room temperature} - \text{night room temperature})$$

### 16.2.4.1 OT activation value in rated operation

If a heating circuit is in reduced operation (automatic mode  $\ominus$ ), this circuit is switched to rated operation whenever the outdoor temperature falls below 'OT activation value in rated operation'. Reduced operation restarts after the outdoor temperature rises above the limit (plus 0.5 °C hysteresis).

This function prevents the building from cooling down excessively outside the times-of-use when low outdoor temperatures occur. The transition towards day mode can be configured to be variable depending on the outdoor temperature.

Parameters	Default	Parameter level: value range
OT activation value in rated operation	-15.0 °C	PA1, 2: -50.0 to +5.0 °C (only when CO1', CO2 → F04 - 0)

### 16.2.4.2 OT deactivation value in rated operation

The associated heating circuit is immediately switched off when the outdoor temperature exceeds the limit 'OT deactivation value in rated operation'. The valve is closed and the pump is switched off after  $t = 2 \times$  Valve transit time. The heating starts immediately again when the outdoor temperature falls below the limit (minus 0.5 °C hysteresis).

The default setting causes the system to be switched off during warm weather at an outdoor temperature of 22 °C.

Parameters	Default	Parameter level: configuration
OT deactivation value in rated operation	22.0 °C	PA1, 2: 0.0 to 50.0 °C

### 16.2.4.3 OT deactivation value in reduced operation

The associated heating circuit is immediately switched off when the outdoor temperature exceeds the limit 'OT deactivation value in reduced operation'. The valve is closed and the pump is switched off after  $t = 2 \times$  Valve transit time. The heating starts immediately again when the outdoor temperature falls below the limit (minus 0.5 °C hysteresis).

The default setting causes the system to be switched off at night time at an outdoor temperature of 15 °C to save energy. However, be aware when this setting is used that the system takes awhile in the morning to warm up the building.

Parameters	Default	Parameter level: configuration
OT deactivation value in reduced operation	+15.0 °C	PA1, 2: -50.0 to +50.0 °C

### 16.2.4.4 Variable night set-back

The CO1', CO2' → F04 - 1 setting causes the night set-back to be variable based on the decreasing outdoor temperature.

The night set-back is fully effective at outdoor temperatures above the outdoor temperature limit value 'OTL night 100 %'. The absolute value of the night set-back is linearly reduced to zero in the range between this value and the outdoor temperature limit value 'OTL night 0 %' for continuous day mode.

By configuring CO1', CO2' → F04-1, the 'OT activation value in rated operation' parameter is not used in the corresponding PA level.

Function	Default	Configuration
Variable night set-back	0	CO1', CO2' → F04 - 1 (only when CO1, CO2 → F11 - 0)
	+5.0 °C	OTL night 100 %: -50 to +20 °C
	-15 °C	

### 16.2.5 Buffer tank systems 16.x

A heating characteristic based on a gradient or four entered points can be set in PA1 for the buffer tanks in systems 16.x. A buffer tank set point for day mode and a buffer tank set point for night mode can be set without outdoor sensors in the customer level. An external demand transmitted from secondary controlled heating circuits, from the DHW circuit or an external request (0 to 10 V or binary signal) can override the current buffer tank set point. The maximum demand is indicated as the buffer tank set point for SF1. If the temperature falls below the buffer tank set point at SF1, charging of the buffer tank is started.

The set point of the charging temperature is determined by the 'Minimum set point to charge buffer tank' parameter setting in the PA1 level. The automatic adaptation ('AT' setting) causes the set point of the charging temperature to always be above the current buffer tank set point by the value entered in 'Charging temperature boost'.

Every other value entered in 'Minimum set point to charge buffer tank' is used as the minimum set point for the charging temperature which first starts to be variable at higher buffer tank set points. When a return temperature sensor RUF1 is used, the charging pump SLP (CO1 → F22 - 1) is first released to avoid cold charging when the temperature measured at RUF1 has reached the same temperature measured at SF1.

An activated discharging protection function (CO1' → F03 - 1) causes the charging to be stopped when the charging temperature does not reach its set point even though the valve is fully open or it falls below the temperature measured at SF1 and does not rise again. Charging with the valve fully open is stopped after one hour at the latest.

The CO1' → F03 - 1 setting causes a 2 °C higher charging set point to be calculated. The following then applies:

$$\text{Charging set point} = \text{Set point at SF1} + \text{'Charging temperature boost'} + 2 \text{ °C}$$

The 'Stop charging of the buffer tank' parameter (PA1, default = OT) determines under which conditions the charging of the buffer tank is stopped. The automatic adaptation ('OT' setting) causes the buffer tank charging to be stopped when the temperature in the buffer tank reaches the value ('Buffer tank set point' + 'Hysteresis of buffer tank'.

Every other value entered for 'Stop charging of the buffer tank' is rated as a fixed switch-off temperature for the buffer tank charging. When SF2 (CO1 → F06 - 1) is configured, SF2 is always used to stop the charging of the buffer tank.

If the temperature falls below the buffer tank set point at SF1 while the temperature measured at SF2 is still greater than the value in 'Stop charging of the buffer tank', charging is not stopped until the temperature is 3° C lower than the buffer tank set point at SF1.

The storage tank charging pump SLP is not switched off until the lag time (entered 'Valve transit time  $T_V$ ' for RK1 multiplied by the value of 'Lag time of charging pump') has elapsed. The operation of the feeder pump UP1 is either determined by the ZP time schedule or prompted over an external demand. For systems with downstream control circuits, either only this external demand or the demand of the downstream control circuits causes the feeder pump UP1 to be activated, depending on the CO5 → F14 setting.

To switch on the pump UP2 of the solid fuel boiler circuit in systems 16.2 and 16.4, the temperature at VF2 must reach 'Start temperature for boiler pump' + 0.5 °C if the buffer tank (SF1) is cold.

If the temperature at SF1 is already reached, the temperature at VF2 must be greater than the temperature at SF1 + 'Boiler pump hysteresis' + 3 °C to switch on the pump UP2.

The pump UP2 is switched off again when the temperature at VF2 is lower than the temperature at SF1 + 'Boiler pump hysteresis' - 3 °C or it falls below the value of 'Start temperature for boiler pump'.

In systems 16.3, 16.4 and 16.6, a solar circuit is integrated, which uses sensor SF2 for control. The collector circuit pump CP is activated when the temperature at the collector sensor RUF2 is higher than that at the storage tank sensor SF2 by the value entered in 'Solar circuit pump ON'. It is deactivated when the temperature difference falls below the value entered in 'Solar circuit pump OFF', when the temperature at the storage tank sensor SF2 reaches 'Max. storage tank temperature' or when the collector temperature rises above 120 °C.

The temperature-based adaptation of the delivery rate of the charging pump SLP can be implemented using a 0 to 10 V signal. It can be reversed, if required.

**i Note**

*The buffer tank control circuit is deactivated as described in Chapter . When predefined gradients of the heating characteristic (CO1 → F11 - 0) are used, night mode is not possible in the buffer tank control circuit. In contrast to an active four-point characteristic (CO1 → F11 - 1): in this case, a four-point characteristic exists for day and night modes.*

Function	Default	Configuration
Storage tank sensor SF2	1	CO1 → F06 - 1
Speed control of the charging pump	0	CO1 → F21 - 1
	40.0 °C	Start speed reduction SF2 limit: 5.0 to 90.0 °C
	50.0 °C	Stop speed reduction SF2 limit: 5.0 to 90.0 °C
	20.0 °C	Minimum speed: 0 to 50 %
SLP depending on return temperature	0	CO1 → F22 - 1
Discharging protection	0	CO1 → F27 - 1
AA (terminals 11/12) reverse	0	CO5' → F01 - 1
AA (terminals 11/12) PWM	0 %	Zero: 0 to 50 %
	0	CO5' → F10 - 0
		TROVIS 5573 cannot process a PWM signal 7 = SLP speed

## Appendix A (configuration instructions)

Parameters	Default	Parameter level: value range
Minimum set point to charge buffer tank	OT	PA1: OT to 90.0 °C
Stop charging of the buffer tank	OT	PA1: OT to 90.0 °C
Charging temperature boost	6.0 °C	PA1: 0 to 50.0 °C
Lag time of charging pump	1.0	PA1: 0.0 to 10.0
Solar circuit pump ON	10.0 °C	PA4: 1.0 to 30.0 °C
Solar circuit pump OFF	3.0 °C	PA4: 0.0 to 30.0 °C
Max. storage tank temperature	80.0 °C	PA4: 20.0 to 90.0 °C
Start temperature for boiler pump	60.0 °C	PA5: 20.0 to 90.0 °C
Boiler pump hysteresis	5.0 °C	PA5: 0.0 to 30.0 °C

### 16.2.6 Summer mode

Summer mode is activated depending on the mean daytime temperature (measured between 7.00 h and 22.00 h) during the adjusted summer time period.

If the mean daytime temperature exceeds the 'Boost' on the number of successive days set in 'No. days until activation', summer mode is activated on the following day. This means that the valves in all heating circuits are closed and the circulation pumps are switched off after  $t = 2 \times$  valve transit time.

If the mean daytime temperature falls below the 'Outdoor temperature limit for summer mode' on the n number of successive days, summer mode is deactivated on the following day.

Function	Default	Configuration
Summer mode	0	CO5 → F04 - 1
	01.06.	Start date for summer mode: 01.01 to 31.12
	2	No. days until activation (n): 1 to 3
	30.09	End date for summer mode: 01.01 to 31.12
	1	No. days until deactivation (m): 1 to 3
	18.0 °C	Limit: 0.0 to 30.0 °C

#### **i** Note

Summer mode only becomes effective when the controller is in automatic mode (Ⓢ).

### 16.2.7 Delayed outdoor temperature adaptation

The calculated outdoor temperature is used to determine the flow temperature set point. The heating response is delayed when the outdoor temperature either increases or decreases or both. If the outdoor temperature varies by, for example 12 °C within a very short period of time, the calculated outdoor temperature is adapted to the actual outdoor temperature in small steps (delay time of 3 °C per hour) over the following time period:

$$t = \frac{12 \text{ °C}}{3 \text{ °C/h}} = 4 \text{ h}$$

**i Note**

The delayed outdoor temperature adaptation helps avoid unnecessary overloads of central heating stations in combination with either overheated buildings occurring, for example due to warm winds or temporarily insufficient heating due to the outdoor sensor being exposed to direct sunshine.

In the operating level, the outdoor temperature reading blinks on the display while delayed outdoor temperature adaptation is active.

The calculated outdoor temperature is displayed.

Function	Default	Configuration
Delayed outdoor temperature adaptation (decreasing)	0	CO5 → F05 - 1
Delayed outdoor temperature adaptation (increasing)	0 3.0 °C	CO5 → F06 - 1 Delay/h: 0.2 to 6.0 °C

### 16.2.8 Remote operation

Apart from measuring the room temperature, the Type 5257-5 <sup>1)</sup> Room Panel, Type 5257-51 Room Panel (Pt1000) and Type 5244 <sup>1)</sup> Room Panel (PTC) provide the following opportunities of influencing the control process:

Selecting the operating mode:    ☰ Automatic mode  
     ✱ Day mode  
     ◀ Night mode

Set point correction:                During rated operation, the room temperature set point can be increased or reduced by up to 5 °C using a continuously adjustable rotary knob.

With an activated room sensor, the measured room temperature is displayed when the remote operation is connected and activated. Nevertheless, it is not used for control when either the **optimization, adaptation** or **flash adaptation** function is activated.

Function	Default	Configuration
Room sensor RF1/RF2	0	CO1, 2 → F01 - 1

<sup>1)</sup> No longer available

### 16.2.9 Optimization

This function requires the use of a room sensor. Depending on the building characteristics, the heating controller determines and adapts the required advance heating time (maximum 8 hours) to ensure that the desired 'Day set point' (rated room temperature) has been reached in the reference room when the time-of-use starts. During the advance heating period, the controller heats with the max. flow temperature. This temperature is built up in steps of 10 °C. As soon as the 'Day set point' has been reached, outdoor-temperature-compensated control is activated.

Depending on the room sensor, the heating controller switches off the heating system up to one hour before the time-of-use ends. The heating controller chooses the deactivation time such that the room temperature does not drop significantly below the desired value until the time-of-use ends.

## Appendix A (configuration instructions)

During the advance heating period and the premature deactivation of the heating system, the ☼ or ☾ icon blinks on the display.

Outside the times-of-use, the heating controller monitors the 'Night set point' (reduced room temperature). When the temperature falls below the night set point, the controller heats with the max. flow temperature until the measured room temperature exceeds the adjusted value by 1 °C.

### **i Note**

- Direct sunshine can cause the room temperature to increase and thus result in the premature deactivation of the heating system.
- When the room temperature decreases while the heating system is shortly outside its times-of-use, this can prematurely cause the controller to heat up to the 'Day set point'.

Function	Default	Configuration
Room sensor RF1/RF2	0	CO1, 2 → F01 - 1
Outdoor sensor AF1	1	CO1, 2 → F02 - 1
Optimization	0	CO1, 2 → F07 - 1

Parameters	Default	Switch position: value range
Day set point	20.0 °C	☼ 0.0 to 40.0 °C
Night set point	15.0 °C	☾ 0.0 to 40.0 °C

### 16.2.10 Flash adaptation

To ensure that the controller reacts immediately to room temperature deviations during day and night mode, the function block setting CO1, 2 → F09 - 1 needs to be made.

The heating is then always switched off as soon as the room temperature exceeds the 'Day set point' or 'Night set point' by 2 °C.

Heating first starts again when the room has cooled off and the room temperature is 1 °C above the set point. Corrections of the flow temperature set point are released after the 'Cycle time' or 'Gain K<sub>p</sub>' are set to a value ≠ 0. The 'Cycle time' determines the intervals at which the flow temperature set point is corrected by 1 °C. 'Gain K<sub>p</sub>' set to ≠ 0 causes a direct increase/decrease in flow temperature set point when a sudden deviation in room temperature arises. A 'Gain K<sub>p</sub>' setting of around 10.0 is recommended.

### **i Note**

- Cooling loads, such as drafts or open windows, affect the control process.
- Rooms may be temporarily overheated after the cooling load has been eliminated.

Function	Default	Configuration
Room sensor RF1/RF2	0	CO1, 2 → F01 - 1
Flash adaptation	0	CO1, 2 → F09 - 1
	20 min	Cycle time: 0 to 100 min
	0.0	K <sub>p</sub> (gain): 0.0 to 25.0

Parameters	Default	Switch position: value range
Day set point	20.0 °C	☼ 0.0 to 40.0 °C
Night set point	15.0 °C	☾ 0.0 to 40.0 °C

### 16.2.11 Flash adaptation without outdoor sensor (based on room temperature)

The flow temperature control starts with 'Flow set point (day)' in day mode or with 'Flow set point (night)' in night mode as no set points calculated using characteristics exist without an outdoor sensor. The 'Cycle time' determines the intervals at which the flow temperature set point is corrected by 1 °C. The heating is then always switched off as soon as the room temperature exceeds the 'Day set point' or 'Night set point' by 2 °C.

Heating first starts again when the room has cooled off and the room temperature is 1 °C above the set point. A 'Gain  $K_p$ ' set to  $\neq 0$  causes a direct increase/decrease in flow temperature set point when a sudden deviation in room temperature arises. A 'Gain  $K_p$ ' setting of around 10.0 is recommended.

Function	Default	Configuration
Room sensor RF1/RF2	0	CO1, 2 → F01 - 1
Outdoor sensor AF1	1	CO1, 2 → F02 - 0
Flash adaptation	0	CO1, 2 → F09 - 1
	20 min	Cycle time: 1 to 100 min
	0.0	$K_p$ (gain): 0.0 to 25.0

Parameters	Default	Switch position: value range
Day set point	20.0 °C	↔ 0.0 to 40.0 °C
Night set point	15.0 °C	↔ 0.0 to 40.0 °C

Parameters	Default	Parameter level: value range
Flow set point (day)	+50 °C	PA1, 2 → P03: -5.0 to +150.0 °C
Flow set point (night)	+30.0 °C	PA1, 2 → P04: -5.0 to +150.0 °C

### 16.2.12 Adaptation

The heating controller is capable of automatically adapting the heating characteristic to the building characteristics.

A gradient characteristic must be set in this case (CO1, 2 → F11 - 0).

The reference room, where the room sensor is located, represents the entire building and is monitored to ensure that the room temperature set point ('Day set point') is maintained. When the mean measured room temperature in rated operation deviates from the adjusted set point, the heating characteristic is modified accordingly for the following time-of-use.

The corrected value is displayed in PA1, 2 → P01 (Flow gradient).

Function	Default	Configuration
Room sensor RF1/RF2	0	CO1, 2 → F01 - 1
Outdoor sensor AF1	1	CO1, 2 → F02 - 1
Adaptation	0	CO1, 2 → F08 - 1
Four-point characteristic	0	CO1, 2 → F11 - 0

Parameters	Default	Switch position: value range
Day set point	20.0 °C	↔ 0.0 to 40.0 °C
Night set point	15.0 °C	↔ 0.0 to 40.0 °C

**i Note**

If the Flash adaptation function is already configured with a small cycle time, the Adaptation function should not be configured as well.

### 16.2.13 Cooling control

#### Cooling control with outdoor sensor

When the cooling control function is activated in a control circuit with outdoor sensor, the four-point characteristic of the corresponding control circuit is automatically activated and the operating direction of the control output is reversed.

In PA1 and/or PA2 the four points for the course of the set point based on the outdoor temperatures can be adjusted separately for day and night mode.

In PA1, PA2 and/or PA3 the four points for the course of the set point based on the outdoor temperatures can be adjusted separately for day and night mode.

The 'Base point for return temperature' that can be adjusted with an active return sensor determines the point at which a minimum limitation of the return temperature starts:

If the measured return temperature falls below this value, the flow temperature set point is raised. The four return temperature values in the four-point characteristic function have no effect.

Function	Default	Configuration
Outdoor sensor AF1	1	CO1, 2 → F02 - 1
Cooling control	0	CO1, 2 → F04 - 1
Four-point characteristic	0	CO1, 2 → F11 - 1

Parameters	Default	Parameter level: value range	
Outdoor temperature	Point 1	+5.0 °C	PA1, 2 → P05: -50.0 to +50.0 °C
	Point 2	+15.0 °C	
	Point 3	+25.0 °C	
	Point 4	+35.0 °C	
Flow temperature	Point 1	+20.0 °C	PA1, 2 → P05: -5.0 to +150.0 °C
	Point 2	+15.0 °C	
	Point 3	+10.0 °C	
	Point 4	+5.0 °C	
Reduced flow temperature	Point 1	+30.0 °C	PA1, 2 → P05: -5.0 to +150.0 °C
	Point 2	+25.0 °C	
	Point 3	+20.0 °C	
	Point 4	+15.0 °C	
Base point for return temperature	65.0 °C	PA1, 2 → P13: 5.0 to 90.0 °C	

**i Note**

The limiting factors 'K<sub>p</sub>' of the return sensor functions (CO1, 2 → F03) apply during cooling control as well.

#### Cooling control without outdoor sensor

When the cooling control function is activated in a control circuit without outdoor sensor, only the adjustment limits for the day and night set points at the rotary switch as well as the 'Base point for return temperature' can be adjusted in PA1 and/or PA2.

Function	Default	Configuration
Outdoor sensor AF1	1	CO1, 2 → F02 - 0
Cooling control	0	CO1, 2 → F04 - 1

Parameters	Default	Switch position: value range
Day set point	+20.0 °C	↕* -5.0 to +150.0 °C
Night set point	+15.0 °C	↕C -5.0 to +150.0 °C

Parameters	Default	Parameter level: value range
Min. flow temperature	+20.0 °C	PA1, 2: -5.0 to +150.0 °C
Max. flow temperature	70.0 °C	PA1, 2: 5.0 to 150.0 °C
Base point for return temperature	65.0 °C	PA1, 2: 5.0 to 90.0 °C

**i Note**

- The limiting factors 'K<sub>p</sub>' of the return sensor functions (CO1, 2 → F03) apply during cooling control as well.
- The request for a signal by downstream control circuits or externally (when a pre-control circuit is used) is based on the maximum selection.  
Therefore, systems (e.g. system 3.0) or systems in which the demand is requested using a 0 to 10 V signal are not suitable for transmitting the signal for required cooling.
- The 'Set point boost (pre-control circuit)' parameter can only generate higher and not lower set points in the pre-control circuit.

### 16.2.14 Differential temperature control

In systems 1.0 and 16.0, the differential temperature control causes the delivery rate of pump UP1 to be adapted through the 0 to 10 V output depending on the difference between the secondary flow temperature and the secondary return temperature.

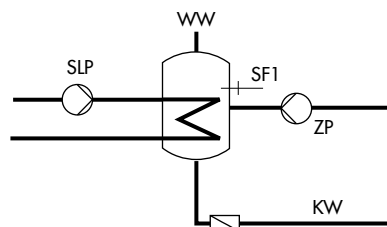
In system 1.0, the sensor input RÜF2 is automatically activated for this purpose with the CO1 → F23 - 1 setting. In system 16.0, the sensor inputs VF2 and RÜF2 are automatically activated. The influence factor K<sub>p</sub> determines how strongly the heating controller responds when the temperature deviates from the set point of the differential temperature control.

Function	Default	Configuration
Differential temperature control	0	CO1 → F23 - 1
	20.0 °C	Set point of differential temperature control: 0.0 to 50.0 °C
	1.0	Influence factor K <sub>p</sub> : 0.1 to 10.0
	20 %	Minimum speed: 0 to 100 %
AA (terminals 11/12) reverse	0	CO5' → F01 - 1
AA (terminals 11/12) PWM	0 %	Zero: 0 to 50 %
	0	CO5' → F10 - 0 (TROVIS 5573 cannot process a PWM signal) Function: Differential temperature control

## 16.3 Functions of the DHW circuit

### 16.3.1 DHW heating in the storage tank system

#### Start storage tank charging



SLP	Storage tank charging pump
SF1	Storage tank sensor
ZP	Circulation pump (DHW)
WW	Hot water
KW	Cold water

Fig. 13: Schematics of a storage tank system

The heating controller begins charging the storage tank when the water temperature measured at storage tank sensor SF1 falls below the 'DHW temperature set point' by 0.1 °C. If the flow temperature in the system exceeds the desired charging temperature, the heating controller tries to reduce the flow temperature in the heating circuit for up to three minutes before the storage tank charging pump is activated. When there is no heating operation or when the flow temperature in the system is lower, the storage tank charging pump is directly switched on.

If CO4 → F15 - 1 (**SLP ON depending on return temperature**) is configured, the primary valve is opened without simultaneously operating the storage tank charging pump. The storage tank charging pump is first switched on when the primary return temperature has reached the temperature currently measured at storage tank sensor SF1. This function enables storage tank charging when the heating system is switched off, e.g. in summer mode, without cooling down the storage tank first by filling it with cold flow water. The storage tank charging pump does not start operation before a sufficiently high temperature has been reached at the heat exchanger.

An activated discharging protection function (CO4' → F03 - 1) causes the charging to be stopped when the charging temperature does not reach its set point even though the valve is fully open or it falls below the temperature measured at SF1 and does not rise again.

Charging with the valve fully open is stopped after one hour at the latest.

#### **i Note**

When a storage tank thermostat is used, the 'Charging temperature' parameter can be adjusted at the rotary switch as the absolute value instead of the 'DHW temperature' parameter.

#### Time-controlled switchover of storage tank sensors

By configuring a second storage tank sensor SF2 (CO4 → F19 - 1), it is possible to determine that the storage tank sensor SF1 is used for day mode in the DHW circuit and storage tank sensor SF2 for night mode.

As a result, different storage tank volumes can be kept at a constant temperature according to a time schedule and also at different temperatures if the 'DHW temperature set point' and 'DHW temperature sustaining value' differ from one another.

#### Stop storage tank charging

The heating controller stops charging the storage tank when the water temperature measured at storage tank sensor SF1 has reached the temperature  $T = \text{'DHW temperature'} + \text{'Hysteresis'}$ . When there is no heating operation or when the flow temperature demand in the system is lower, the corresponding valve is closed. The storage tank charging pump is switched off after  $t = \text{'Lag time of storage tank charging pump'} \times \text{'Valve transit time'}$ .

With the default settings, the temperature in the storage tank is increased by 5 °C to reach 65 °C when the storage tank temperature falls below 60 °C. The charging temperature is calculated from the DHW temperature (60 °C) + 'Charging temperature boost' (10 °C), which equals 70 °C.

When the storage tank has been charged, the heating valve is closed and the charging pump continues to run for the time t. Outside the times-of-use, the storage tank is only charged when the temperature falls below 40 °C ('DHW temperature sustaining value').

In this case, the tank is charged with a charging temperature of 50 °C until 45 °C is reached in the tank.

Function	Default	Configuration
Storage tank sensor SF1	1	CO4 → F01 - 1
Storage tank sensor SF2	0	CO4 → F02 (- 1 when CO4 → F019 - 1)
SLP ON depending on return temperature	0	CO4 → F015
Switchover	0	CO4 → F19 (-1 only when CO4 → F02 - 1)
Discharging protection	0	CO4' → F03 - 1

Parameters	Default	Switch position: value range
DHW temperature set point or charging temperature with CO4 → F01 - 0 setting	60.0 °C	⚡ Min. to max. DHW temperature
DHW temperature sustaining value	40.0 °C	⚡ Min. to max. DHW temperature

Parameters	Default	Parameter level: value range
Min. DHW temperature <sup>1)</sup>	40.0 °C	PA4: 5.0 to 90.0 °C
Max. DHW temperature <sup>1)</sup>	60.0 °C	PA4: 5.0 to 90.0 °C
Hysteresis <sup>2)</sup>	5.0 °C	PA4: 0.0 to 30.0 °C
Charging temperature boost <sup>3)</sup>	10.0 °C	PA4: 1.0 to 50.0 °C
Lag time for storage tank charging pump	1.0 °C	PA4: 0.0 to 10.0

1) Parameters serve as limitation of the adjustment range for the DHW temperature to be set at the rotary switch  
 2) Deactivation value T = DHW temperature + 'Hysteresis'  
 3) Charging temperature T = DHW temperature + 'Charging temperature boost'

### 16.3.1.1 DHW circuit additionally controlled by a globe valve

In systems 7.1, 8.1, 9.1, 9.5, 11.1, 12.1, 13.1 and 21.1, the following versions with globe valve can be configured instead of the three-way valve control in the DHW circuit:

In system 11.1, the following version with globe valve can be configured instead of the three-way valve control in the DHW circuit:

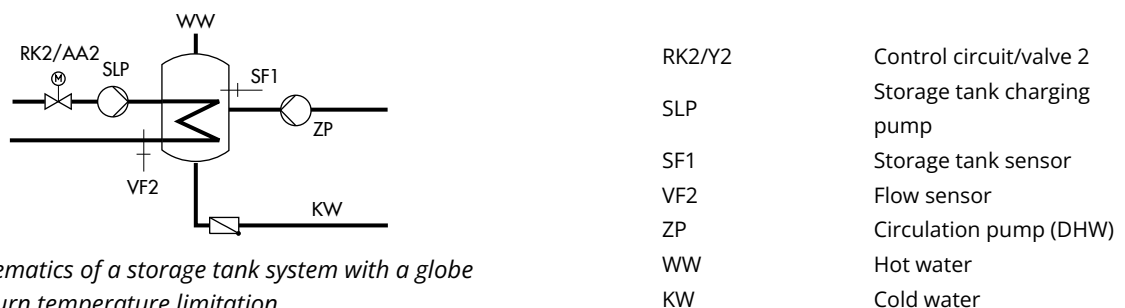


Fig. 14: Schematics of a storage tank system with a globe valve for return temperature limitation

## Appendix A (configuration instructions)

Globe valve and flow sensor VF2 are used exclusively for return temperature limitation in the schematics shown above. The pre-control circuit provides at least the same flow temperature as in the standard hydraulic schematic version, which is calculated from 'DHW temperature set point' + 'Charging temperature boost' + 'Boost set point of pre-control circuit'.

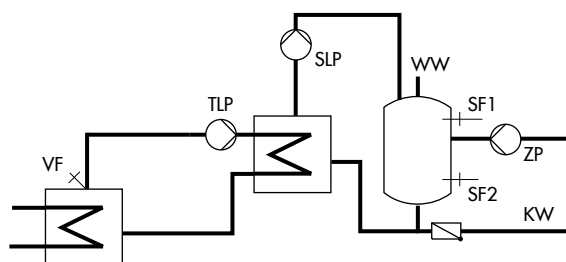
The functions and parameters of the **DHW heating in the storage tank system** are upgraded by the following settings:

Function	Default	Configuration
DHW circuit additionally controlled by a globe valve	0	CO4 → F20 - 1

Parameters	Default	Parameter level: value range
Max. return temperature	65.0 °C	PA4 → P07: 20.0 to 90.0 °C

### 16.3.2 DHW heating in the storage tank charging system

#### Start storage tank charging



**Fig. 15:** Schematics of a storage tank charging system

TLP	Heat exchanger charging pump
VF	Flow sensor
SLP	Storage tank charging pump
SF1	Storage tank sensor
SF2	Storage tank sensor
ZP	Circulation pump (DHW)
WW	Hot water
KW	Cold water

The heating controller begins charging the storage tank when the water temperature measured at storage tank sensor SF1 falls below the 'DHW temperature set point' by 0.1 °C. If the flow temperature in the system exceeds the desired charging temperature, the heating controller tries to reduce the flow temperature in the heating circuit for up to three minutes before the heat exchanger charging pump together with the storage tank charging pump is activated.

When there is no heating operation or when the flow temperature in the system is lower, the heat exchanger charging pump is directly switched on. If the temperature currently measured at storage tank sensor 1 is reached at the flow sensor VF, the storage tank charging pump is switched on.

The CO4' → F03 - 1 setting to activate the discharging protection function causes the charging to be stopped when the charging temperature does not reach its set point even though the valve is fully open or it falls below the temperature measured at SF1 and does not rise again.

Charging with the valve fully open is stopped after one hour at the latest.

If a storage tank thermostat is used, the storage tank charging pump is switched on when the temperature  $T = \text{Charging temperature} - 5 \text{ °C}$  is reached at the flow sensor VF.

#### **i** Note

When a storage tank thermostat is used, the 'Charging temperature' parameter can be adjusted at the rotary switch as the absolute value instead of the 'DHW temperature' parameter.

When the flow sensor VF4 is activated, the set point in the heat exchanger circuit is influenced by the system deviation in the storage tank charging circuit upon activation of the storage tank charging pump: if the temperature measured at flow sensor VF4 is lower than the 'Charging temperature', the set point in the heat exchanger circuit is increased in steps of 1 °C.

When the set point in the heat exchanger charging circuit reaches the 'Max. charging temperature', the set point is no longer increased.

'Err 4' error message is generated.

**i Note**

*The set point in the heat exchanger circuit which is valid at the end of the charging cycle will be used again at the beginning of the next cycle.*

If times-of-use have been programmed for DHW heating, the 'DHW temperature set point' parameter adjusted at the rotary switch is applied during these times-of-use. Outside the times-of-use, the 'DHW temperature sustaining value' parameter is used as the basis.

This function does not apply when a storage tank thermostat is used.

**Time-controlled switchover of storage tank sensors**

By configuring a second storage tank sensor SF2 (CO4 → F19 - 1), it is possible to determine that the storage tank sensor SF1 is used for day mode in the DHW circuit and storage tank sensor SF2 for night mode.

As a result, different storage tank volumes can be kept at a constant temperature according to a time schedule and also at different temperatures if the 'DHW temperature set point' and 'DHW temperature sustaining value' differ from one another.

**Stop storage tank charging**

The heating controller stops charging the storage tank when the water temperature measured at storage tank sensor SF2 has reached the temperature  $T = \text{'DHW temperature'} + \text{'Hysteresis'}$ . To do so, the heat exchanger charging pump is immediately switched off.

When there is no heating operation or when the flow temperature demand in the system is lower, the corresponding valve is closed.

The storage tank charging pump is switched off after  $t = \text{'Lag time of storage tank charging pump'} \times \text{'Valve transit time'}$ .

Function	Default	Configuration
Storage tank sensor SF1		CO4 → F01 - 1
Storage tank sensor SF2		CO4 → F02 - 1
Flow sensor VF4	0	CO4 → F05
Switchover	0	CO4 → F19
Discharging protection	0	CO4' → F03 - 1

## Appendix A (configuration instructions)

Parameters	Default	Parameter level: value range
Min. DHW temperature <sup>1)</sup>	40.0 °C	PA4: 5.0 to 90.0 °C
Max. DHW temperature <sup>1)</sup>	60.0 °C	PA4: 5.0 to 90.0 °C
Hysteresis <sup>2)</sup>	5.0 °C	PA4: 1.0 to 30.0 °C
Charging temperature boost <sup>3)</sup>	10.0 °C	PA4: 0.0 to 50.0 °C
Max. charging temperature	80.0 °C	PA4: 20.0 to 150.0 °C (only with VF4)
Lag time for storage tank charging pump	1.0	PA4: 0.0 to 10.0

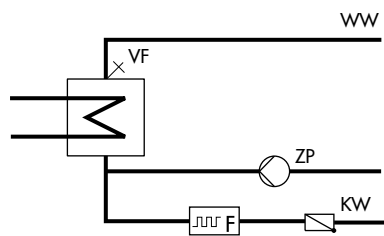
1) Parameters serve as limitation of the adjustment range for the DHW temperature to be set at the rotary switch.  
2) Deactivation value  $T = \text{DHW temperature} + \text{'Hysteresis'}$   
3) Charging temperature  $T = \text{DHW temperature} + \text{'Charging temperature boost'}$

### 16.3.2.1 Cold charging protection

In system 1.1(-1), the **Cold charging protection** function prevents a storage tank charging from starting until the primary flow temperature is sufficiently high enough. The CO4 → F22 - 1 setting automatically activates the FG2 input to measure the primary flow temperature. If the measured primary flow temperature is lower than the measured storage tank temperature (e.g. due to a supply line that has cooled down at the start of a storage tank charging), the heating circuit valve is moved to the adjusted position at first. The storage tank charging is not released in absolute priority operation until the primary flow temperature has risen enough as a result. Parallel operation must be additionally configured if it is required.

Function	Default	Configuration
Cold charging protection	0	CO4 → F22 - 1
	10 %	Valve position: 1 to 100 %
Parallel pump operation	0	CO4 → F06 - 1
	10 min	Stop: 0 to 10 min
	40.0 °C	Temperature limit: 20.0 to 90.0 °C

### 16.3.3 DHW heating in instantaneous heating system



VF	Flow sensor
ZP	Circulation pump (DHW)
WW	Hot water
KW	Cold water

Fig. 16: Schematics of an instantaneous heating system

The control of the required DHW temperature at the flow sensor VF is only active during times-of-use of the circulation pump ZP.

Parameters	Default	Switch position: value range
DHW temperature set point	60.0 °C	↕* Min. to max. DHW temperature
DHW temperature sustaining value	40.0 °C	↕◀ Min. to max. DHW temperature

Parameters	Default	Parameter level: value range
Min. DHW temperature	40.0 °C	PA4: 5.0 to 90.0 °C
Max. DHW temperature	60.0 °C	PA4: 5.0 to 90.0 °C

### 16.3.4 Domestic hot water with solar system

The systems 1.3 and 2.3 are fitted with a solar system for DHW heating.

In these systems, the difference between the temperatures measured at storage sensor SF2 and the sensor at the solar collector VF3 is determined. The 'Solar circuit pump ON' parameter determines the minimum temperature difference between sensors VF3 and SF2 required to activate the solar circuit pump. If the temperature difference falls below the value of 'Solar circuit pump OFF', the solar circuit pump is switched off. Basically, the solar circuit pump is also switched off when either the water temperature measured at storage tank sensor SF2 has reached the 'Max. storage tank temperature' or when the solar collector temperature rises above 120 °C.

**i Note**

The times-of-use of the DHW circuit do not affect the operation of the solar system.

After the key number 1999 has been entered, the operating hours of the solar pump are displayed in extended operating level (see Chapter 8).

Parameters	Default	Parameter level: value range
Solar circuit pump ON	10.0 °C	PA4: 1.0 to 30.0 °C
Solar circuit pump OFF	3.0 °C	PA4: 0.0 to 30.0 °C
Max. storage tank temperature	80.0 °C	PA4: 20.0 to 90.0 °C

### 16.3.5 Intermediate heating

This function can only be activated in systems 2.1 to 2.1, 4.1 and 4.5.

The CO4 → F07 - 1 setting causes the heating operation of the UP1 heating circuit to start again for a period of ten minutes after 20 minutes of priority operation (heating deactivated during DHW heating). The CO4 → F07 - 0 setting is used to give storage tank charging unlimited priority over the heating operation in the UP1 heating circuit.

Function	Default	Configuration
Intermediate heating	1	CO4 → F07 - 1

### 16.3.6 Parallel pump operation

This function can only be activated in systems 2.1 to 2.1, 4.1 and 4.5.

When CO4 → F06 - 1 is configured, the circulation pump UP1 remains activated during DHW heating.

This does not include operating situations during which the current flow temperature demand of the pump circuit is lower than the adjusted 'Temperature limit'. In this case, the controller applies priority operation, if necessary with intermediate heating. Once a parallel pump operation cycle has been activated and the time period set in 'Stop' has elapsed, system deviations greater than 5 °C cause the controller to suspend parallel operation for ten minutes and to apply priority operation.

'Stop parallel pump operation in the event of a system deviation' = 0 min leads to a parallel operation once initiated to continue running, regardless of a system deviation.

Function	Default	Configuration
Parallel pump operation	0	CO4 → F06 - 1
	10 min	Stop parallel pump operation in the event of a system deviation:
	40.0 °C	0 to 10 min Flow temperature limit for parallel operation: 20.0 to 90.0 °C

### 16.3.7 Circulation pump during storage tank charging

The CO4 → F11 - 1 setting causes the circulation pump (DHW) to continue operating according to the programmed time schedule even during storage tank charging. By configuring CO4 → F11 - 0, the circulation pump is switched off as soon as the storage tank charging pump is activated. The circulation pump starts to operate again according to the time schedule when the storage tank charging pump has been switched off again.

Function	Default	Configuration
Circulation pump operation during storage tank charging	0	CO4 → F11

### 16.3.8 Priority circuit

In many district heating systems with primary DHW heating, the allotted amount of water cannot meet DHW heating and heating operation demands when they are required at the same time. As a result, the capacity required for DHW heating needs to be taken from the heating system when great heating loads occur; and this, until DHW demand has been concluded. Nevertheless, heating operation is not to be interrupted simply. Only the amount of energy required for DHW heating is to be deducted. This can be achieved by using the priority functions: 'Reverse control' and 'Set-back operation'.

The priority functions (reverse control and priority operation) can be activated for each heating circuit separately in system 4.5.

	RK1
	RK2
	RK1 and RK2

#### 16.3.8.1 Reverse control

In all systems with DHW heating and at least one heating circuit with a control valve, DHW heating can be given priority by applying reverse control. The CO4 → F08 - 1 setting causes the temperature to be monitored at sensor VFx.

In systems without sensor VFx in the DHW circuit, the temperature is monitored directly at storage tank sensor SF1. If system deviations still occur after the time set in 'Start' has elapsed, the set point of the heating circuit with the control valve is gradually reduced each minute until the flow temperature set point has reached 5 °C at the minimum. How strongly the heating controller responds is determined by  $K_p$ .

When 'Start' is set to 0, the priority operation is started regardless of the time and temperature in the system. The control valves of the corresponding heating circuits are closed.

Examples of systems without sensor VFx in the DHW circuit:

System 4.5 and 11.0

Function	Default	Configuration
Priority through reverse control	0	CO4 → F08 - 1
	2 min	Activate priority in the event of a system deviation
	1.0	$K_p$ (influence factor): 0.1 to 10.0
Priority through set-back operation	HC2	Select control circuit
	0	CO4 → F09 - 0

### 16.3.8.2 Set-back operation

In all systems with DHW heating and at least one heating circuit with a control valve, DHW heating can be given priority by applying set-back operation. The CO4 → F09 - 1 setting causes the temperature to be monitored at sensor VFx in the DHW circuit.

In systems without sensor VFx in the DHW circuit, the temperature is monitored directly at storage tank sensor 1. If system deviations still occur after the time entered in 'Start' has elapsed, the selected heating circuits with the control valve are set to reduced operation. When 'Start' is set to 0, the priority operation is started in all heating circuits regardless of the time and temperature in the system.

Examples of systems without sensor VFx in the DHW circuit:

System 4.5, 11.0, 12.0, 13.0 and 21.0

System 4.5 and 11.0

Function	Default	Configuration
Priority through reverse control	0	CO4 → F08 - 0
Priority through set-back operation	0	CO4 → F09 - 1
	2 min	Activate priority in the event of a system deviation: 0 to 10 min
	HC2	Select control circuit

### 16.3.9 Forced charging of DHW storage tank

To provide the full network performance for room heating when the time-of-use of the heating circuits begins, any storage tanks are charged one hour before the time-of-use of the heating circuits starts. For the individual heating controller, this means that storage tank charging is activated when the water temperature in the storage tank falls below the adjusted deactivation value of  $T = \text{'DHW temperature'} + \text{'Hysteresis'}$ .

#### **i Note**

*This function is not available when a storage tank thermostat is used.*

### 16.3.10 Thermal disinfection of DHW storage tank

In all systems with DHW heating, a thermal disinfection is performed on a selected day of the week or daily.

- In systems with DHW storage tank, it is heated to the adjusted 'Disinfection temperature', taking into account the 'Charging temperature boost' parameter (or 'Set point boost', depending on the system). Disinfection takes place within the adjusted time period ('Time').
- In systems with DHW heating in instantaneous heating system, the function remains active taking into account the 'Set point boost' parameter until the circulation pipe, measured at storage tank sensor SF1, has reached the adjusted 'Disinfection temperature', provided disinfection has not been terminated prematurely after reaching the 'Stop time'.

The 'Disinfection temperature sustaining time' determines how long the disinfection temperature must be maintained within the adjusted time period to rate the process successful. If the 'Disinfection temperature sustaining time' is set to  $\neq 0$ , no intermediate heating operation takes place during thermal disinfection.

When 'Start time' and 'Stop time' are set to an identical time, disinfection is controlled depending on the switching state of the binary input (terminals 03/12) to be performed daily or on the programmed day of the week: disinfection starts optionally with a break contact (BI = 0) or a make contact (BI = 1). The process stops at the latest when the switching state of the binary input next changes.

When the 'Disinfection temperature' has not been reached before the end of the thermal disinfection cycle, it is indicated correspondingly on the display. This error message can also be generated prematurely if the remaining time until the disinfection temperature is reached is shorter than the adjusted 'Duration'. The indication is automatically reset when the disinfection temperature is properly reached during the following thermal disinfection cycle.

Thermal disinfection for preventing legionella infection has the following effect:

- High return temperatures during the disinfection cycle (return temperature limitation suspended)
- High DHW temperatures after thermal disinfection has been concluded
- Possibly lime scale, which can have a negative effect on heat exchanger performance.

**i Note**

*This function is not available when a storage tank thermostat is used.*

**i Note**

*The forced operation of the circulation pump (DHW) starts while thermal disinfection is active.*

Function	Default	Configuration
Storage tank sensor SF1	1	CO4 → F01 - 1
Thermal disinfection	0	CO4 → F14 - 1
Bottom sensor for thermal disinfection	3	Day of the week: 1-7, 1, 2, ..., 7, with 1-7 = daily, 1 = Monday, ..., 7 = Sunday
	00:00	Start time: 00:00 to 23:45 h; in steps of 15 minutes
	04:00	Stop time: 00:00 to 23:45 h; in steps of 15 minutes
	70.0 °C	Disinfection temperature: 60.0 to 90.0 °C
	10.0 °C	Set point boost: 0.0 to 50.0 °C
	0 min	Disinfection temperature sustaining time: 0 to 255 min
	BI = 1	BI = 1, BI = 0 (start of disinfection with terminal 03/12 = ON, OFF; only applies when Start time = Stop time)

## 16.4 System-wide functions

### 16.4.1 Automatic summer/standard time switchover

The time is automatically changed on the last Sunday in March at 2.00 h and on the last Sunday in October at 3.00 h.

Function	Default	Configuration
Summer time	1	CO5 → F08 - 1

#### **i Note**

*The automatic summer/standard time switchover can also be programmed in the Time/date menu (see Chapter 6).*

### 16.4.2 Frost protection

Frost protection measures are taken when the outdoor temperature falls below 'Limit'. The switching differential to cancel the frost protection measures is always 1 °C.

#### **Frost protection program I (restricted frost protection)**

Frost protection measures are taken only when all heating circuits in the system are in stand-by mode. The circulation pumps are automatically switched on and their flow temperature set points are adjusted to 10 °C. The circulation pump in the DHW circuit is automatically switched on only when the stand-by mode has been adjusted at the rotary switch in all heating circuits. Nevertheless, the storage tank is always recharged to 10 °C if the storage tank temperature falls below 5 °C.

#### **Frost protection program II**

The heating circuit circulation pumps are always switched on automatically. The flow temperature set points of all heating circuits currently in stand-by mode are set to +10 °C. In the DHW circuit, the circulation pump is always activated. If the storage tank temperature falls below +5 °C, the storage tank is recharged to +10 °C.

Function	Default	Configuration
Frost protection program I	+3.0 °C	CO5 → F09 - 0 Frost protection limit: -15 to +3.0 °C
Frost protection program II	+3.0 °C	CO5 → F09 - 1 Frost protection limit: -15 to +3.0 °C

#### **i Note**

*Frost protection operation of a pump, a heating circuit or the DHW circuit is only active when the ❄ frost protection icon is displayed.*

*In the stand-by mode (⊖) fixed set point control without outdoor temperature sensor does not include frost protection.*

### 16.4.3 Forced pump operation

When the heating circuit pumps have not been activated for 24 hours, forced operation of the pumps is started between 12.02 h and 12.03 h. This is done to avoid that the pumps get stuck when they are not operated for long periods of time. In the DHW circuit, the circulation pump is operated between 12.04 h and 12.05 h, the other pumps between 12.05 h and 12.06 h.

### 16.4.4 Return temperature limitation

The temperature difference between the flow and return in a network indicates how well the energy is used: the greater the difference, the higher the efficiency. A return sensor is sufficient to evaluate the temperature difference when the flow temperatures are predefined. The return temperature can be limited either to a value depending on the outdoor temperature (variable) or to a fixed set point. When the temperature measured at return sensor RüF exceeds the current return temperature limit, the set point of the flow temperature (flow temperature of the heating system, charging temperature) is reduced. This causes the primary flow rate to be reduced and the return temperature to drop.

System 2.x and 4.1

The 'KP (limiting factor)' determines how strongly the heating controller responds when the limit values are exceeded in either direction (PI algorithm).

If just the proportional component is to be implemented, configure CO5 → F16 - 1. This allows the integral-action component in the return temperature limitation algorithm of all control circuits of the heating controller to be deactivated. The set point reading (flow temperature of the heating, charging temperature) of the control circuit concerned blinks to indicate that a return temperature limitation is active.

#### **i Note**

*When outdoor-temperature-compensated control with gradient characteristic is used, the return temperature is limited to a fixed value by equating the 'Base point for return temperature' and 'Max. return temperature' (PA1, 2#) parameters.*

Function	Default	Configuration
Return sensor RüF1/2	1	CO1, 2, 4 → F03 - 1
	1.0	K <sub>p</sub> (limiting factor): 0.1 to 10.0
Return temperature limitation with P algorithm <sup>1)</sup>	0	CO5 → F16
1) If the heating controller indicates CO5 → F00 - 1, any access to the return, flow rate and capacity settings is locked.		

Parameters	Default	Parameter level: value range
Return gradient	1.2	PA1, 2: 0.2 to 3.2
Return level	0.0 °C	PA1, 2: -30.0 to 30.0 °C
Base point for return temperature	65.0 °C	PA1, 2: 5.0 to 90.0 °C
Max. return temperature	65.0 °C	PA1, 2: 5.0 to 90.0 °C

or:

Parameters	Default	Parameter level: value range
Return temperature, points 1 to 4	65.0 °C	PA1, 2: 5.0 to 90.0 °C

**i Note**

To ensure the entered return temperature limit can be kept, observe the following:

- ⇒ Do not adjust the heating characteristic to ascend too steeply.
- ⇒ The speed of the circulation pumps is not set too high.
- ⇒ The heating systems have been balanced.

### 16.4.5 Condensate accumulation control

The heating controller response to set point deviations which cause the primary valve to open is attenuated. The heating controller response to set point deviations which cause the control valve to close remains unaffected.

**i Note**

The Condensate accumulation control function can only be activated when the control circuit concerned is controlled using a PI algorithm (three-step control).

Function	Default	Configuration
Control mode	1	CO1, 2, 4 → F12 - 1
Limitation of system deviation for OPEN signal	0 3.0 °C	CO1, 2, 4 → F13 - 1 Max. system deviation: 3.0 to 10.0 °C

### 16.4.6 Three-step control

The flow temperature can be controlled using a PI algorithm. The valve reacts to pulses that the heating controller sends when a system deviation occurs. The length of the first pulse, in particular, depends on the extent of the system deviation and the selected 'K<sub>p</sub> (gain)' (the pulse length increases as K<sub>p</sub> increases). The pulse and pause lengths change continuously until the system deviation has been eliminated.

The pause length between the single pulses is greatly influenced by 'Reset time T<sub>n</sub>' (the pause length increases as T<sub>n</sub> increases). The 'Valve transit time T<sub>v</sub>' specifies the time required by the valve to travel through the range of 0 to 100 %.

Function	Default	Configuration
Control mode	1	CO1, 2, 3, 4, 11, 12, 13 → F12 - 1
	2.0	K <sub>p</sub> (gain): 0.1 to 50.0
	120 s	T <sub>n</sub> (reset time): 1 to 999 s
	0 s	T <sub>v</sub> (derivative-action time): <b>Do not change the value.</b>
	35 s	T <sub>v</sub> (valve transit time): 15, 20, 25, ..., 240 s

### 16.4.7 On/off control

The flow temperature can be controlled, for example by activating and deactivating a boiler. The heating controller switches on the boiler when the flow temperature falls below the set point by  $T = 0.5 \times \text{'Hysteresis'}$ . When the set point is exceeded by  $T = 0.5 \times \text{'Hysteresis'}$ , the boiler is switched off again. The greater the value for 'Hysteresis', the less frequent switching on and off will be. By entering the 'Minimum ON time', an activated boiler remains switched on during this period regardless of the flow temperature fluctuations. Similarly, a deactivated boiler remains switched off regardless of the flow temperature fluctuations if the 'Min. OFF time' has been specified.

Function	Default	Configuration
Control mode	1	CO1, 2, 4 → F12 - 0
	5.0 °C	Hysteresis: 1.0 to 30.0 °C
	2 min	Min. ON time: 0 to 10 min
	2 min	Min. OFF time: 0 to 10 min

### 16.4.8 Continuous control in control circuit RK1

The flow temperature in the control circuit RK1 can be controlled using a PID algorithm. The valve receives an analog 0 to 10 V signal from the heating controller. When a system deviation occurs, the 'Proportional-action coefficient  $K_p$ ' immediately causes the 0 to 10 V signal to change (the greater the  $K_p$ , the greater the change). The integral component becomes effective with time: 'Reset time  $T_n$ ' represents the time which elapses until the integral component has changed the output signal to the same extent as the immediate change performed by the proportional component (the greater  $T_n$  is, the slower the rate of change will be). Due to the derivative component, any change of the system deviation is incorporated into the output signal with a certain gain (the greater the derivative-action time  $T_v$  is, the stronger the change will be).

Function	Default	Configuration
Control mode	1	CO1 → F12 - 1
	2.0	$K_p$ (gain): 0.1 to 50.0
	120 s	$T_n$ (reset time): 1 to 999 s
	0 s	$T_v$ (derivative-action time): 0 to 999 s
	35 s	$T_y$ (valve transit time): 15, 20, 25, ..., 240 s

### 16.4.9 Releasing a control circuit/heating controller with binary input

The release of an individual control circuit or the heating controller with the binary input only becomes effective when the respective control circuit is in automatic mode (⊙ icon). The released control circuit always works in automatic mode; the deactivated control circuit behaves as if it were transferred to stand-by mode. It remains active, however, in any case for processing an external demand. The control circuit can be released over the binary input when the binary input is either a make contact ('Active when binary input (BE)' = OFF) or a break contact ('when binary input (BE)' = ON).

**i Note**

- In systems with downstream heating circuit without a valve (systems 2.x, 4.x), the binary input BE1 only influences the operation of this heating circuit when 'Release control circuit' is configured, whereas the operation of the entire heating controller (including the control circuits of the connected TROVIS I/O expansion modules; excluding the processing of external demand) is influenced when 'Release controller' is configured.
- In system 3.0, the binary input BE15 influences the operation of the entire heating controller (except for processing an external demand) when 'Release control circuit' is configured.
- In buffer tank systems 15.x and 16.x, the binary input BE15 influences only the operation of the buffer tank charging circuit when 'Release control circuit' is configured.

Function	Default	Configuration
Release	0	CO1, 2, 3 → F14 - 1
Release controller	0	CO5 → F15 - 1
1) Active when BI = ON, OFF		

### 16.4.10 Speed control of the charging pump

This function allows the delivery rate of the charging pump in systems with buffer tank (CO1 → F21 - 1) and in systems with DHW storage tank (CO4 → F21 - 1) to be varied based on the temperature. When this function is activated, the input SF2 is automatically activated. In combination with the CO1 → F06 - 0 or CO4 → F02 - 0 setting, this input is only used for speed control and not to stop the storage tank charging.

All storage tank charging actions start with the minimum delivery rate of the charging pumps. As soon as the charging temperature is nearly reached, the delivery rate of the charging pump is increased and the valve controls the flow rate. If the charging temperature drops 5 °C below its associated set point, the delivery rate is reduced again.

At the latest when the temperature at the sensor SF2 for speed control has reached the 'Start' value to reduce the delivery rate, the linear reduction of the delivery rate based on the temperature at the sensor SF2 for speed control starts. If the temperature at the sensor SF2 for speed control reaches the 'Stop' value to reduce the delivery rate, the charging pump runs again at the minimum delivery rate. Following the lag time, the charging pump is deactivated when the storage tank is fully charged.

Function	Default	Configuration
Speed control of the charging pump	0	CO1 → F21 - 1 or CO4 → F21 - 1
	40.0 °C	Start speed reduction, limit: 5.0 to 90.0 °C
	50.0 °C	Stop speed reduction - SF2 limit: 5.0 to 90.0 °C
	20 %	Minimum speed: 0 to 50 %
AA (terminals 11/12) reverse	0	CO5' → F01 - 1
	0 %	Zero: 0 to 50 %
AA (terminals 11/12) PWM	0	CO5' → F10 - 0

### 16.4.11 Processing an external demand

The heating controller can process binary or analog requests for an externally required signal by a more complex secondary system.

A binary request can only be processed when the input SF2 or RF2 is not assigned.

#### NOTICE

#### **Risk of damage of the heating circuit through overheating.**

*Overheating may occur in the heating circuits of the primary controller without control valve.*

Excessive charging temperatures in DHW circuits without control valve controlled by the primary controller are excluded when the default settings of the heating controller are used: while storage tank charging is active, no flow temperature higher than the charging temperature is used by the primary controller.

If the **Priority for external demand** function is activated, the external demand is also processed during storage tank charging.

The heating circuits can be configured in such a way that they only process external demand. The possible settings for each heating circuit do not apply with this configuration as only the external demand is processed with associated UP as feeder pump.

Function	Default	Configuration
Priority for external demand	0	CO4 → F16 - 1
Demand only	0	CO1' → F00 - 1
	0	CO2' → F00 - 1

#### Binary demand processing

Regardless of the operating mode set for control circuit RK1, except for manual mode, the controller regulates the flow temperature when either the binary input (terminals 03/12) is a make contact (BI = 0) or a break contact (BI = 1) in control circuit RK1 to at least the adjusted flow temperature adjusted in 'Set point for binary demand processing'.

Regardless of the operating mode set for control circuit, except for manual mode, the controller regulates the flow temperature in the heating circuit concerned when either the binary input (terminals 17/18) is a make contact ('Active when binary input' = OFF) or a break contact ('Active when binary input' = ON) in control circuit RK1 to at least the adjusted flow temperature adjusted in PA1 → P10 ('Minimum flow temperature set point HC for binary demand processing').

Function	Default	Configuration
Demand processing, 0 to 10 V	0	CO1, 2 → F16 - 0
Binary demand processing	0	CO1 → F17 - 1
	BI = 1	BI = 1, BI = 0

Parameters	Default	Parameter level: value range
Set point for binary demand processing	40.0 °C	PA1: 5.0 to 150.0 °C

#### Demand processing, 0 to 10 V

Regardless of the operating mode set for the control circuit concerned (except for manual mode), the controller regulates the flow temperature at least to the temperature corresponding with the 0 to 10 V signal connected to terminals 11/12.

Function	Default	Configuration
Demand processing, 0 to 10 V	0	CO1, 2 → F16 - 1
AE zero shift	0	CO5' → F07 - 0
	0 °C	Lower transmission range: 0 to 150 °C
	120 °C	Upper transmission range: 0 to 150 °C
	0	CO5' → F07 - 1
	5 %	CO5 → F31 - 1
	0 °C	Zero: 5 to 20 %
	120 °C	Lower transmission range: 0 to 150 °C
		Upper transmission range: 0 to 150 °C
Binary demand processing	0	CO1 → F17 - 0

### 16.4.12 External demand using a 0 to 10 V signal

The heating controller can request a demand for the maximum flow set point (with boost, if need be) by issuing an analog 0 to 10 V signal for external demand.

For this purpose, the 0 to 10 V output is used as an alternative to issuing the control signal.

Analog, binary signals or requests processed over the device bus are integrated into the analog request for an external demand.

Function	Default	Configuration
External demand	0	CO1 → F18 - 1
	0.0 °C	Lower range value: 0.0 to 150.0 °C
	120.0 °C	Upper range value: 0.0 to 150.0 °C
	0.0 °C	Boost: 0.0 to 30.0 °C
AA (terminals 11/12) PWM	0	CO5' → F10 - 0
		Function: 6 = External demand

### 16.4.13 Creep feed rate limitation with a binary input

It is possible to report to the heating controller when the creep feed rate has fallen below a certain level by using a limit switch of the primary valve connected to the terminals 04/12 or to RÜF1. Either the break contact (BI = 0) or break contact (BI = 1) at the binary input can be configured at terminals 04/12 to indicate that the creep feed rate has fallen below a certain level.

Only the binary input as make contact at RÜF1 can be processed. Shortly after the alert, the heating controller closes the valve RK1. As soon as the flow temperature falls below the set point by more than 5 °C after the valve has been closed, control operation is started again.

Function	Default	Configuration
Creep feed rate limitation	0	CO5 → F12 - 1
	bin	bin (terminals 04/12), AnA (RÜF1)
	BI = 1	When 'bin' is selected: BI = 0, BI = 1

### 16.4.14 Connecting potentiometers for valve position input

The FG1 and FG2 inputs can be used to connect potentiometers (e.g. to input valve positions) when a resistance room sensor is not configured in the control circuit concerned.

The measured values in the range from 0 to 2000  $\Omega$  are not shown on the display of the heating controller. They are only available as Modbus data points.

Function	Default	Configuration
Room sensor RF1, 2	0	CO1, 2 → F01 - 0

### 16.4.15 Locking manual level

To protect the heating system, this function can be used to lock the manual level. When this function has been activated, automatic mode is started when the rotary switch is set to in automatic mode.

Function	Default	Configuration
Lock manual level	0	CO5 → F21 - 1

### 16.4.16 Locking the rotary switch

When this function has been activated, the heating controller remains in automatic mode regardless of the rotary switch position. The rotary switch can no longer be used to adjust the controller settings.

It is still possible to enter the key number.

Function	Default	Configuration
Lock rotary switch	0	CO5 → F22 - 1

### 16.4.17 Feeder pump operation

In system 3.0, the feeder pump UP1 only starts to operate in the default setting when a flow temperature demand of a secondary controller exists:

If CO5 → F14 - 1 is configured, this is also the case when the control circuit RK2 requires heat.

Function	Default	Configuration
Operation UP1	0	CO5 → F14 - 1

### 16.4.18 External demand for heat due to insufficient heat supply

An external heat source can be demanded using the 0 to 10 V output. The CO1 → F18 - 1 function block for a request for external demand is automatically set. The function block parameters allow the transmission range to be determined. When a system deviation in RK1 greater than 10 °C lasts longer than 30 minutes, a voltage signal corresponding to the actual demand is generated. At the same time, the RK1 valve is forced to close.

The RK1 valve icon blinks to indicate that the operating situation has changed as long as the external heat source is released.

After 30 minutes, the external demand for heat is canceled and the control signal output in RK1 is enabled again.

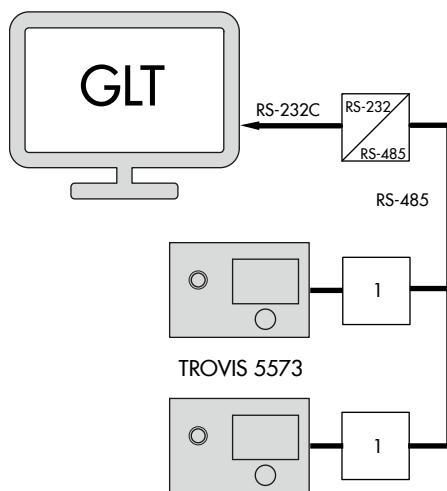
Function	Default	Configuration
Demand for external heat	0	CO1 → F20 - 1
External demand	0	CO1 → F18 - 1
	0.0 °C	Lower range value: 0.0 to 150 °C
	120.0 °C	Upper range value: 0.0 to 150 °C
	0.0 °C	Boost: 0.0 to 30 °C
AA (terminals 11/12) PWM	0	CO5' → F10 - 0
		Function: 6 = External demand

## 16.5 Communication

The TROVIS 5573 Heating and District Heating Controller can communicate with a control system using the optional RS-485 communication module (Modbus RTU interface for two-wire bus networks). In combination with a suitable software for process visualization and communication, a complete control system can be implemented.

### **i Note**

The operating software can be updated over a data cable, provided Modbus has been activated (CO6 → F01 - 1).



**Fig. 17:** Network structure

1 Optional RS-485 communication module

### 16.5.1 RS-485 communication module

When looking onto the controller front, the connection for the optional RS-485 communication module is located on the left side of the controller housing (RJ-45 port).

The bus line links the control units/devices in an open ring. At the end of the bus line, the data cable is connected to the control station using an RS-485 to RS-232 converter (e.g. #CoRe02).

The maximum range of the bus connection (cable length) is 1200 meters. For greater distances, repeaters (e.g. CoRe02) must be used to regenerate the signal level. A maximum of 246 devices with 8-bit addressing can be connected to a bus.

If no communication is established between the control system and controller, the time of access by the control system can be restricted to dynamic process by the **monitoring** function. The controller resets the monitoring function, provided the valid Modbus requests are registered. However, in case of an error, all level bits are initialized back to "autonomous" after 30 minutes have elapsed.

### **NOTICE**

**Risk of damage of the heating circuit due to lightning or overvoltage.**

⇒ Upon installation, observe the relevant standards and regulations governing lightning and overvoltage protection.

Function	Default	Configuration
Modbus	1	CO6 → F01 - 1
16-bit address	0	CO6 → F02
Monitoring	0	CO6 → F07

Parameters	Default	Parameter level: value range
Station address (ST)	255	PA6: 1 to 247 When CO6 → F02 - 1: 1 to 32000

### Description of communication parameter settings

- Station address (ST)  
This address is used to identify the heating controller in bus or modem mode.  
In a system, each controller needs to be assigned a unique address.

## 16.5.2 Memory module/mini module

The use of a memory module or mini module (see Chapter 17.1) is particularly useful to transfer all data from one TROVIS 5573 Heating Controller to several other TROVIS 5573 Heating Controllers.

### **i** Note

*In contrast to the memory module, the mini module is not suitable for transferring the programmed vacations to the individual control circuits or a data logging configuration programmed in TROVIS-VIEW.*

The memory module/mini module is plugged into the RJ-45 connector socket located at the side of the controller.

Once the module has been connected, '73 SP' appears on the controller display.

If the memory module already contains data from a different TROVIS 5573 Controller, turn the rotary pushbutton until 'SP 73' is displayed.

- Pressing the rotary pushbutton to confirm '73 SP' causes the controller settings to be transferred to the memory module/mini module.
- Pressing the rotary pushbutton to confirm 'SP 73' causes the controller settings to be transferred from the memory module/mini module.

While the data is being exchanged, bars run across the display. When the transfer is completed, 'I.O.' is displayed. After that, the connection between controller and memory module/mini module can be terminated.

TROVIS-VIEW allows users to configure all controller settings on a convenient user interface at the computer and to document these settings.

The controller starts to write over the oldest data as soon the memory of the data logging module is full after approximately eight days.

The current memory capacity of the data logging module can be read in the extended operating level under 'InFo 2' as the second value in the sequence (range of values: 0 to 6035).

Directly after inserting the data logging module, data can be first read after the first scanning cycle has been performed.

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**i Note**

*The internal memory of the controller is full after approx. 14 days. After that, the controller starts to write over the oldest data.*

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The data log viewer software allows the data to be viewed in graph format. The USB converter 3 (see 17) is required to connect the data logging module to a computer. The data log viewer software is supplied together with the USB converter 3.

### 16.5.3 Data logging

A data logging module (see Chapter 17) saves the following controller data every two minutes:

- Temperatures measured by the sensors
- Control signals in %
- Switching states of the pump outputs

The data logging module is plugged into the RJ-45 connector socket located at the side of the controller. The controller starts to write over the oldest data as soon the memory of the data logging module is full after approximately eight days. The current memory capacity of the data logging module can be read in the extended operating level under 'InFo 2' as the second value in the sequence (range of values: 0 to 6035). Directly after inserting the data logging module, data can be first read after the first scanning cycle has been performed. The data log viewer software allows the data to be viewed in graph format. The USB converter 3 (see Chapter 17) is required to connect the data logging module to a computer. The data log viewer software is supplied together with the USB converter 3.

## 16.6 Function block lists

### CO1: RK1 - Heating circuit 1

F	Function	De- fault	Systems	Comments Function block parameters: value range (default setting)
01	Room sensor RF1	0	Not systems 1.5, 1.6, 3.x, 16.x	CO1 → F01 - 1: Room sensor RF1 Temperature reading and FG1 input for Type 5244, 5257-5 or 5257-51 Room Panel active
02	Outdoor sensor	0	1.5, 1.6	CO1 → F02 - 1: Outdoor sensor AF1 Outdoor-temperature-compensated control active
		1	Not systems 1.5, 1.6	
03	Return sensor RüF1	0	1.2	CO1 → F03 - 1: Return sensor RüF1; limitation function active <b>Function block parameters</b> K <sub>p</sub> (limiting factor): 0.1 to 10.0 (1.0)
		1	Not system 1.2	
04	Cooling control	0	Not system 1.9	CO1 → F04 - 1: Cooling control (only when CO1 → F11 - 1) The cooling control function causes a reversal of the operating direction and a minimum limitation of the return temperature in RK1.
05	Underfloor heating	0	Not systems 1.5, 1.6, 3.x, 16.x	CO1 → F05 - 1: Underfloor heating/drying of jointless floors <b>Function block parameters</b> Boost: 0.0 to 50.0 °C (0.0 °C) Start temperature: 20.0 to 60.0 °C (25 °C) Hold (days): 0 to 10 days (0 days) Temp. rise/day: 0.0 to 20.0 °C (5.0 °C) Maximum temperature: 25.0 to 60.0 °C (45.0 °C) Hold (days): 0 to 30 days (4 days) Temp. reduction/day: 0.0 to 20.0 °C (0.0 °C) STOP, ■START, ■■START, ■■■START, ■■■■START
06	Storage tank sensor SF2	1	System 16.x only	CO1 → F06 - 1: Activate SF2 to switch off charging of the buffer tank
07	Optimization	0	Not systems 1.5, 1.6, 3.x, 16.x	CO1 → F07 - 1: Optimization of heating times (only when CO1 → F01 - 1 and CO1 → F02 - 1)
08	Adaptation	0		CO1 → F08 - 1: Heating characteristic adaptation (only when CO1 → F01 - 1, CO1 → F02 - 1 and CO1 → F11 - 0)
09	Flash adaptation	0		CO1 → F09 - 1: Flash adaptation of flow temperature (only when CO1 → F01 - 1) <b>Function block parameters</b> Cycle time: 0 or 1 to 100 min (20 min) K <sub>p</sub> (gain): 0.0 to 25.0 (0.0)
11	Four-point characteristic	0	Not systems 1.5, 1.6	CO1 → F11 - 1: Four-point characteristic (only when CO1 → F08 - 0) CO1 → F11 - 0: Gradient characteristic
12	Three-step control mode	1	Not system 1.9	CO1 → F12 - 1: Three-step control <b>Function block parameters</b> K <sub>p</sub> (gain): 0.1 to 50.0 (2.0) T <sub>n</sub> (reset time): 1 to 999 s (120 s) T <sub>v</sub> (derivative-action time): 0 to 999 s (0 s) T <sub>v</sub> (valve transit time): 15, 20, 25, ..., 240 s (35 s)  CO1 → F12 - 0: On/off control <b>Function block parameters</b> Hysteresis: 1.0 to 30.0 °C (5.0 °C) Min. ON time: 0 to 10 min (2 min) Min. OFF time: 0 to 10 min (2 min)

F	Function	De- fault	Systems	Comments Function block parameters: value range (default setting)
13	Limitation of system deviation for OPEN signal	0	Not system 1.9	CO1 → F13 - 1: (only when CO1 → F12 - 1) <b>Function block parameters</b> Max. system deviation: 3.0 to 10.0 °C (3.0 °C)
14	Release	0	Not system 1.9	CO1 → F14 - 1: Release RK1 at BE1; FG1 has no function. <b>Function block parameters</b> Select: BI = 1, BI = 0 (BI = 1)
16	Demand processing, 0 to 10 V To terminals 11/12	0	Not system 1.9	CO1 → F16 - 1: Demand processing, 0 to 10 V (only when CO1 → F17 - 0) The standardized signal output (terminals 11/12) is not available anymore as a control output.
17	Binary demand processing To terminals 03/12	0	Not for systems with SF2/RF2	CO1 → F17 - 1: Binary demand processing (only when CO1 → F16 - 0) <b>Select:</b> BI = 1, BI = 0 (BI = 1) <b>Function block parameters</b>
18	Request max. flow set point using 0 to 10 V Output terminals 11/12	0	Not system 1.9	CO1 → F18 - 1: The standardized signal output (terminals 11/12) is not available anymore as a control output. The maximum flow set point (with boost, if applicable) is demanded as a 0 to 10 V signal at the standardized signal output. <b>Function block parameters</b> Lower transmission range: 0.0 to 150.0 °C (0.0 °C) Upper transmission range: 0.0 to 150.0 °C (120.0 °C) Boost flow temperature demand: 0.0 to 30.0 °C (0.0 °C)
20	Demand for external heat	0	All	CO1 → F20 - 1: External demand for heat due to insufficient heat supply
21	Speed control of the charging pump	0	16.x	CO1 → F21 - 1: Temperature-based adaptation of the delivery rate of the charging pump <b>Function block parameters</b> Start speed reduction - SF2 limit: 5.0 to 90.0 °C (40.0 °C) Stop speed reduction - SF2 limit: 5.0 to 90.0 °C (50.0 °C) Minimum speed: 0 to 50 % (20 %)
22	SLP depending on return temperature	0	16.x	CO1 → F22 - 1: Storage tank charging pump not ON unless return hot
23	Differential temperature control	0	1.0, 16.0	CO1 → F23 - 1: Activation of differential temperature control <b>Function block parameters</b> Set point of differential temperature control: 0.0 to 50.0 °C (20.0 °C) Influence factor K <sub>p</sub> : 0.1 to 10.0 (1.0) Minimum speed: 0 to 100 % (20 %)

F: Function block number, WE: Default setting, Anl: System code number

### CO1': RK1 - Heating circuit 1

F	Function	De- fault	Systems	Comments Function block parameters: value range (default setting)
00	Demand only	0	Not system 1.9	CO1' → F00 - 1: RK1 works as a feeder circuit. RK1 only processes external demand for heating; UP1 runs depending on demand.

## Appendix A (configuration instructions)

F	Function	De- fault	Systems	Comments Function block parameters: value range (default setting)
03	Discharging protection	0	16.x	CO1' → F03 - 1: Discharging protection active
04	Variable night set-back	0	1.5, 1.6, 3.x, 16.x	CO1' → F04 - 1: Variable night set-back (only when CO1 → F11 - 0) <b>Function block parameters</b> OTL night 100 %: -50 to +20.0 °C (+5.0 °C) OTL day 0 %: -50 to +5.0 °C (-15.0 °C)

F: Function block number, WE: Default setting, AnI: System code number

### CO2: RK2 - Heating circuit 2

F	Function	De- fault	Systems	Comments Function block parameters: value range (default setting)
01	Room sensor	0	3.x, 4.x, 10.0, 16.6	CO2 → F01 - 1: Room sensor RF2, temperature reading and FG2 input for Types 5244, 5257-5 and 5257-51 Room Panels active
02	Outdoor sensor	1		CO2 → F02 - 1: With outdoor sensor AF1; Outdoor-temperature-compensated control active
03	Return sensor	0	3.0, 4.x, 16.6	CO2 → F03 - 1: Return sensor RüF2; limitation function active
		1	10.x	
04	Cooling control	0	3.x, 4.x, 10.0, 16.6	CO2 → F04 - 1: Cooling control The cooling control function causes a reversal of the operating direction and a minimum limitation of the return temperature in RK2.
05	Underfloor heating/drying of jointless floors	0	3.x, 4.x, 10.0, 16.6	CO2 → F05 - 1: Underfloor heating/drying of jointless floors <b>Function block parameters</b> Boost: 0.0 to 50.0 °C (0.0 °C) Start temperature: 20 to 60 °C (25 °C) Hold (days): 0 to 10 days (0 days) Temp. rise/day: 0.0 to 20.0 °C (5.0 °C) Maximum temperature: 25.0 to 60.0 °C (45.0 °C) Hold (days): 0 to 30 days (4 days) Temp. reduction/day: 0.0 to 20.0 °C (0.0 °C) SToP, ■ STArT, ■■ STArT, ■■■ STArT, ■■■■ STArT
07	Optimization	0	3.x, 4.x, 10.0, 16.6	CO2 → F07 - 1: Optimization of heating times (only when CO2 → F01 - 1 and CO1 → F02 - 1)
08	Adaptation	0		CO2 → F08 - 1: Heating characteristic adaptation (only when CO2 → F01 - 1, CO1 → F02 - 1 and CO2 → F11 - 0)
09	Flash adaptation	0		CO2 → F09 - 1: Flash adaptation of flow temperature (only when CO2 → F01 - 1) <b>Function block parameters</b> Cycle time: 0 or 1 to 100 min (20 min) K <sub>p</sub> (gain): 0.0 to 25.0 (0.0)
11	Four-point characteristic	0	Not system 3.5, 10.5, 25.5	CO2 → F11 - 1: Four-point characteristic (only when CO2 → F08 - 0) CO2 → F11 - 0: Gradient characteristic

F	Function	De- fault	Systems	Comments Function block parameters: value range (default setting)
12	Control mode	1	3.x, 4.x, 10.0, 16.6	CO2 → F12 - 1: Three-step control <b>Function block parameters</b> K <sub>p</sub> (gain): 0.1 to 50.0 (2.0) T <sub>n</sub> (reset time): 1 to 999 s (120 s) T <sub>v</sub> TV (derivative-action time): 0 to 999 s (0 s, do not change the value) T <sub>v</sub> (valve transit time): 15, 20, 25, ..., 240 s (35 s)  CO2 → F12 - 0: On/off control <b>Function block parameters</b> Hysteresis: 1.0 to 30.0 °C (5.0 °C) Min. ON time: 0 to 10 min (2 min) Min. OFF time: 0 to 10 min (2 min)
13	Limitation of system deviation for OPEN signal	0		CO2 → F13 - 1: OPEN signal damping (only when CO2 → F12 - 1) <b>Function block parameters</b> Max. system deviation: 3.0 to 10.0 °C (3.0 °C)
14	Release	0		CO2 → F14 - 1: Release RK2 at BE2; FG2 has no function.
16	Demand processing 0 to 10 V	0	3.x, 4.x, 10.0, 16.6	CO2 → F16 - 1: Demand processing in RK2 at terminals 11/12

F: Function block number, WE: Default setting, Anl: System code number

#### CO2': RK2 - Heating circuit 2

F	Function	De- fault	Systems	Comments Function block parameters: value range (default setting)
00	Demand only	0	3.x, 4.x, 10.0, 16.6	CO2' → F00 - 1: RK2 works as a feeder circuit. RK2 only processes external demand for heating; UP1 runs depending on demand.
04	Variable night set-back	0	Not 3.5	CO2' → F04 - 1: Variable night set-back (only when CO2 → F11 - 0) <b>Function block parameters</b> OTL night 100 %: -50 to +20.0 °C (+5.0 °C) OTL day 0 %: -50 to +5.0 °C (-15.0 °C)

F: Function block number, WE: Default setting, Anl: System code number

## Appendix A (configuration instructions)

### CO4: DHW circuit

F	Function	De- fault	Systems	Comments Function block parameters: value range (default setting)
01	Storage tank sensor SF1	0	1.9, 11.9	CO4 → F01 - 1: Storage tank sensor SF1 CO4 → F01 - 0: Storage tank thermostat (only when CO4 → F02 - 0)
		1	1.1-1.3, 1.5, 1.6, 2.x, 4.1, 4.5, 11.0, 11.2	
02	Storage tank sensor SF2 with <b>Stop storage tank charging</b> function (not assigned to the solar circuit)	0	1.1, 1.3, 1.5, 2.0, 2.1, 2.3, 4.1, 4.5, 11.0, 11.1, 11.5	CO4 → F02 - 1: Storage tank sensor SF2 (not systems 1.3, 1.9, 2.3, 11.0 and 11.9) (only when CO4 → F01 - 1)
		1	1.2, 1.6, 2.2, 11.2	
03	Return sensor RüF2	0	1.9, 11.x	CO4 → F03 - 1: Return sensor RüF2; Limitation function active <b>Function block parameters</b> K <sub>p</sub> (limiting factor): 0.1 to 10.0 (1.0)
05	Flow sensor	0	1.9, 11.x	CO4 → F05 - 1: Flow sensor VF4 (to measure storage tank charging temperature) active
06	Parallel pump operation	0	2.1-2.3, 4.1, 4.5	CO4 → F06 - 1: Parallel pump operation <b>Function block parameters</b> Stop parallel pump operation in the event of a system deviation: 0 to 10 min (10 min) Flow temperature limit for parallel operation: 20.0 to 90.0 °C (40.0 °C)  CO4 → F06 - 0: UP1 switched off during DHW heating
07	Intermediate heating	1	2.x, 4.1-4.5	CO4 → F07 - 1: After 20 minutes of DHW heating, heating operation in UP1 circuit reactivated for 10 minutes CO4 → F07 - 0: Unlimited priority of storage tank charging in UP1 circuit
08	Priority (reverse)	0	1.1-1.3, 4.1, 4.5, 11.x	CO4 → F08 - 1: Priority by reverse control (only when CO4 → F09 - 0) <b>Function block parameters</b> Start: 0 to 10 min (2 min) K <sub>p</sub> (influence factor): 0.1 to 10.0 (1.0) System 4.5 only: control circuit HC1, HC2, HC1+HC2 (HC2)
09	Priority (set-back)	0	1.1-1.4, 3.1-3.4, 4.1-4.5, 5.1, 5.2, 9.x, 10.1-10.3, 11.x, 12.x, 13.x, 15.0, 15.4, 15.5, 21.x	CO4 → F09 - 1: Priority through set-back operation (only when CO4 → F08 - 0) <b>Function block parameters</b> Start: 0 to 10 min (2 min) System 4.5 only: HC1, HC2, HC1+HC2 (HC2)
10	Circulation pump (DHW) integrated into heat exchanger	0	1.6, 11.2	CO4 → F10 - 1: Control of DHW circuit active while circulation pump (ZP) is running
		1	11.6	CO4 → F10 - 1: Control of DHW circuit active while circulation pump (ZP) is running
11	Operation of circulation pump (DHW) during storage tank charging	0	1.1-1.3, 1.5, 1.6, 2.x, 4.1, 4.5, 11.1, 11.2	CO4 → F11 - 1: Circulation pump ZP runs according to time schedule during storage tank charging CO4 → F11 - 0: Circulation pump (ZP) switched off during storage tank charging

F	Function	De- fault	Systems	Comments Function block parameters: value range (default setting)
12	Control mode	1	1.9, 11.x	CO4 → F12 - 1: Three-step control <b>Function block parameters</b> K <sub>p</sub> (gain): 0.1 to 50.0 (2.0; systems 1.9, 11.9, 12.9, 13.9, 21.9: 0.6) T <sub>n</sub> (reset time): 1 to 999 s (120 s, systems 3.9, 5.9, 17.x 18.x: 30 s; systems 1.9, 11.9, 12.9, 13.9, 21.9: 12 s) T <sub>v</sub> (derivative-action time): 0 to 999 s (0 s) T <sub>y</sub> (valve transit time): 15 to 240 s (35 s; system x.9: 20 s)  CO4 → F12 - 0: On/off control (not systems 3.8, 3.9, 5.9, 17.x, 18.x, 20.0); in this case: F12 - 0 = F12 - 1 <b>Function block parameters</b> Hysteresis: 1.0 to 30.0 °C (5.0 °C) Min. ON time: 0 to 10 min (2 min) Min. OFF time: 0 to 10 min (2 min)
13	Limitation of system deviation for OPEN signal	0	1.9, 11.x	CO4 → F13 - 1: OPEN signal damping (only when CO4 → F12 - 1) <b>Function block parameters</b> Max. system deviation: 3.0 to 10.0 °C (8.0 °C)
14	Thermal disinfection	0	1.1-1.3, 1.5, 1.6, 1.9, 2.x, 4.1, 4.5, 11.x	CO4 → F14 - 1: Thermal disinfection (only when CO4 → F01 - 1) <b>Function block parameters</b> Day of the week: 1, 2, ..., 7, 1-7 (3) Start time: 00:00 to 23:45 (00:00) Stop time: 00:00 to 23:45 (04:00) Disinfection temperature: 60.0 to 90.0 °C (70.0 °C) Set point boost: 0 to 50 °C (10 °C) Disinfection temperature sustaining time: 0 to 255 min (0 min) when Start time = Stop time Select: BI = 1, BI = 0 (BI = 1), input at terminals 03/12 (only possible without SF2/RF2)
15	SLP depending on return temperature	0	1.5, 1.6, 2.0, 2.1, 2.3, 4.1, 11.1, 11.2	CO4 → F15 - 1: Storage tank charging pump not ON unless return hot (for systems 1.5, 2.0, 2.1, 2.3, 4.1 only when CO1 → F03 - 1; for system 11.1 only when CO4 → F03 - 1) (for systems 1.5, 1.6, 2.0, 2.1, 2.3, 4.1 only when CO4 → F03 - 1)
16	Priority for external demand	0	1.5, 1.6, 2.x, 4.1	CO4 → F16 - 1: Priority for external demand <b>Note:</b> a high external demand causes excessive charging temperatures in DHW circuits without control valve.
19	Time-controlled changeover of storage tank sensors	0	1.1-1.3, 1.5, 1.6, 2.x, 4.1, 4.5, 11.1, 11.2	CO4 → F19 - 1: SF1 applies for day mode and SF2 for night mode. (only when CO4 → F02 - 1)
20	DHW circuit additionally controlled by a globe valve	0	11.1	CO4 → F20 - 1: Return temperature limitation using the globe valve with VF2 in the heating register return of the storage tank

## Appendix A (configuration instructions)

F	Function	De- fault	Systems	Comments Function block parameters: value range (default setting)
21	Speed control of the charging pump	0	1.1-1.3, 1.5, 1.6, 2.x, 4.1, 11.1, 11.2	CO4 → F21 - 1: Temperature-based adaptation of the delivery rate of the charging pump <b>Function block parameters</b> Start speed reduction - SF2 limit: 5.0 to 90 °C (40.0 °C) Stop speed reduction - SF2 limit: 5.0 to 90.0 °C (50.0 °C) Minimum speed: 0 to 50 % (20 %)
22	Cold charging protection	0	1.1	CO4 → F22 - 1: Storage tank charging started when the primary flow temperature is high enough <b>Function block parameters</b> Valve position: 1 to 100 %

F: Function block number, WE: Default setting, AnI: System code number

### CO4': DHW circuit (systems 1.1-1.3, 1.5, 1.6, 1.9, 2.x, 4.1, 4.5, 11.x)


F	Function	De- fault	Systems	Comments Function block parameters: value range (default setting)
03	Discharging protection		Not systems 1.1-1.3, 1.9, 11.0, 11.9	CO4' → F03 - 1: Discharging protection active

F: Function block number, WE: Default setting, AnI: System code number

### CO5: System-wide functions

If the reading CO5 → F00 - 1 appears on the display, any access to the return, flow rate and capacity settings is locked.

F	Function	De- fault	Systems	Comments Function block parameters: value range (default setting)
01	Sensor initialization	1	All	CO5 → F01 - 1, F02 → 0: Pt 1000
02				CO5 → F01 - 0, F02 → 0: PTC
03				CO5 → F01 - 1, F02 → 1: Ni 1000
04	Summer mode	0	Not systems 1.5, 1.6, 1.9, 3.5	CO5 → F04 - 1: Summer mode <b>Function block parameters</b> Start date for summer mode: 01.01 to 31.12 (01.06) No. days until activation: 1 to 3 (2) End date for summer mode: 01.01 to 31.12 (30.09) No. days until deactivation: 1 to 3 (1) Outdoor temperature limit for summer mode: 0.0 to 30.0 °C (18 °C)
05	Delayed outdoor temperature adaptation (decreasing)	0	Not system 1.9	CO5 → F05 - 1: Delayed outdoor temperature adaptation as the temperature falls <b>Function block parameters</b> Delay/h: 0.2 to 6.0 °C (3.0 °C)
06	Delayed outdoor temperature adaptation (increasing)	0	Not system 1.9	CO5 → F06 - 1: Delayed outdoor temperature adaptation as the temperature rises <b>Function block parameters</b> Delay/h: 0.2 to 6.0 °C (3.0 °C)
08	Summer time	0	All	CO5 → F08 - 1: Summer/standard time switchover

F	Function	De- fault	Systems	Comments Function block parameters: value range (default setting)
09	Frost protection program II	0	1.5, 1.6, 1.9, 3.5	CO5 → F09 - 0: Frost protection program I (restricted frost protection) <b>Function block parameters</b> Frost protection limit: -15.0 to +3.0 °C (+3.0 °C)
		1	Not systems 1.5, 1.6, 1.9, 3.5	CO5 → F09 - 1: Frost protection program II <b>Function block parameters</b> Frost protection limit: -15.0 to +3.0 °C (+3.0 °C)
12	Creep feed rate limitation	0	Not system 1.9	CO5 → F12 - 1: Creep feed rate limitation <b>Select:</b> bin (input terminals 04/12), AnA (input RüF1) <b>Function block parameters</b> BI = 1, BI = 0 (BI = 1)
14	Operation UP1	0	3.0, 16.x	CO5 → F14 - 1: Feeder pump UP1 operation to cover own demand <b>Note:</b> The feeder pump UP1 also starts to run to cover the demand of RK2.
15	Release controller at binary input BE1	0	All	CO5 → F15 - 1: Release controller at BE1 FG1 has no function. <b>Select:</b> BI = 1, BI = 0 (BI = 1)
16	Return temperature limitation	0	All	CO5 → F16 - 1: Return temperature limitation with P algorithm
19	Monitoring	0	All	CO5 → F19 - 1: Temperature monitoring active
20	Sensor calibration	1	All	CO5 → F20 - 1: Set all sensor calibration values CO5 → F20 - 0: Delete all sensor calibration values
21	Lock manual level	0	All	CO5 → F21 - 1: Lock manual level Controller runs in automatic mode in  switch position.
22	Lock rotary switch	0	All	CO5 → F22 - 1: Lock the rotary switch It is still possible to enter the key number.
23	Outdoor temperature as 0 to 10 V signal	0	All	CO5 → F23 - 1: Send (analog output) or receive (analog input) outdoor temperature as 0 to 10 V signal (terminals 11/12) <b>Function block parameters</b> Direction: AE, AA (AE) Lower range value: -50.0 to +100.0 °C (-20.0 °C) Upper range value: -50.0 to +100.0 °C (+50.0 °C)

F: Function block number, WE: Default setting, AnI: System code number

## Appendix A (configuration instructions)

### CO5': Other system-wide functions

F	Function	De- fault	Systems	Comments Function block parameters: value range (default setting)
01	AA reverse Output terminals 11/12	0	All	CO5' → F01 - 0: 0 V/0 % = Valve CLOSED/pump OFF CO5' → F01 - 1: 0 V/0 % = Valve OPEN/pump with max. delivery rate <b>Function block parameters</b> Zero: 0 to 50 % (0 %)
07	AE zero Input terminals 11/12	0	All	CO5' → F07 - 1 <b>Function block parameters</b> Zero: 5 to 20 % (5 %) Lower transmission range: 0 to 150 °C (0 °C) Upper transmission range: 0 to 150 °C (120 °C)
10	AA PWM Output terminals 11/12	0	All	CO5' → F10 - 0/1 TROVIS 5573 cannot process a PWM signal at the 0 to 10 V output <b>Function block parameters</b> 0 = 0 to 10 V input 1 = Control signal RK1 (default) 2 = Control signal RK2 5 = Outdoor temperature 6 = External demand 7 = SLP speed 9 = Differential temperature control 10 = 10 V supply 14 = 3 V supply

F: Function block number, WE: Default setting, AnI: System code number

**CO6: Modbus**

<b>F</b>	<b>Function</b>	<b>De- fault</b>	<b>Systems</b>	<b>Comments</b> <b>Function block parameters: value range (default setting)</b>
01	Modbus	1	All	CO6 → F01 - 1: Modbus active
02	16-bit address	0	All	CO6 → F02 - 1: Modbus 16-bit addressing (only when CO6 → F01 - 1) CO6 → F02 - 0: Modbus 8-bit addressing
03	Modem function	0	All	CO6 → F03 to F06 settings are required to configure the error message transfer to a connected Modbus/GPRS gateway.
04	Automatic configuration	0	All	
05	Lock dial-up to building automation system	0	All	
06	Dial-up to building automation system also when error corrected	0	All	
07	Monitoring	0	All	CO6 → F07 - 1: Control system monitoring Resets all level bits to 'Autonomous' when there is no communication. (only when CO6 → F01 - 1)
08	Text message	0	All	CO6 → F08 is required to configure the error message transfer to a connected Modbus/GPRS gateway.
20	Modbus without building automation system	0	All	CO6 → F20 - 1: Various Modbus specifications do not have any effect on the collective level/building automation system reading

F: Function block number, WE: Default setting, Anl: System code number

**CO8: Initialization of binary inputs BE1 and BE2 (all systems)**

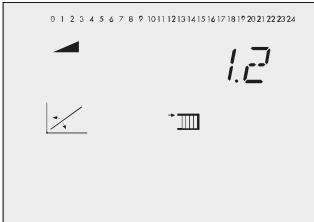
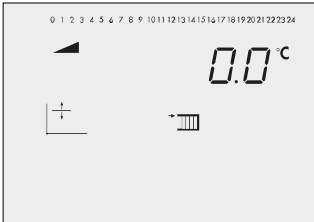
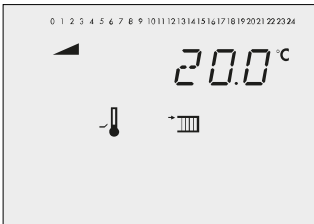
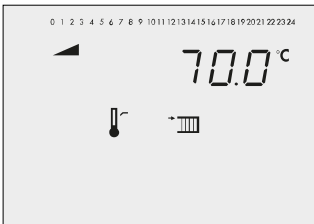
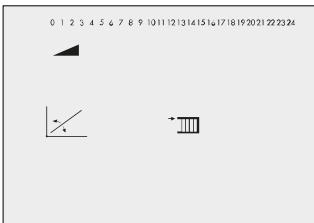
<b>F</b>	<b>Function</b>	<b>De- fault</b>	<b>Systems</b>	<b>Comments</b> <b>Function block parameters: value range (default setting)</b>
01	Processing of binary input BE1	0	All	CO8 -> F01 - 1: Processing active <b>Function block parameters</b> Error message when binary input BE = 0, BE = 1, none (1)
02	Processing of binary input BE2	0	All	CO8 -> F02 - 1: Processing active <b>Function block parameters</b> Error message when binary input BE = 0, BE = 1, none (1)

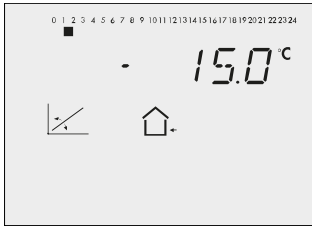
F: Function block number, WE: Default setting, Anl: System code number

## 16.7 Parameter lists

### PA1: RK1 parameters (heating circuit 1)

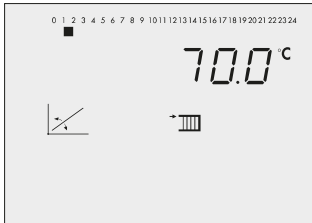
### PA2: RK2 parameters (heating circuit 2)

Display	Parameter name Value range (default setting)
	<p>Flow gradient</p> <p>0.2 to 3.2 (1.2) (when CO1, 2 → F05 - 1, 0.2 to 1.0 (0.5) applies)</p>
	<p>Level (parallel shift)</p> <p>-30.0 to +30.0 °C (0.0 °C)</p>
	<p>Min. flow temperature</p> <p>-5.0 to +150.0 °C (+20.0 °C)</p>
	<p>Max. flow temperature</p> <p>5.0 to 150.0 °C (70.0 °C) When CO1, 2 → F05 - 1: 5.0 to 50.0 °C (50.0 °C)</p>
	<p>Four-point characteristic</p> <p>* Press rotary pushbutton to set the following parameters:</p> <ul style="list-style-type: none"> <li>- Outdoor temperature</li> <li>- Flow temperature</li> <li>- Reduced flow temperature</li> <li>- Return temperature</li> </ul>



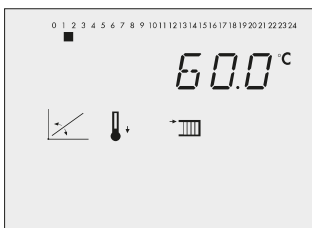
Four-point characteristic  
Point 1: outdoor temperature

Outdoor temperatures of points 2, 3 and 4 are marked by squares under the numbers 2, 3 and 4.  
-50.0 to +50.0 °C  
(pt. 1: -15.0 °C, pt. 2: -5.0 °C, pt. 3: +5.0 °C, pt. 4: +15.0 °C)  
When CO1, 2 → F04 - 1:  
(pt. 1: 5.0 °C, pt. 2: 15.0 °C, pt. 3: 25.0 °C, pt. 4: 30.0 °C)



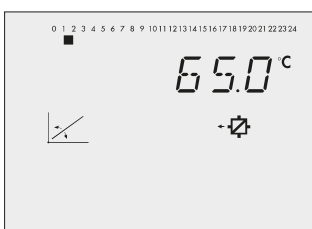
Four-point characteristic  
Point 1: flow temperature

Flow temperatures of points 2, 3 and 4 are marked by squares under the numbers 2, 3 and 4.  
-5.0 to +150.0 °C  
(pt. 1: 70.0 °C, pt. 2: 55.0 °C, pt. 3: 40.0 °C, pt. 4: 25.0 °C)  
When CO1, 2 → F04 - 1:  
(pt. 1: 20.0 °C, pt. 2: 15.0 °C, pt. 3: 10.0 °C, pt. 4: 5.0 °C)



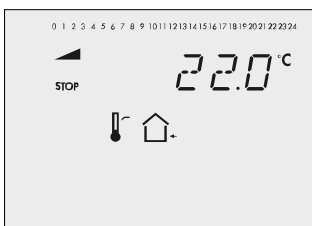
Four-point characteristic  
Point 1: Reduced flow temperature

Reduced flow temperatures of points 2, 3 and 4 are marked by squares under the numbers 2, 3 and 4.  
-5.0 to +150.0 °C  
(pt. 1: 60.0 °C, pt. 2: 40.0 °C, pt. 3: 20.0 °C, pt. 4: 20.0 °C)  
When CO1, 2 → F04 - 1:  
(pt. 1: 30.0 °C, pt. 2: 25.0 °C, pt. 3: 20.0 °C, pt. 4: 15.0 °C)



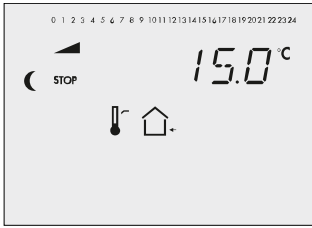
Four-point characteristic  
Point 1: return temperature

Return flow temperatures of points 2, 3 and 4 are marked by squares under the numbers 2, 3 and 4.  
5.0 to 90.0 °C  
(points 1 to 4: 65.0 °C)

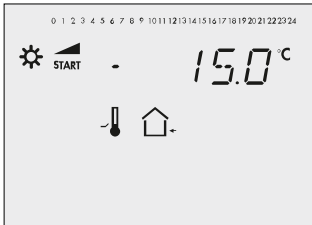


OT deactivation value in rated operation  
0.0 to 50.0 °C (22.0 °C)

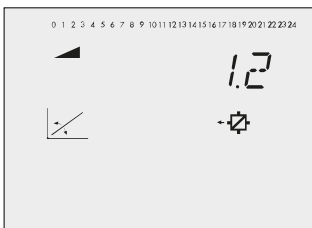
## Appendix A (configuration instructions)



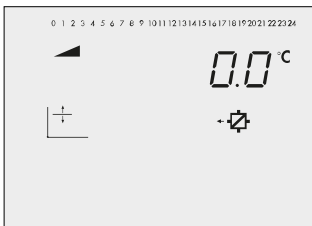
OT deactivation value in reduced operation  
-50.0 to +50.0 °C (+15.0 °C)



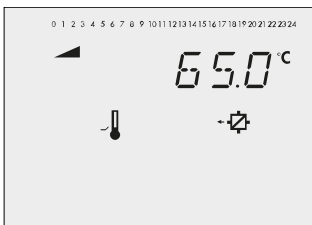
OT activation value in rated operation  
-50.0 to +5.0 °C (-15.0 °C)



Return gradient  
0.2 to 3.2 (1.2)



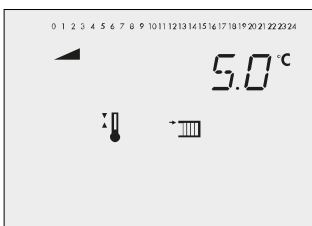
Return level  
-30.0 to +30.0 °C (0.0 °C)



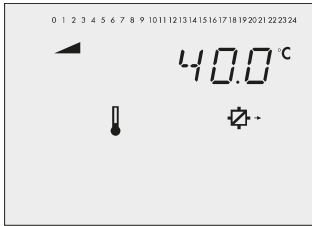
Base point for return temperature  
5.0 to 90.0 °C (65.0 °C)



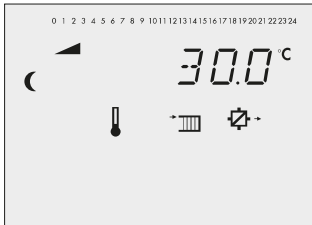
Max. return temperature  
5.0 to 90.0 °C (65.0 °C)



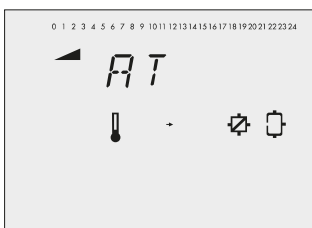
Set point boost (primary exchanger control)  
0.0 to 50.0 °C (5.0 °C)



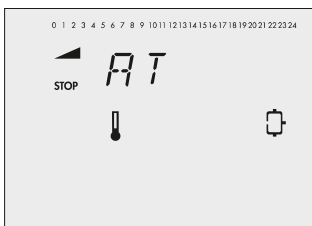
Set point for binary demand processing  
 0.0 to 150.0 °C (40.0 °C)  
 Only in PA1 parameter level



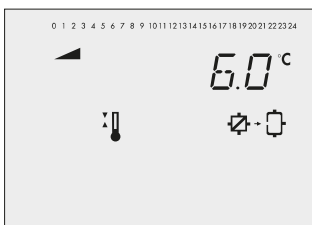
Flow set point (night)  
 -5.0 to +150.0 °C (+30.0 °C)  
 Only with flash adaptation without outdoor sensor



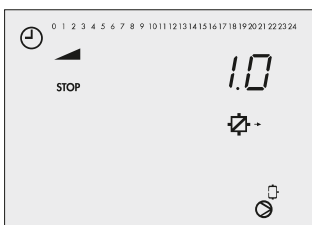
Minimum set point to charge buffer tank  
 OT to 90.0 °C (OT)  
 In PA1 only



Stop charging of the buffer tank  
 OT to 90.0 °C (OT)  
 In PA1 only



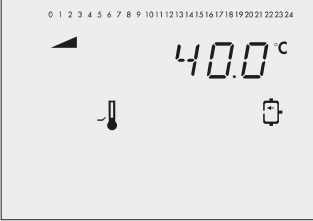
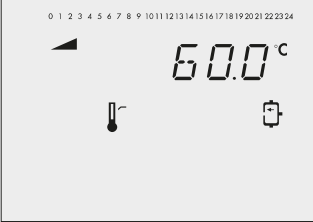
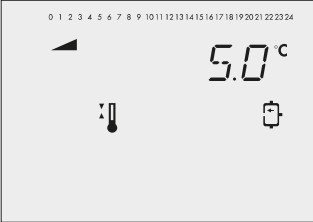
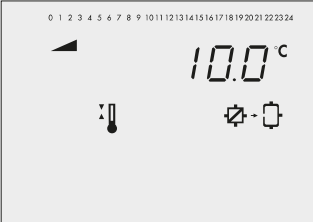
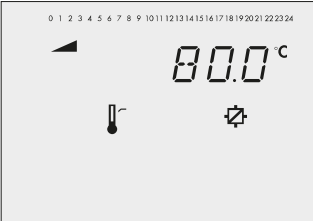
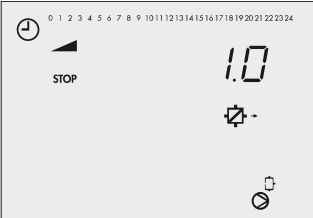
Charging temperature boost  
 0.0 to 50.0 °C (6.0 °C)  
 In PA1 only

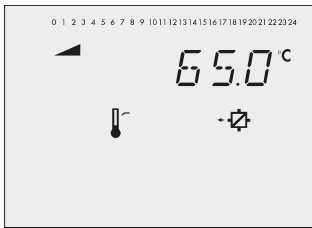


Lag time of charging pump  
 0.0 to 10.0 (1.0)  
 In PA1 only

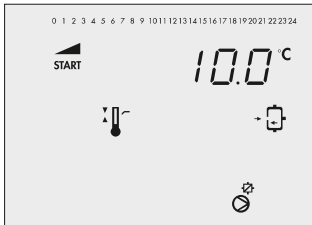
## Appendix A (configuration instructions)

### PA4: DHW circuit parameters

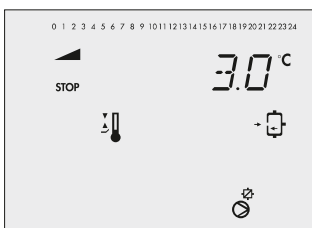
Display	Parameter name Value range (default setting)
 <p>The display shows a digital readout of 40.0°C. Above the digits is a horizontal scale from 0 to 24. To the left is a triangle icon, and to the right is a battery icon. Below the digits is a thermometer icon.</p>	<p>Min. DHW temperature 5.0 to 90.0 °C (40.0 °C)</p>
 <p>The display shows a digital readout of 60.0°C. Above the digits is a horizontal scale from 0 to 24. To the left is a triangle icon, and to the right is a battery icon. Below the digits is a thermometer icon.</p>	<p>Max. DHW temperature 5.0 to 90.0 °C (60.0 °C)</p>
 <p>The display shows a digital readout of 5.0°C. Above the digits is a horizontal scale from 0 to 24. To the left is a triangle icon, and to the right is a battery icon. Below the digits is a thermometer icon.</p>	<p>Hysteresis 1.0 to 30.0 °C (5.0 °C)</p>
 <p>The display shows a digital readout of 10.0°C. Above the digits is a horizontal scale from 0 to 24. To the left is a triangle icon, and to the right is a battery icon. Below the digits is a thermometer icon and a square icon with a diagonal line through it.</p>	<p>Charging temperature boost 0.0 to 50.0 °C (10.0 °C)</p>
 <p>The display shows a digital readout of 80.0°C. Above the digits is a horizontal scale from 0 to 24. To the left is a triangle icon, and to the right is a battery icon. Below the digits is a thermometer icon and a square icon with a diagonal line through it.</p>	<p>Max. charging temperature 20.0 to 150.0 °C (80.0 °C) Only with VF4</p>
 <p>The display shows a digital readout of 1.0. Above the digits is a horizontal scale from 0 to 24. To the left is a triangle icon and the word 'STOP'. To the right is a battery icon. Below the digits is a square icon with a diagonal line through it and a circular icon with a diagonal line through it.</p>	<p>Lag time for storage tank charging pump 0.0 to 10.0 (1.0)</p>



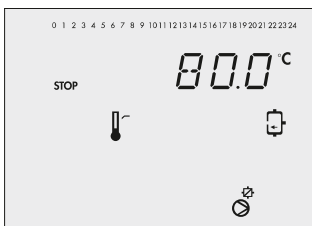
Max. return temperature  
20.0 to 90.0 °C (65.0 °C)



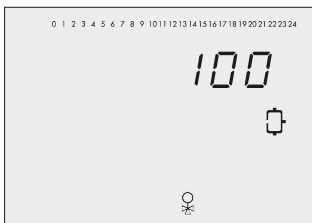
Solar circuit pump ON  
1.0 to 30.0 °C (10.0 °C)



Solar circuit pump OFF  
0.0 to 30.0 °C (3.0 °C)



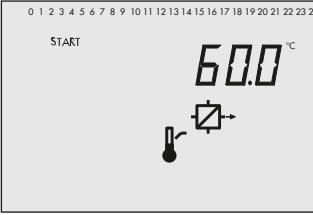
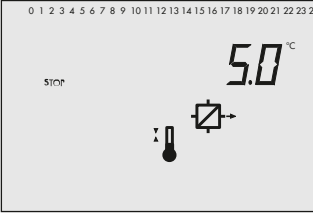
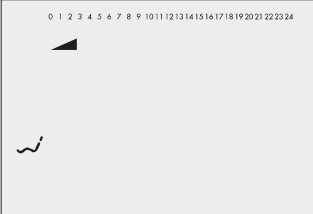
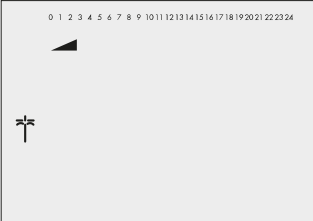
Max. storage tank temperature  
20.0 to 90.0 °C (80.0 °C)



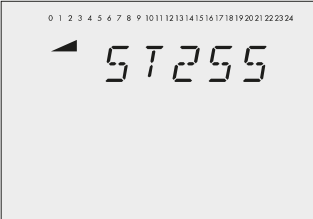
Control signal DHW for storage tank charging  
5 to 100 % (100 %)

## Appendix A (configuration instructions)

### PA5: System-wide parameters (all systems)

Display	Parameter name Value range (default setting)
	Boiler pump ON 20 to 90 °C (60 °C) System 16.x only
	Hysteresis 0 to 30 °C (5 °C) System 16.x only
	Public holidays 01.01 to 31.12 (see Chapter 8)
	Vacations 01.01 to 31.12 (see Chapter 8)

### PA6: Modbus parameters

Display	Parameter name Value range (default setting)
	Station address 1 to 247 (255) When CO6 → F02 - 1: 1 to 32000 applies

## 16.8 Customer-specific data

⇒ See next page.



## Heating circuit 1 (RK1) and heating circuit 2 (RK2)

Levels 1 and 2 parameters	PA1	PA2	Value range
Flow gradient			0.2 to 3.2
Flow level			-30.0 to +30.0 °C
Min. flow temperature			-5.0 to +150.0 °C
Max. flow temperature			5.0 to 150.0 °C
Four-point characteristic			
Outdoor temperature, point 1			-50.0 to +50.0 °C
Outdoor temperature, point 2			-50.0 to +50.0 °C
Outdoor temperature, point 3			-50.0 to +50.0 °C
Outdoor temperature, point 4			-50.0 to +50.0 °C
Flow temperature, point 1			-5.0 to +150.0 °C
Flow temperature, point 2			-5.0 to +150.0 °C
Flow temperature, point 3			-5.0 to +150.0 °C
Flow temperature, point 4			-5.0 to +150.0 °C
Reduced flow temperature, point 1			-5.0 to +150.0 °C
Reduced flow temperature, point 2			-5.0 to +150.0 °C
Reduced flow temperature, point 3			-5.0 to +150.0 °C
Reduced flow temperature, point 4			-5.0 to +150.0 °C
Return temperature, point 1			5.0 to 90.0 °C
Return temperature, point 2			5.0 to 90.0 °C
Return temperature, point 3			5.0 to 90.0 °C
Return temperature, point 4			5.0 to 90.0 °C
OT deactivation value in rated operation			0.0 to 50.0 °C
OT deactivation value in reduced operation			-50.0 to +50.0 °C
OT activation value in rated operation			-50.0 to +5.0 °C
Return gradient			0.2 to 3.2
Return level			-30 to +30.0 °C
Base point for return temperature:			5.0 to 90.0 °C
Flow set point (day)			-5.0 to +150 °C
Flow set point (night)			-5.0 to +150 °C
Minimum set point to charge buffer tank			OT to 90.0 °C
Stop charging of the buffer tank			OT to 90.0 °C
Charging temperature boost			0.0 to 50.0 °C
Lag time for storage tank charging pump			0.0 to 10.0
Set point boost (primary exchanger control)			0.0 to 50.0 °C
Set point for binary demand processing			0.0 to 150 °C

<b>F</b>	<b>Function block parameters</b>	<b>CO1</b>	<b>CO1'</b>	<b>CO2</b>	<b>CO2'</b>	<b>Value range</b>
03 - 1	$K_p$ (limiting factor)		-			0.1 to 10.0
04 - 1	Variable night set-back, OTL night	-		-		-50 to +20 °C
04 - 1	Variable night set-back, OTL day	-		-		-50 to +5 °C
05 - 1	Boost		-		-	0.0 to 50.0 °C
05 - 1	Start temperature		-		-	20.0 to 60.0 °C
05 - 1	Hold (days)		-		-	0 to 10 days
05 - 1	Temp. rise/day		-		-	0.0 to 10.0 °C
05 - 1	Maximum temperature		-		-	25.0 to 60.0 °C
05 - 1	Hold (days)		-		-	0 to 10 days
05 - 1	Temp. reduction/day		-		-	0.0 to 10.0 °C
09 - 1	Cycle time		-		-	0/1 to 100 min
09 - 1	$K_p$ (gain)		-		-	0.0 to 25.0
12 - 1	$K_p$ (gain)		-		-	0.1 to 50.0
12 - 1	$T_n$ (reset time)		-		-	1 to 999 s
12 - 1	$T_v$ (derivative-action time)		-		-	0 to 999 s
12 - 1	$T_y$ (valve transit time)		-		-	15 to 240 s
12 - 0	Hysteresis		-		-	1.0 to 30.0 °C
12 - 0	Min. ON time		-		-	0 to 10 min
12 - 0	Min. OFF time		-		-	0 to 10 min
13 - 1	Max. system deviation		-		-	3.0 to 10.0 °C
14 - 1	Binary input		-		-	BI = 1, BI = 0
17 - 1	Binary input		-	-	-	BI = 1, BI = 0
18 - 1	Lower transmission range		-	-	-	0.0 to 150.0 °C
18 - 1	Upper transmission range		-	-	-	0.0 to 150.0 °C
18 - 1	Boost flow temperature demand		-	-	-	0.0 to 30.0 °C
21 - 1	Start speed reduction		-	-	-	5 to 90 °C
21 - 1	Stop speed reduction		-	-	-	5 to 90 °C
21 - 1	Min. speed signal		-	-	-	0 to 10 V
23 - 1	Set point of differential temperature control		-	-	-	0.0 to 50.0 °C
23 - 1	Influence factor $K_p$		-	-	-	0.1 to 10
23 - 1	Minimum speed		-	-	-	0 to 100 %

## DHW circuit

Level 4 parameters	PA4	Value range
Min. DHW temperature		5.0 to 90.0 °C
Max. DHW temperature		5.0 to 90.0 °C
Hysteresis		1.0 to 30.0 °C
Charging temperature boost		0.0 to 50.0 °C
Max. charging temperature		20.0 to 150.0 °C
Lag time for storage tank charging pump		0.0 to 10.0
Max. return temperature		0.0 to 90.0 °C
Solar circuit pump ON		1.0 to 30.0 °C
Solar circuit pump OFF		0.0 to 30.0 °C
Max. storage tank temperature		20.0 to 90.0 °C
Control signal DHW for storage tank charging		5 to 100 %

F	Function block parameters	CO4	Value range
03 - 1	$K_p$ (limiting factor)		0.1 to 10.0
06 - 1	Stop parallel pump operation in the event of a system deviation		0 to 10 min
06 - 1	Flow temperature limit for parallel operation		20.0 to 90.0 °C
08 - 1	Activate priority in the event of a system deviation		0 to 10 min
08 - 1	$K_p$ (influence factor)		0.1 to 10.0
09 - 1	Activate priority in the event of a system deviation		0 to 10 min
12 - 1	$K_p$ (gain)		0.1 to 50.0
12 - 1	$T_n$ (reset time)		1 to 999 s
12 - 1	$T_v$ (derivative-action time)		0 s, do not change the value.
12 - 1	$T_y$ (valve transit time)		15 to 240 s
12 - 0	Hysteresis		1.0 to 30.0 °C
12 - 0	Min. ON time		0 to 10 min
12 - 0	Min. OFF time		0 to 10 min
13 - 1	Max. system deviation		3.0 to 10.0 °C
14 - 1	Day of the week		1-7, 1 to 7
14 - 1	Start time		00:00h to 23:45h
14 - 1	Stop time		00:00h to 23:45h
14 - 1	Disinfection set point		60.0 to 90.0 °C
14 - 1	Set point boost		0.0 to 50.0 °C
14 - 1	Disinfection temperature sustaining time		0 to 255 min
21 - 1	Start speed reduction		5 to 90 °C
21 - 1	Stop speed reduction		5 to 90 °C
21 - 1	Min. signal		0 to 50 %
22 - 1	Valve position when cold charging protection is active		1 to 100 %

Level 5 parameters	PA5					Value range
Boiler pump ON						20 to 90 °C
Hysteresis						0 to 30 °C
Public holidays						01.01 to 31.12
Vacation periods, Start						01.01 to 31.12
Vacation periods, Stop						01.01 to 31.12
Control circuit assignment						<b>1, 2, 3</b>
Vacation periods, Start						01.01 to 31.12
Vacation periods, Stop						01.01 to 31.12
Control circuit assignment						<b>1, 2, 3</b>

F	Function block parameters	CO5	Value range
04 - 1	Start date for summer mode		01.01 to 31.12
04 - 1	No. days until activation		1 to 3
04 - 1	End date for summer mode		01.01 to 31.12
04 - 1	No. days until deactivation		1 to 3
04 - 1	Outdoor temperature limit		0.0 to 30.0 °C
05 - 1 06 - 1	Delay per hour		1.0 to 6.0 °C
09 - 0 09 - 1	Frost protection limit		-15.0 to +3.0 °C
12 - 1	Input		bin, AnA
12 - 1, bin	Binary input		BI = 1, BI = 0
15 - 1	Binary input		BI = 1, BI = 0
23 - 1	Direction		AE, AA
23 - 1	Lower transmission range		-50 to +100 °C
23 - 1	Upper transmission range		-50 to +100 °C

F	Function block parameters	CO5'	Value range
01 - 1	Zero point		0 to 50 %
07 - 1	Zero point		5 to 20 %
07 - 1	Lower transmission range		0 to 150.0 °C
07 - 1	Upper transmission range		0 to 150.0 °C
10 - 0 /-1	Output		0 = 0 to 10 V input, 1 = Control signal RK1, 2 = Control signal RK2, 5 = Outdoor temperature, 6 = External demand, 7 = SLP speed, 9 = Differential temperature control, 10 = 10 V supply 14 = 3 V supply

Level 6 parameters	PA6	Value range
Station address (ST)		1 to 247 1 to 32000

F	Function block parameters	CO8	Value range
01 - 1	Error message when		BI = 0, BI = 1, none
10 - 1	Error message when		BI = 0, BI = 1, none

## Settings at the rotary switch

### Heating circuit 1 · Reading on display: 1



Parameters	Value range						
Day set point	-5.0 to +150.0 °C						
Night set point	-5.0 to +150.0 °C						
<b>Times-of-use</b>	<b>Mon</b>	<b>Tue</b>	<b>Wed</b>	<b>Thu</b>	<b>Fri</b>	<b>Sat</b>	<b>Sun</b>
Start first time-of-use							
Stop first time-of-use							
Start second time-of-use							
Stop second time-of-use							
Start third time-of-use							
Stop third time-of-use							

### Heating circuit 2 · Reading on display: 2

Parameters	Value range						
Day set point	-5.0 to +150.0 °C						
Night set point	-5.0 to +150.0 °C						
<b>Times-of-use</b>	<b>Mon</b>	<b>Tue</b>	<b>Wed</b>	<b>Thu</b>	<b>Fri</b>	<b>Sat</b>	<b>Sun</b>
Start first time-of-use							
Stop first time-of-use							
Start second time-of-use							
Stop second time-of-use							
Start third time-of-use							
Stop third time-of-use							

### DHW circuit · Reading on display: 3

Parameters	Value range	
DHW temperature set point	Min. to max. DHW temperature	
DHW temperature sustaining value		

 <b>Times-of-use for DHW</b>	<b>Mon</b>	<b>Tue</b>	<b>Wed</b>	<b>Thu</b>	<b>Fri</b>	<b>Sat</b>	<b>Sun</b>
Start first time-of-use							
Stop first time-of-use							
Start second time-of-use							
Stop second time-of-use							
Start third time-of-use							
Stop third time-of-use							
 <b>Times-of-use for DHW circulation pump</b>	<b>Mon</b>	<b>Tue</b>	<b>Wed</b>	<b>Thu</b>	<b>Fri</b>	<b>Sat</b>	<b>Sun</b>
Start first time-of-use							
Stop first time-of-use							
Start second time-of-use							
Stop second time-of-use							
Start third time-of-use							
Stop third time-of-use							

### 17 Appendix B

#### 17.1 Accessories

**Table 6:** *Accessories*

Surge arrester SA 5000	Order no. 1400-9868
Memory module	Order no. 1400-9379
Mini module	Order no. 1400-7436
Data logging module	Order no. 1400-9378
USB Converter 3	Order no. 1400-9377
4-port bus hub	Order no. 1400-7140
RS-485 communication module	Order no. 8812-2002
Modbus GPRS gateway	Order no. 1402-0701
▶ SAM HOME Gateway	Type 5660
▶ SAM MOBILE Gateway	Type 5655
TROVIS-VIEW software (free of charge)	▶ <a href="http://www.samsongroup.com">www.samsongroup.com</a> > DOWNLOADS > Software & Drivers > TROVIS-VIEW
SAM DISTRICT ENERGY	▶ <a href="http://www.samsongroup.com">www.samsongroup.com</a> > PRODUCTS > Digital solutions > SAM DISTRICT ENERGY ▶ EB 6901
Sensors and room panels	▶ <a href="http://www.samsongroup.com">www.samsongroup.com</a> > PRODUCTS > Sensors and Thermostats ▶ T 5200 (Information Sheet: Temperature Sensors and Thermostats)

#### 17.2 After-sales service

##### Product support

Service hotline for heating controllers belonging to TROVIS 5400 and TROVIS 5500 Automation Systems (fees apply):

Monday to Friday: 7:30 to 16:00 h (CET)

Phone: +9001 4009-24 (EUR 0.99/min. for landline calls within Germany, other rates apply to calls from outside Germany or from a mobile network)

##### After-sales service

Contact our after-sales service for support concerning service or repair work or when malfunctions or defects arise.

You can reach our after-sales service at the following e-mail address.

▶ [aftersaleservice@samsongroup.com](mailto:aftersaleservice@samsongroup.com)

##### Addresses of SAMSON AG and its subsidiaries

The addresses of SAMSON AG, its subsidiaries, representatives and service facilities worldwide can be

found on our website (▶ [www.samsongroup.com](http://www.samsongroup.com)) or in all product catalogs.

##### Required specifications

Please submit the following details:

- Model number
- Serial number
- Firmware version

**Key number**

**1732**



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